

III.) Kinetic Equations

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- Special Applications: TST, kramers, Colloidal Aggregation, Ita vs. Stratonovich, Diffusion in Inhomogeneous Medium, Poisson Process, Slow Modes, Mode Coupling

q.) Kinetic Equations - An Overview

- consider Langevin equation, for Brownian motion

$$\frac{d\mathbf{v}}{dt} = -\rho \mathbf{v} + \tilde{\mathbf{q}}$$

really seek $P(\mathbf{x}, \mathbf{v}, t) \equiv$ probability to find the
 particle at (\mathbf{x}, \mathbf{v}) on phase
 space at time t .
 object of
 Kinetic Equation

Kinetic equations seek to evolve/determine $P(\mathbf{x}, \mathbf{v}, t)$ directly, rather than to solve Langevin equation and the average.

- Boltzmann equation is an example of a kinetic equation

$$f(x_1, v_1, \dots, x_N, v_N, t) \xrightarrow{\substack{\text{Bogolyubov} \\ \text{Liouvillean}}} f(x, v, t) + \text{Boltzmann Eqn}$$

standard distribution eqn
(phase space density)

e.g. involves $\begin{cases} \text{coarse graining} \\ \text{averaging} \end{cases}$, from $\Gamma_1^t \dots \Gamma_N^t \rightarrow x, v$

- for stochastic processes can formulate hierarchy of equations

① Master Equation (c.f. homework)

$P(n, t) \equiv$ probability to find system in n^{th} state

then, "birth" "death"

$$\frac{\partial P(n, t)}{\partial t} = \underset{\substack{\text{in} \\ \text{from} \\ \text{other states} \\ n'}}{\underset{\text{transitions}}{\uparrow}} - \underset{\substack{\text{out} \\ \text{to other states} \\ n'}}{\underset{\text{transitions}}{\downarrow}}$$

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$$\frac{\partial P(n, t)}{\partial t} = \sum_{n'} \left[P(n', t) W(n' | n) - P(n, t) W(n | n') \right]$$

↑ $n' \rightarrow n$ transition probability (rate)
 ↓ $n \rightarrow n'$ transition probability (rate)

↑ $P(n')$
 ↓ $P(n)$
 ↑ n' probability of state
 ↓ n probability of state

here: probability in $\sim (P \text{ of other states}) * (\text{transition probability})$

probability out $\sim (P \text{ of } n) * (\text{transition probability})$

Master equation is splendid example of "garbage in, garbage out" nature of kinetic equations, in that Master Egn. is only as good as transition probabilities used to construct it!

Master equation tacitly "coarse-grains" in that evolution slower than transition event rate

$$t \rightarrow t + \tau \rightarrow t + 2\tau \rightarrow \dots$$

then $n \rightarrow n'$ event occurs faster than τ ,

② Fokker-Planck Equation

Consider system with no memory i.e. each step on \mathcal{T} independent of prior history.

so can write:

$$P(x_3, t_3 | x_1, t_1) = \int dx_2 P(x_3, t_3 | x_2, t_2) \cdot P(x_2, t_2 | x_1, t_1)$$

⌠ ⌠ ⌠ ⌠
 prob. of x_3 at t_3 integration $2 \rightarrow 3$ $1 \rightarrow 2$ jump
 starting from x_1 over jump states

$$\xrightarrow{1 \rightarrow 3} = \sum_{1 \rightarrow 2} \xrightarrow{1 \rightarrow 2} \xrightarrow{2 \rightarrow 3}$$

and

- multiplicative, as independent steps
- sum over intermediate states.

above is Chapman-Kolmogorov Equation

I will extend to where

transition probability of x , of
↓ step Δx in time τ

$$P(x_2, t_2 | x_1, t_1) = T(x, \Delta x, \tau)$$

i.e. $t_2 - t_1$ is jump time τ
 $x_2 - x_1$ is jump step Δx

then Chapman-Kolmogorov Equation becomes

$$P(x, t+\tau) = \int d(\Delta x) P(x-\Delta x, t) T(x, \Delta x, \tau)$$

and expansion (with T indep. x) \Rightarrow

$$\frac{\partial P}{\partial t} = -\frac{\partial}{\partial x} \left\{ \frac{\langle \Delta x \rangle}{\tau} P - \frac{\partial}{\partial x} \frac{\langle \Delta x \Delta x \rangle}{2\tau} P \right\}$$

$$= -\frac{\partial}{\partial x} \underset{\substack{\downarrow \\ \text{probability}}}{F_p} \quad \begin{array}{l} \text{generic form of} \\ \text{Fokker-Planck Equation} \\ (\text{F-P. E.}) \end{array}$$

Note :

- F.P. Equation - no memory on scales $\tau > \tau'$
- F.P. Equation - "coarse-grains" out $\left\{ \begin{array}{l} t < \tau \\ x < \Delta x \end{array} \right.$

- F-P Equation is less general, but more tractable than Master Equation.

③ Zwanzig - Mori Equation

F-P Eqn. with Memory kernel (Memory correction) \equiv Memory

i.e. variables x_1, x_2, \dots, x_N

for t slower than some $\bar{\tau}_1$, separate into 'fast' and 'slow' variables

$$\begin{array}{c} x_1, x_2, \dots, x_p \} x_{p+1} \dots x_N \\ \downarrow \text{slow} \qquad \qquad \qquad \downarrow \text{fast} \\ \dot{x}_i/x_i < 1/\bar{\tau} \qquad \qquad \dot{x}_i/x_i > 1/\bar{\tau} \end{array}$$

Z-M theory:

- assumes fast variables come to \odot equilibrium on time scales $\bar{\tau}$
- can describe evolution in terms of slow variables, only.

then:

- $\underline{P}(x_1, x_2, \dots, x_N) \rightarrow (x_1, \dots, x_p)$

\uparrow
projection operator P projects evolution onto reduced # degrees of freedom, the slow variables.

- write projected Liouville equation, for slow variables $\Rightarrow Z\text{-M. Egn.}$
- not surprisingly, $Z\text{-M. Egn.}$ can reduce to $F\text{-P. Egn.}$
- $Z\text{-M.}$ clearly coarse-grains over fast variables
- $Z\text{-M.}$ projection procedure part, but not all of R.G. procedure (Renormalization Group) theory.

8. Fokker-Planck Theory

- seek Pdf P of Markovian, stochastic variable
- Markovian \equiv stochastic process s/t $t + \Delta t$ determined by state at t , only.

\hookrightarrow no memory

so, as in Brownian Motion

$$P(v, t + \Delta t) = \int d(\Delta v) P(v - \Delta v, t) T(\Delta v, \Delta t)$$

↑ ↑ ↑
 state at state at transition
 $t + \Delta t$ t probability

\Rightarrow expand

$$P(v, t) + \Delta t \frac{\partial P}{\partial t} = \int d(\Delta v) \left\{ P(v, t) T(\Delta v, \Delta t) \right\}$$

$$- \frac{\partial}{\partial v} \left(\Delta v T(\Delta v, \Delta t) P(v, t) \right) + \frac{1}{2} \frac{\partial^2}{\partial v^2} \left(\Delta v \Delta v T(\Delta v, \Delta t) P(v, t) \right)$$

now, as T is transition probability, it is normalized, so \Rightarrow

$$\underline{\text{so}} \quad \int d\Delta V T(\Delta V, \Delta t) = 1$$

$$\int d\Delta V \Delta V T(\Delta V, \Delta t) = \langle \Delta V \rangle$$

expectation
(must exist)

$$\int d\Delta V \Delta V \Delta V T(\Delta V, \Delta t) = \langle \Delta V \Delta V \rangle$$

Variance
(must exist)

$$P(\underline{v}, t) + \Delta t \frac{\partial P}{\partial t} = P(\underline{v}, t) - \frac{\partial}{\partial \underline{v}} \left(\langle \Delta V \rangle P(\underline{v}, t) \right)$$

$$+ \frac{1}{2} \frac{\partial}{\partial \underline{v}} \cdot \left[\frac{\partial}{\partial \underline{v}} \left(\langle \Delta V \Delta V \rangle P(\underline{v}, t) \right) \right]$$

$$\left\{ \begin{aligned} \frac{\partial P(\underline{v}, t)}{\partial t} &= - \frac{\partial}{\partial \underline{v}} \cdot \left\{ \frac{\langle \Delta V \rangle P(\underline{v}, t)}{\Delta t} - \frac{\partial}{\partial \underline{v}} \cdot \frac{\langle \Delta V \Delta V \rangle P(\underline{v}, t)}{2 \Delta t} \right\} \\ &= - \frac{\partial}{\partial \underline{v}} \cdot F_p \end{aligned} \right.$$

- Fokker-Planck Equation

Now, can note:

- $\frac{\partial P}{\partial t} = -D \cdot \nabla_P^2 P$ structure assures F-P. Egn. conserves probability. Derivative order matters!
- Obviously can relate F-P. Egn. to Master Egn. in "small kick" limit. (See Prob. 3 of HW 1).
- as example, for Brownian Motion

$$\frac{\partial v}{\partial t} = -\beta v + \tilde{q}(t)$$

\tilde{q}
↔ broadband noise

$$\text{so } \frac{\langle \Delta v \rangle}{\Delta t} = -\beta v$$

$$\frac{\langle \Delta v \Delta v \rangle}{2\Delta t} = D_v \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$D_v = \tilde{q}_0^2 T_{\text{ac}}$$

(uncorrelated direction)

$$\frac{\partial P}{\partial t} = -\frac{\partial}{\partial v} \cdot \left\{ -\beta v P - \frac{\partial D_v}{\partial v} P \right\} \rightarrow \begin{cases} \text{F-P. Egn.} \\ \text{for} \\ \text{Brownian} \\ \text{Motion} \end{cases}$$

$$\text{in 1D, } \frac{\partial P}{\partial t} = +\frac{\partial}{\partial v} \left\{ \beta v P + D_v \frac{\partial P}{\partial v} \right\}$$

so, at equilibrium ($\partial P / \partial t = 0$)

$$P \approx \exp \left[-\beta v^2 / 2 D_v \right]$$

i.e. Gaussian pdf formed by balance of drag with diffusion.

In the absence of drag, with $P(v, 0) = \delta(v - v_0)$

$$P(v, t) = \frac{1}{\sqrt{\pi D_v t}} \exp \left[-v^2 / 2 D_v t \right] \quad \text{i.e. diffusion pdf}$$

- F-P. Equation structure (general) :

$$\begin{matrix} \text{drag/drift} \\ \text{term} \end{matrix} \rightarrow \frac{\langle \Delta v \rangle P}{4t} = \nabla P \quad \hookrightarrow \begin{matrix} \text{drift} \\ \text{velocity} \end{matrix}$$

$$\begin{matrix} \text{diffusion} \\ \text{term} \end{matrix} \rightarrow -\frac{\partial}{\partial v} \cdot \frac{\langle \Delta v \Delta v \rangle}{2t} P = -\frac{\partial}{\partial v} \cdot \frac{\underline{D}_v}{\underline{v} v} P$$

↓
diffusion tensor

$$\text{and: } \frac{\partial P}{\partial t} + \frac{\partial}{\partial v} (\nabla P) = + \underline{D}_v \cdot \nabla_{\underline{v}} P$$

$$\underline{D}_v = -\nabla P + \underline{D}_v \cdot \underline{R}_v P$$

drift \rightarrow deterministic part of motion

diffusion \rightarrow random part. (noise related)

- requirements for applicability of Fokker Planck Theory

\rightarrow stochastic motion

\rightarrow step size

$\Delta v, \Delta p$

\rightarrow no memory ($t > \Delta t$)

and

$$\left. \begin{array}{l} \langle \Delta v \rangle < \infty \\ \langle \Delta v^2 \rangle < \infty \end{array} \right\} \rightarrow \text{convergence of lowest 2 moments}$$

at Central Limit Theorem.

if $\langle \Delta v^2 \rangle \rightarrow \infty$, need turn to Fractional kinetics.
 CTRW
 \rightarrow Levy Flights, etc.

- Fokker-Planck equation \leftrightarrow Markov Process or chain, which is gradient unfolding of transition probability just \approx

conservative dynamical system is gradual unfolding of contact transformation.

- for
 - Hamiltonian system \leftrightarrow Liouville Thm.
 - no systematic bias

can show: (HW)

$$\frac{1}{2} \frac{\partial}{\partial V} \cdot \langle \underline{\Delta V} \underline{\Delta V} \rangle = \langle \underline{\Delta V} \rangle$$

i.e. partial cancellation of diffusion and drag / drift

$$\begin{aligned} \text{i.e. } \frac{\partial P}{\partial t} &= - \frac{\partial}{\partial V} \left(\frac{\langle \underline{\Delta V} \rangle P}{\Delta t} - \frac{\partial}{\partial V} \frac{\langle \underline{\Delta V} \underline{\Delta V} \rangle P}{2 \Delta t} \right) \\ &= - \frac{\partial}{\partial V} \left(\frac{\langle \underline{\Delta V} \rangle}{\Delta t} - \left(\frac{\partial}{\partial V} \frac{\langle \underline{\Delta V} \underline{\Delta V} \rangle}{2 \Delta t} \right) P \right. \\ &\quad \left. - \frac{\langle \underline{\Delta V} \underline{\Delta V} \rangle}{2 \Delta t} \cdot \frac{\partial P}{\partial V} \right) \end{aligned}$$

$$= \frac{\partial}{\partial V} \frac{P_V \cdot \partial P}{\partial V} \rightarrow \begin{array}{l} \text{Form of diffusion} \\ \text{equation for} \\ \text{Hamiltonian system} \\ (\text{note order of derivatives!}) \end{array}$$

Here $\langle \Delta V \rangle = \frac{1}{2} \frac{\partial}{\partial V}$, $\langle \Delta V \Delta V \rangle$ is analogue of incompressibility of phase space flow for stochastic system.

→ Now can extend Fokker-Planck theory to bivariate evolution.

i.e. consider Brownian Motion in External Force Field ---

$$\frac{\partial V}{\partial t} = -\beta V + q_{ext} + \tilde{q}$$

\downarrow

↳ Brownian force

$$\frac{f_{ext}}{m_p} = -\frac{\partial \phi}{\partial p} \quad \begin{matrix} \rightarrow \text{potential} \\ (\text{i.e. spring gravity}) \end{matrix}$$

$$\frac{dX}{dt} = v$$

so obviously particle random walks in X and V ,
For phase space pdf:

$$P(X, V, t + \Delta t) = \int d(\Delta X) \int d(\Delta V) \left\{ P(X - \Delta X, V - \Delta V, t) T(\Delta X, \Delta V, \Delta t) \right\}$$

Furthermore, Brownian kick applied only in \underline{v}
 so \underline{x} kinematic

\Rightarrow

$$T(\underline{\Delta x}, \underline{\Delta v}, \Delta t) = \delta(\underline{\Delta x} - \underline{v} \Delta t) T(\underline{\Delta v}, \Delta t)$$

∴

$$\begin{aligned} P(\underline{x}, \underline{v} + \Delta t) &= \int d(\underline{\Delta x}) \int d(\underline{\Delta v}) P(\underline{x} - \underline{\Delta x}, \underline{v} - \underline{\Delta v}, +) * \\ &\quad \delta(\underline{\Delta x} - \underline{v} \Delta t) T(\underline{\Delta v}, \Delta t) \\ &= \int d(\underline{\Delta v}) P(\underline{x} - \underline{v} \Delta t, \underline{v} - \underline{\Delta v}, +) T(\underline{\Delta v}, \Delta t) \end{aligned}$$

so can re-write:

$$P(\underline{x} + \underline{v} \Delta t, \underline{v}, + \Delta t) = \int d\underline{\Delta v} P(\underline{x}, \underline{v} - \underline{\Delta v}, +) T(\underline{\Delta v}, \Delta t)$$

and now expand, as before:

$$+ q_{ext} \cdot \frac{\partial P}{\partial \underline{v}}$$

$$\frac{\partial P}{\partial t} + \underline{v} \cdot \nabla_x P = - \frac{q}{\Delta t} \left[\frac{\langle \underline{\Delta v} \rangle}{\Delta t} P - \frac{\partial}{\partial \underline{v}} \cdot \frac{\langle \underline{\Delta v} \underline{\Delta v} \rangle}{2 \Delta t} P \right]$$

more generally have shown can write:

$$\left. \frac{dP}{dt} \right\} = F.P. \text{ Operator} = \beta \underbrace{\frac{\partial}{\partial V} \cdot (V P)}_{\text{deterministic orbits}} + \alpha \frac{\partial^2 P}{\partial V^2} \underbrace{\text{randomly fluctuating orbits}}$$

where "deterministic orbits" means:

$$\frac{dx}{dt} = v, \quad \frac{dv}{dt} = g_{ext}$$

$$\rightarrow \text{Now } P = P(x, v, t).$$

Often seek only $P(x, t)$, so ... can obtain full $P(x, v, t)$ and integrate over v , which is laborious

or
derive moment equations of F.P. Equation
in Γ , yield "fluid equations" in x !

obviously

akin to deriving fluid equations from Boltzmann equation

i.e. from F-P eqn. for $P(\underline{x}, \underline{v}, t)$

derive equations for:

$$n(\underline{x}, t) = \int d\underline{v} P(\underline{x}, \underline{v}, t) \rightarrow \text{density}$$

$$\underline{v}(\underline{x}, t) = \int d\underline{v} \underline{v} P(\underline{x}, \underline{v}, t) / n(\underline{x}, t) \rightarrow \begin{matrix} \text{Eulerian} \\ \text{velocity} \end{matrix}$$

n -equation \leftrightarrow Schnoluchowski Equation

Next have: (for Brownian Particle)

$$\frac{\partial P}{\partial t} + \underline{v} \cdot \nabla_{\underline{x}} P + q_{\text{ext}} \cdot \nabla_{\underline{v}} P$$

$$= \beta \frac{\partial}{\partial \underline{v}} \cdot (\underline{v} P) + D_v \frac{\partial^2 P}{\partial \underline{v}^2}$$

which can be re-written as:

$\underbrace{\qquad}_{\text{in a superficially very complicated form, as...}}$

$$\frac{\partial P}{\partial t} = \beta \left(\frac{\partial}{\partial v} - \frac{1}{\beta} \frac{\partial}{\partial x} \right) \cdot \left(v P + \frac{\partial v}{\beta} \frac{\partial P}{\partial v} - \frac{P_{ext}}{\beta} + \frac{\partial v}{\beta^2} \frac{\partial P}{\partial x} \right)$$

$$+ \frac{\partial}{\partial x} \left(\frac{\partial v}{\beta} \frac{\partial P}{\partial x} - \frac{P_{ext}}{\beta} \right)$$

①

②

$$\text{Now: } n(x, t) = \int dv P(x, v, t)$$

$$x + \frac{v}{\beta} = x_0$$

i.e. integrate along line s.t. $\dot{x} = -v/\beta$

→ This annihilates term #①!

$$\text{i.e. } x + \frac{v}{\beta} = \text{const} \Rightarrow \frac{\partial}{\partial v} - \frac{1}{\beta} \frac{\partial}{\partial x} = 0$$

so obtain:

$$\frac{\partial n(x, t)}{\partial t} = \frac{1}{\beta} \cdot \left(\frac{\partial v}{\partial^2} \frac{\partial n}{\partial x} - \frac{q_{ext}}{\beta} n \right)$$

- the Smoluchowski eqn. for $n(x, t) \rightarrow$ spatial pdf

Observe:

- can short-circuit complicated derivation by simply going to "terminal velocity" limit.

i.e. eqns of motion:

$$\frac{\partial v}{\partial t} = -\beta v + q_{ext} + \tilde{q}$$

$$\frac{dx}{dt} = v$$

at terminal velocity,

$$v = \frac{q_{ext}}{\beta} + \frac{\tilde{q}}{\beta}$$

\rightarrow random

$$\frac{dx}{dt} = q_{ext} + \frac{\tilde{q}}{\beta}$$

\hookrightarrow deterministic

$$\left\{ \begin{array}{l} \frac{\partial n}{\partial t} + \underline{\partial} \cdot \left(\frac{dx}{dt} \underline{n} \right) = D_{xx} \frac{\partial^2 n}{\partial x^2} \\ \text{deterministic} \\ D_{xx} = Dv/\beta^2 \end{array} \right.$$

\Rightarrow Schmoluchowski Eqn.

- still conservative:

$$\frac{\partial n}{\partial t} = - \underline{\partial} \cdot \underline{\Gamma}_n$$

$$\underline{\Gamma}_n = \left(\frac{q_{\text{ext}}}{\beta} n - \frac{Dv}{\beta^2} \frac{\partial n}{\partial x} \right)$$

Next: I - Another look at Fokker-Planck Theory

II - Kinetics of Chemical Reactions

a) Transition State Theory

b) Kramers' Problem

- 1.) first passage time } $\gamma \rightarrow \infty$
- 2.) reaction rate constants } $\gamma \rightarrow 0$
- 3.) energy diffusion } $\gamma \rightarrow 0$.

III. Colloidal Aggregation

I Another Look at Fokker-Planck Theory

ref. R. Zwanzig, "Nonequilibrium Statistical Mechanics"

For dynamics which preserves phase space volume
i.e. incompressible V_T , can write:

Theory of
Liouville

$$\frac{\partial}{\partial t} f = \left(\frac{\partial \mathcal{L}}{\partial x_i}, \frac{\partial \mathcal{L}}{\partial p_i} \right) ; \quad V = V_T = \left\{ \frac{df}{dt}, \frac{dp}{dt} \right\} \text{ operator}$$

so $f(x, t) = e^{-tL} f(x, 0)$

as $\frac{\partial f}{\partial t} + Lf = 0$ (x, p) dimensionality
arbitrary

$$L = \frac{\partial H}{\partial p} \cdot \frac{\partial}{\partial q} - \frac{\partial H}{\partial q} \cdot \frac{\partial}{\partial p} \quad \leadsto \text{Liouville operator}$$

Interesting to note properties of Liouville operator... e.

) For $A = A(\underline{x}) \rightarrow$ arbitrary $\left\{ \begin{array}{l} \text{function} \\ \text{operator} \end{array} \right\}$ of/in Γ

often seek: $\int_{\text{Vol}} d\underline{x} L A f$ $\stackrel{\text{c.e.}}{=} \left\{ \begin{array}{l} \text{weighted avg/expectation} \\ \text{of } A \text{ in domain } \Gamma \end{array} \right\}$

now: $L = \underline{V} \cdot \underline{\nabla} = \underline{\nabla} \cdot (\underline{V})$, as $\underline{\nabla} \cdot \underline{V}_{\Gamma} = 0$
 $\frac{\partial}{\partial t} + L = 0$ (and $\frac{\partial \rho}{\partial t} = -\underline{\nabla} \cdot (\underline{\rho} \cdot \underline{V})$)

$$\int_{\text{Vol}} d\underline{x} L A f = + \int_{\text{Vol}} d\underline{x} \frac{d}{dx} \cdot (\underline{V} A f)$$

effective
flow velocity

$$= - \oint d\underline{s} \cdot \underline{V} A f \quad (\text{normal c.g.})$$

so avg of evolution A entirely determined by values of: $\underline{V} \leftrightarrow$ phase space flow velocity and f on boundary of averaging region

2) L is anti-self adjoint $\therefore L^+ = -L$

$$L(Af) = (LA)f + A(Lf)$$

as L is first order diffntl operator

Now, consider $\int d\underline{x} A(Lf)$

but $L(Af) = (LA)f + A(Lf)$

$$\therefore \int dx A(Lf) = \int dx \{ L(Af) - (LA)f \}$$

$$= \int dx \left\{ \frac{d}{dx} (Aaf) - (LA)f \right\}$$

and for $f \rightarrow 0$ at $x \rightarrow \infty$ (normalizability) \Rightarrow

$$\boxed{\int dx A(Lf) = - \int dx (LA)f}$$

What does $\int e^{Lt} \underline{\underline{mean}}$, physically?

In general; seek calculate aspects of general many body system

$A(x)$ = generic dynamical variable

then $\left. \frac{\partial A}{\partial t} \right|_{t=0} = \left. \frac{\partial A}{\partial \underline{x}} \cdot \frac{\partial \underline{x}}{\partial t} \right|_{t=0} + \left. \frac{\partial A}{\partial p} \cdot \frac{\partial p}{\partial t} \right|_{t=0}$

$$= LA$$

and $\left(\frac{\partial^n A}{\partial t^n} \right)_{t=0} = L^n A$

$$\text{so } A(\underline{x}, t) = \sum_{n=0}^{\infty} \frac{t^n}{n!} \left. \frac{\partial^n A}{\partial t^n} \right|_{t=0}$$

d.e. Taylor Series

$$= \sum_{n=0}^{\infty} \frac{t^n}{n!} L^n A(\underline{x}) = e^{tL} A(\underline{x})$$

thus

$$\begin{cases} \frac{\partial A}{\partial t} (\underline{x}, t) = L A(\underline{x}, t) \Rightarrow A(\underline{x}, t) = e^{tL} A(\underline{x}) \\ A(\underline{x}, 0) = A(\underline{x}) \end{cases}$$

$e^{tL} \rightarrow$ propagator / orbit evolution operator

→ moves particle along trajectory in phase space

d.e.

$$\int_{t=0}^t \frac{dx(t)}{dt} \leftrightarrow e^{tL}$$

then rather obvious (as V_H is compressible)
that:

$$e^{tL} A(\underline{x}) = A(e^{tL} \underline{x})$$

and

trajectory unique!

$$\begin{aligned} e^{tL} (A(\underline{x}) B(\underline{x})) &= (e^{tL} A(\underline{x})) (e^{tL} B(\underline{x})) \\ &= A(e^{tL} \underline{x}) B(e^{tL} \underline{x}) \end{aligned}$$

Now can formulate phase space averages of A (aka expectation in \mathcal{QM}). Point is that can approach either aka' Schrödinger or Heisenberg, i.e.

$$\begin{aligned} \langle A, t \rangle &= \int d\underline{x} A(\underline{x}) f(\underline{x}, t) \\ \text{avg. at } t \text{ time } t &= \int d\underline{x} A(\underline{x}) e^{-tL} f(\underline{x}, 0) \end{aligned} \quad \frac{\partial f}{\partial t} + Lf = 0$$

i.e. aka' Schrödinger \rightarrow f evolves

$\sim 1/p^2$ weighting pdf

equivalently \downarrow value of A at t , from initial state \underline{x} .

$$\langle A, t \rangle = \int d\underline{x} A(\underline{x}, t) f(\underline{x}, 0)$$

$$= \int d\underline{x} (e^{tL} A(\underline{x}, 0)) f(\underline{x}, 0)$$

L anti-self-adjoint

i.e. aka' Heisenberg \rightarrow A evolves

\sim aka' operator.

→ which brings us to Fokker-Planck theory, again . . .

Point of F-P theory :

- convert stochastic orbit equation (i.e. Langevin equation) into 'well-behaved' equation for pdf [HARD, in general]
- consider 'simplest' case \rightarrow zero 'memory' limit
 \rightarrow Markovian approximation

Now $\frac{d\alpha}{dt} = \underline{v(\alpha)} + \underline{F(t)}$ \rightarrow schematic Langevin equation

$\begin{matrix} \text{deterministic} \\ \text{velocity/flow} \end{matrix}$ $\begin{matrix} \text{noise} \\ \text{flctns} \end{matrix}$

Now, generically : $(\frac{d\alpha}{dt}) f$

$$\frac{\partial f(\alpha, t)}{\partial t} + \underline{\omega} \cdot \left((\underline{v(\alpha)} + \underline{F(t)}) f \right) = 0 \quad \left\{ \begin{matrix} \text{can develop} \\ \text{P.T. on noise} \\ \text{strength} \end{matrix} \right.$$

* $\frac{\partial f(\alpha, t)}{\partial t} = - \underline{\omega} \cdot \left(\underline{v(\alpha)} f(\alpha, t) + \underline{F(t)} f(\alpha, t) \right)$

$$= -L f - \underline{\omega} \cdot \left(\underline{F(t)} f(\alpha, t) \right)$$

170.

Now,

$$\underset{\text{in } \tilde{F}}{-L \cdot \underset{Q}{\cancel{\frac{\delta f}{\delta t}}} + Lf = 0}$$

$$f(\underline{q}, t) = e^{-tL} f(\underline{q}, 0)$$

and plugging into $\textcircled{*}$ gives:

$$\underset{t}{\frac{\partial f(\underline{q}, t)}{\partial t}} = -Lf - \underset{Q}{\cancel{\frac{\partial}{\partial q} \cdot (F(t) f(\underline{q}, t))}} \quad \textcircled{**}$$

- 1st order in \tilde{F}

Solving $\textcircled{**} \Rightarrow$

$$f(\underline{q}, t) = e^{-tL} f(\underline{q}, 0) - \int_0^t ds e^{-(t-s)L} \underset{Q}{\cancel{\frac{\partial}{\partial q} \cdot (F(s) f(\underline{q}, s))}}$$

$$l.o. \rightarrow O(F^{(1)})$$

$O(F^{(1)}) -$
first order

and plug $f(\underline{q}, t)$ above into Eqn. $\textcircled{*}$



\Rightarrow

$$\begin{aligned} \frac{\partial f(g, t)}{\partial t} &= -Lf - \frac{\partial}{\partial g} \cdot \left(\underline{F(t)} \left\{ e^{-tL} f(g, 0) \right. \right. \\ &\quad \left. \left. - \int_0^t ds e^{-(t-s)L} \frac{\partial}{\partial g} \cdot (\underline{F(s)} f(g, s)) \right\} \right) \\ &= -Lf - \frac{\partial}{\partial g} \cdot \underline{F(t)} e^{-tL} f(g, 0) \\ &\quad + \frac{\partial}{\partial g} \cdot \underline{F(t)} \int_0^t ds e^{-(t-s)L} \frac{\partial}{\partial g} \cdot (\underline{F(s)} f(g, s)) \end{aligned}$$

Now, average over $P(F)$, assuming:

$$\rightarrow \langle F \rangle = 0, \quad \langle FF \rangle \neq 0$$

$$\rightarrow \langle F(t) F(s) \rangle = F_0^2 \tau_{av} \delta(t-s)$$

"delta correlated" limit

so $\langle f \rangle = \langle f(g, t) \rangle$ evolves according to:
 ↓ ↗
 coarse-grained pdf

$$\boxed{\frac{\partial \langle f \rangle}{\partial t} = - \frac{\partial}{\partial q} \cdot \left(V(q) \langle f \rangle - \frac{\partial}{\partial q} \cdot \frac{B}{\eta} \langle f \rangle \right)}$$

→ Fokker-Planck Eqn.
(again...)

the lesson:

- F-P. Eqn. emerges from Liouville equation for stochastic phase space evolution, i.e.
Langevin eqn. = orbit eqn. + noise.
- F-P. Eqn. requires: delta correlated forcing (Markovianization), symmetric pdf forcing, $\langle P^2 \rangle < \infty$
- Can develop F-P. equation as series expansion on \tilde{F} .

→ Properties of Fokker-Planck Operator

$$\left\{ \begin{array}{l} \langle f(q,t) \rangle = f(q,t) , \text{ hereafter} \\ \underline{\beta} \text{ indep. } q \end{array} \right.$$

$$\frac{\partial f(q,t)}{\partial t} = \mathcal{D} f(q,t)$$

$$\mathcal{D}f = -\frac{\partial}{\partial q} \cdot (\underline{V}(q) f) + \frac{\partial}{\partial q} \cdot \underline{\beta} \cdot \frac{\partial f}{\partial q}$$

Now, easy to define/derive adjoint operator
to \mathcal{D} .

$$\int d\Omega \varphi(q) \mathcal{D} \psi(q) = \int d\Omega \psi(q) \mathcal{D}^+ \varphi(q)$$

Exercise: Show
this!

$$\mathcal{D}^+ = \underline{V}(q) \cdot \frac{\partial}{\partial q} + \frac{\partial}{\partial q} \cdot \underline{\beta} \cdot \frac{\partial}{\partial q}$$

↑
sign flip,
deriv. order
changes.

↑
diffusing is self-adjoint
(this form)

$$\text{Now, } f(\underline{q}, t) = e^{\frac{D}{\hbar}t} f(\underline{q}, 0)$$

so expectation value defined as;

$$\begin{aligned}\langle \phi, t \rangle &= \int d\underline{q} \ \phi(\underline{q}) f(\underline{q}, t) \\ &= \int d\underline{q} \ \phi(\underline{q}) e^{\frac{D}{\hbar}t} f(\underline{q}, 0)\end{aligned}$$

~ Schrödinger representation \rightarrow pdf evolves.

$$\stackrel{\text{on}}{=} \langle \phi, t \rangle = \int d\underline{q} \ f(\underline{q}, 0) e^{\frac{D}{\hbar}t} \phi(\underline{q})$$

~ Heisenberg representation \rightarrow ϕ , the expectation of which is calculated, evolves ...