## PHYSICS 110A : MECHANICS I

- 1. <u>Introduction to Dynamics</u> (Sept. 23 and 26) essential elements of dynamics discrete and differential equations deterministic *versus* stochastic dynamical systems examples
- 2. <u>Motion in d = 1: Two-Dimensional Phase Flows</u> (Sept. 28) (x, v) phase space dynamical system  $\frac{d}{dt} \{ {x \atop v} \} = \left\{ {v \atop a(x,v)} \right\}$ two-dimensional phase flows examples: harmonic oscillator and pendulum fixed points in two-dimensional phase space; separatrices
- 3. Solution of the Equations of One-Dimensional Motion (Sept. 30 and Oct. 3)

potential energy U(x)conservation of energy sketching phase flows from U(x)solution by quadratures turning points; period of orbit

- 4. <u>Linear Oscillations</u> (Oct. 5) Taylor's theory and the ubiquity of harmonic motion the damped harmonic oscillator:  $\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = 0$ reduction to algebraic equation generalization to all autonomous homogeneous linear ODEs solution to the damped harmonic oscillator: underdamped and overdamped behavior
- 5. <u>Forced Linear Oscillations</u> (Oct. 7)

 $\ddot{x} + 2\beta \dot{x} + \omega_0^2 x = f(t)$ solution for harmonic forcing  $f(t) = A\cos(\Omega t)$ presence of homogeneous solution: transients amplitude resonance and phase lag; Q factor

6. <u>Green's Functions for Autonomous Linear ODEs</u> (Oct. 10) Fourier transform physical meaning of G(t - t'); causality response to a pulse 7. Systems of Particles (Oct. 12 and 14)

kinetic, potential, and interaction potential energies forces; Newton's third law momentum conservation torque and angular momentum kinetic energy and the work-energy theorem

- 8. <u>MIDTERM EXAMINATION</u> (Oct. 17)
- 9. <u>Calculus of Variations I</u> (Oct. 19)

Snell's law for refraction at an interface continuum limit of many interfaces functionals variational calculus: extremizing  $\int dx L(y, y', x)$ preview: Newton's second law from L = T - U

10. <u>Calculus of Variations II</u> (Oct. 21 and 24)

Examples surfaces of revolution geodesics brachistochrone generalization to several dependent and independent variables Constrained Extremization Lagrange undetermined multipliers in calculus: review systems with integral constraints hanging rope of fixed length holonomic constraints

11. Lagrangian Dynamics (Oct. 26 and 28)

generalized coordinates
action functional
equations of motion: Newton's second law
examples: spring, pendulum, etc.
double pendulum: Lagrangian and equations of motion
Lagrangian for a charged particle interacting with an electromagnetic field
Lorentz force law

- 12. <u>Noether's Theorem and Conservation Laws</u> (Oct. 31 and Nov. 2) continuous symmetries "one-parameter family of diffeomorphisms"  $q_i \rightarrow h_i^{\lambda}(q_1, \dots, q_N)$ Noether's theorem and the conserved "charge"  $Q = \sum_i \frac{\partial L}{\partial q_i} \frac{\partial h_i^{\lambda}}{\partial \lambda}\Big|_{\lambda=0}$ linear and angular momentum
- 13. <u>Constrained Dynamical Systems</u> (Nov. 4 and 7)

undetermined multipliers as forces of constraints simple pendulum with r = l or  $x^2 + y^2 = l^2$  constraint Examples

15.The Two-Body Central Force Problem (Nov. 9, 11, and 14) CM and relative coordinates angular momentum conservation and Kepler's law A = const.energy conservation the effective potential radial equation of motion for the relative coordinate the effective potential and its interpretation phase curves solution for r(t) and  $\phi(t)$  by quadratures 16. The Shape of the Orbit (Nov. 16 and 18) equation for  $r(\phi)$ , the geometric shape of the orbit s = 1/r substitution examples almost circular orbits: bound versus closed motion, precession 17.Coupled Oscillations I: The Double Pendulum (Nov. 21 and 23) review: Lagrangian for the double pendulum equations of motion linearization solution of two coupled linear equations normal modes Coupled Oscillations II: General Theory (Nov. 25 and 28) 18.

harmonic potentials T and V matrices normal modes the mathematical problem: simultaneous diagonalization of T and V

- 19. <u>Coupled Oscillations III: The Recipe</u> (Nov. 30 and Dec. 2) eigenvalues: det $(\omega^2 T - V) = 0$ eigenvectors:  $(\omega_s^2 T_{ij} - V_{ij})a_j^{(s)} = 0$ normalization:  $a_i^{(s)} T_{ij}a_j^{(s')} = \delta_{ss'}$ modal matrix:  $A_{js} = a_j^{(s)}$ examples
- <u>COMPREHENSIVE FINAL EXAMINATION</u> (Dec. 6)