

CBE

Suppose $\vec{F}_{\text{ext}} = -\vec{\nabla}U = 0$. We can then take $U=0$, in which case CBE is

$$\frac{\partial f}{\partial t} + \vec{v}(\vec{p}) \cdot \frac{\partial f}{\partial \vec{r}} = 0$$

Solution (check it!): $f(\vec{r}, \vec{p}, t) = \varphi(\vec{r} - \vec{v}(\vec{p})t, \vec{p})$

where $f(\vec{r}, \vec{p}, t=0) = \varphi(\vec{r}, \vec{p})$ is any function.

Example: $\varphi(\vec{r}, \vec{p}) = C e^{-\vec{r}^2/2\sigma^2} e^{-\vec{p}^2/2k^2}$. Then

$$f(\vec{r}, \vec{p}, t) = C e^{-(\vec{r} - \frac{\vec{p}t}{m})^2/2\sigma^2} e^{-\vec{p}^2/2k^2}$$

One-dim^l version (rescaled x, p, t):

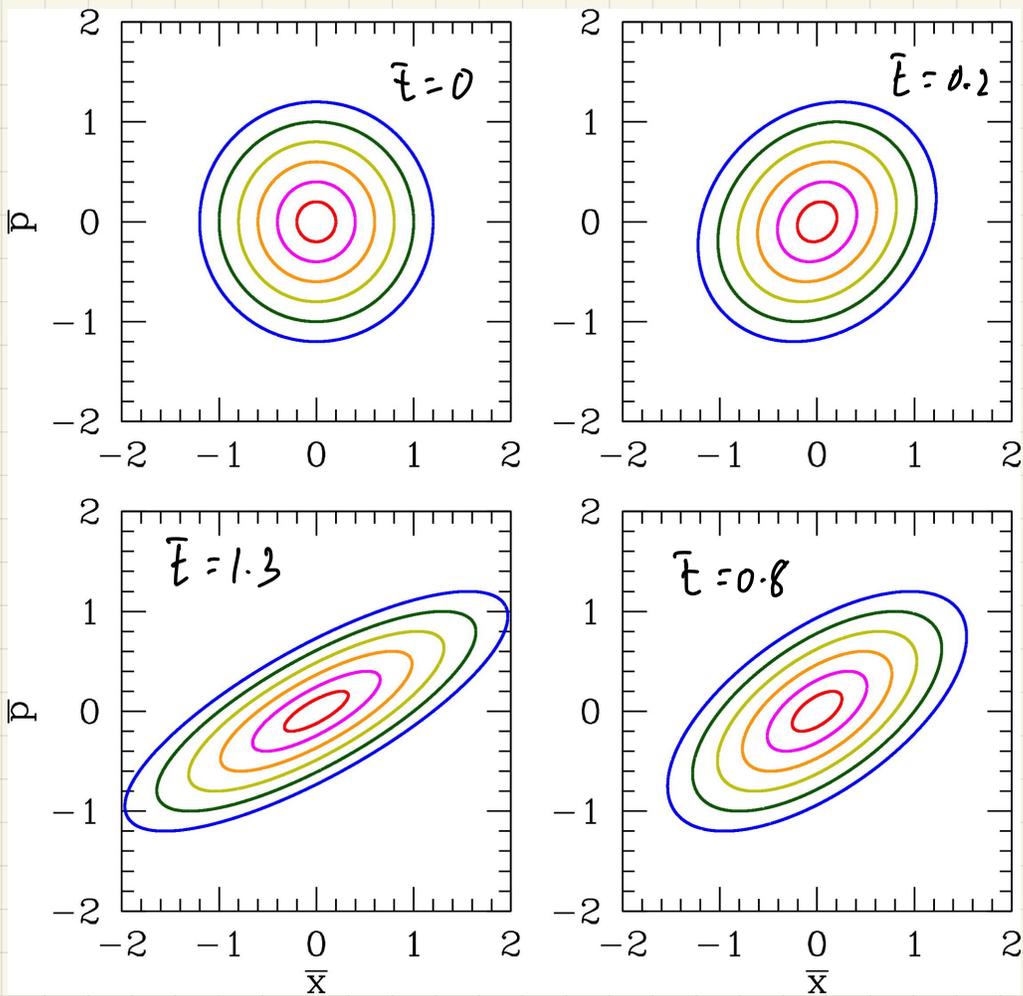
$$f(\bar{x}, \bar{p}, \bar{t}) = C e^{-(\bar{x} - \bar{p}\bar{t})^2/2} e^{-\bar{p}^2/2}$$

Level sets of f : set $f(\bar{x}, \bar{p}, \bar{t}) = C e^{-\alpha^2/2}$

Then $\bar{x} = \bar{p}\bar{t} \pm \sqrt{\alpha^2 - \bar{p}^2}$ are the eqns for

the level sets. With constant force (rescaled):

$$f(\bar{x}, \bar{p}, \bar{t}) = C \varphi(\bar{x} - \bar{p}\bar{t} - \frac{1}{2}\bar{F}\bar{t}^2, \bar{p} - \bar{F}\bar{t})$$



- $\alpha = 0.2$
- $\alpha = 0.4$
- $\alpha = 0.6$
- $\alpha = 0.8$
- $\alpha = 1.0$
- $\alpha = 1.2$

Collisional Invariants

Consider $A(\vec{r}, \vec{p})$. Then its avg value at time t is

$$\langle A(t) \rangle = \int d^3r \int d^3p A(\vec{r}, \vec{p}) f(\vec{r}, \vec{p}, t)$$

$$\frac{d\langle A(t) \rangle}{dt} = \int d^3r \int d^3p A(\vec{r}, \vec{p}) \left\{ -\frac{\partial}{\partial \vec{r}} \cdot (\dot{\vec{r}} f) - \frac{\partial}{\partial \vec{p}} \cdot (\dot{\vec{p}} f) + \left. \left(\frac{df}{dt} \right)_{\text{coll}} \right\}$$

Integrating by parts,

$$\frac{d\langle A \rangle}{dt} = \int d^3r \int d^3p \left\{ \left(\frac{\partial A}{\partial \vec{r}} \cdot \frac{d\vec{r}}{dt} + \frac{\partial A}{\partial \vec{p}} \cdot \frac{d\vec{p}}{dt} \right) f + A(\vec{r}, \vec{p}) \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} \right\}$$

If $A(\vec{r}(t), \vec{p}(t))$ is conserved between collisions, then

$$\frac{d\langle A(t) \rangle}{dt} = \int d^3r \int d^3p A(\vec{r}, \vec{p}) \left(\frac{\partial f}{\partial t} \right)_{\text{coll}}$$

A quantity $A(\vec{r}, \vec{p})$ which is conserved in collisions is called a collisional invariant. Examples include particle number ($A=1$), total momentum ($A=p^\alpha$), and total kinetic energy ($A=\varepsilon(\vec{p})$).

Scattering Processes

$$\text{Let } w(\vec{p}' | \vec{p}) f(\vec{p}) d^3p d^3p' = \begin{cases} \text{rate per volume to scatter} \\ \{ |\vec{p} + d\vec{p}\rangle \} \rightarrow \{ |\vec{p}' + d\vec{p}'\rangle \} \\ \text{at time } t \end{cases}$$

Units of $w d^3p$ are T^{-1}

because $[f(\vec{p}) d^3p] = L^{-3}$. The differential scattering cross section is then

$$d\sigma = \frac{w(\vec{p}'|\vec{p})}{n_s |\vec{v}|} d^3 p' \quad ; \quad \vec{v}(\vec{p}) = \frac{\partial \mathcal{E}}{\partial \vec{p}} = \frac{\vec{p}}{m}$$

and \uparrow density of scatterers

$$\left(\frac{df}{dt} \right)_{\text{coll}} = \int d^3 p' \left\{ w(\vec{p}|\vec{p}') f(\vec{r}, \vec{p}', t) - w(\vec{p}'|\vec{p}) f(\vec{r}, \vec{p}, t) \right\}$$

This is called single particle scattering. We also have two particle scattering. Let

$$w(\vec{p}', \vec{p}'_1 | \vec{p}, \vec{p}_1) f(\vec{p}) f(\vec{p}_1) d^3 p d^3 p_1 d^3 p' d^3 p'_1 =$$

rate per (volume)² to scatter two particles
 $\{ |\vec{p} + d\vec{p}, \vec{p}_1 + d\vec{p}_1 \rangle \} \rightarrow \{ |\vec{p}' + d\vec{p}', \vec{p}'_1 + d\vec{p}'_1 \rangle \}$

Then

$$\left(\frac{df}{dt} \right)_{\text{coll}} = \int d^3 p_1 \int d^3 p' \int d^3 p'_1 \left\{ w(\vec{p}, \vec{p}_1 | \vec{p}', \vec{p}'_1) f_2(\vec{r}, \vec{p}'; \vec{r}, \vec{p}'_1; t) - w(\vec{p}', \vec{p}'_1 | \vec{p}, \vec{p}_1) f_2(\vec{r}, \vec{p}; \vec{r}, \vec{p}_1; t) \right\}$$

Approximation:

$$f_2(\vec{r}, \vec{p}; \vec{r}, \vec{p}_1; t) \approx f(\vec{r}, \vec{p}; t) f(\vec{r}, \vec{p}_1; t)$$

Then we have

$$\left(\frac{df}{dt}\right)_{\text{coll}} = \int d^3 p_1 \int d^3 p'_1 \int d^3 p''_1 \left\{ W(p, \vec{p}_1 | \vec{p}', \vec{p}'_1) f(\vec{r}, \vec{p}; t) f(\vec{r}, \vec{p}'_1; t) \right. \\ \left. - W(\vec{p}', \vec{p}'_1 | p, \vec{p}_1) f(\vec{r}, \vec{p}; t) f(\vec{r}, \vec{p}_1; t) \right\}$$

Detailed Balance

DB is a constraint on the equilibrium distⁿ $f^0(\vec{p})$.

For one-body scattering, the integrand of the collision term is

$$W(\vec{p} | \vec{p}') f(\vec{r}, \vec{p}', t) - W(\vec{p}' | \vec{p}) f(\vec{r}, \vec{p}, t)$$

Thus, a uniform and time-independent $f^0(\vec{p})$ satisfying

$$W(\vec{p} | \vec{p}') f^0(\vec{p}') = W(\vec{p}' | \vec{p}) f^0(\vec{p})$$

$$\Rightarrow \frac{f^0(\vec{p}')}{f^0(\vec{p})} = \frac{W(\vec{p}' | \vec{p})}{W(\vec{p} | \vec{p}')}$$

will make the integrand of $\left(\frac{df}{dt}\right)_{\text{coll}}$ vanish for all \vec{p} and \vec{p}' . Thus $f^0(\vec{p})$ is a solⁿ to

the BE with collisions. For two-body scattering, DB requires

$$W(p, \vec{p}_1 | \vec{p}', \vec{p}'_1) f(\vec{r}, \vec{p}; t) f(\vec{r}, \vec{p}'_1; t) \\ = W(\vec{p}', \vec{p}'_1 | p, \vec{p}_1) f(\vec{r}, \vec{p}; t) f(\vec{r}, \vec{p}'_1; t)$$

Boltzmann's H - theorem

Although the microscopic laws governing a system may be time-reversal invariant, the Boltzmann equation itself establishes an arrow of time.

Define

$$h(\vec{r}, t) = \int d^3 p f(\vec{r}, \vec{p}, t) \log [f(\vec{r}, \vec{p}, t) a^3] \\ \vec{j}(\vec{r}, t) = \int d^3 p f(\vec{r}, \vec{p}, t) \log [f(\vec{r}, \vec{p}, t) a^3] \frac{d\vec{r}}{dt}$$

where a is any constant with dimensions of action. After some grinding (see § 8.3.7 in the lecture notes), we arrive at

$$\frac{\partial h(\vec{r}, t)}{\partial t} + \vec{\nabla} \cdot \vec{j}(\vec{r}, t) = \sigma(\vec{r}, t) < 0$$

with

$$\sigma(\vec{r}, t) = -\frac{1}{2} \int d^3 p \int d^3 p_1 \int d^3 p' \int d^3 p'_1 \left\{ \omega(\vec{p}', \vec{p}'_1 | \vec{p}, \vec{p}_1) \right. \\ \left. \times f(\vec{r}, \vec{p}', t) f(\vec{r}, \vec{p}'_1, t) (x \log x - x + 1) \right.$$

where

$$x(\vec{p}, \vec{p}_1, \vec{p}', \vec{p}'_1; \vec{r}, t) = \frac{f(\vec{r}, \vec{p}, t) f(\vec{r}, \vec{p}_1, t)}{f(\vec{r}, \vec{p}', t) f(\vec{r}, \vec{p}'_1, t)}$$

Integrating,

$$\frac{dH(t)}{dt} = \int d^3 r \sigma(\vec{r}, t) < 0$$

$$H(t) = \int d^3 r h(\vec{r}, t)$$

So $H(t)$ always decreases -- the arrow of time!