



(i) **Dynamical variables:** There are many equivalent choices. The simplest one is the angular displacement of each mass, θ_n , with respect to the equilibrium position (defined by all penduli masses directly below the wire and the wire being untwisted). We can be even more careful and define the sense of positive displacement, e.g., counter-clockwise when looking down the wire in the direction of increasing index "n". We won't need to be that specific.

The range of the variables is $\theta_n \in (-\infty, \infty)$. Note that θ_n and $\theta_n + 2\pi$ need not be identified, because holding all other penduli fixed, there is a different twist in the wire between configurations $\{\dots, \theta_{n-1}, \theta_n, \theta_{n+1}, \dots\}$ and $\{\dots, \theta_{n-1}, \theta_n + 2\pi, \theta_{n+1}, \dots\}$.

(ii) Kinetic energy of n-th pendulum: $\frac{1}{2} m l \dot{\theta}_n^2$

Gravitational energy \checkmark : $m g l (1 - \cos \theta_n)$

Elastic energy (twist) in wire between n-th and n+1-st penduli: $\frac{1}{2} k (\theta_{n+1} - \theta_n)^2$

$$\Rightarrow L = \sum_n \left[\frac{1}{2} m l^2 \dot{\theta}_n^2 + m g l \cos \theta_n - \frac{1}{2} k (\theta_{n+1} - \theta_n)^2 \right]$$

$$\text{E.O.M. } \frac{\partial L}{\partial \dot{\theta}_n} = m l^2 \ddot{\theta}_n \quad \frac{\partial L}{\partial \theta_n} = -m g l \sin \theta_n - k (\theta_{n+1} - \theta_{n-1}) - k (\theta_n - \theta_{n+1})$$

$$\Rightarrow -\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) + \frac{\partial L}{\partial \theta} = 0 \quad ; \quad m l^2 \ddot{\theta}_n + m g l \sin \theta_n - k (\theta_{n+1} + \theta_{n-1} - 2\theta_n) = 0$$

(iii) We want $L \rightarrow \int dx \mathcal{L}(x)$ when $\Theta_n \rightarrow \phi(x_n)$, $x_n = na$.

So write $\Delta n = (n+1) - n = 1$ and $\Delta x = a \Delta n$, so

$$\sum_n L_n = \sum_n \Delta n L_n \rightarrow \int dx \frac{1}{a} L(na)$$

To this end inspect terms in L/a

$$\frac{1}{a} \left(\frac{m}{2} l^2 \dot{\theta}_n^2 \right) = \frac{1}{2} m l^2 \left(\frac{\partial \phi(x,t)}{\partial t} \right)^2 \Big|_{x=na}$$

$$\frac{1}{a} m g l \cos \theta_n = \frac{m}{a} g l \cos \phi(x,t) \Big|_{x=na}$$

$$-\frac{1}{2} \frac{k}{a} (\theta_{n+1} - \theta_n)^2 = -\frac{1}{2} k a \left(\frac{\phi(x+a,t) - \phi(x,t)}{a} \right)^2 \Big|_{x=na} \rightarrow -\frac{1}{2} k a \left(\frac{\partial \phi}{\partial x} \right)^2 \Big|_{x=na}$$

Collecting and taking the limit $a \rightarrow 0$ ($n \rightarrow \infty$),

$$\mathcal{L} = \frac{1}{2} \left(\frac{m}{a} \right) l^2 \left(\frac{\partial \phi}{\partial t} \right)^2 + \frac{m}{a} g l \cos \phi - \frac{1}{2} (ka) \left(\frac{\partial \phi}{\partial x} \right)^2$$

Clearly we want $\frac{ml^2}{a} = \text{fixed}$, $\frac{mgl}{a} = \text{fixed}$ and $ka = \text{fixed}$ as $a \rightarrow 0$.

It is sufficient to take, say, $\frac{m}{a} = \sigma$ and $ka = \rho$, with g and l constant.

$$EOM: \quad \mathcal{L} = \frac{1}{2} (l^2 \partial_t \phi, \partial_x \phi, \phi) \quad \delta S = \int dt dx \delta \phi \left[- \partial_t \frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} - \partial_x \frac{\partial \mathcal{L}}{\partial (\partial_x \phi)} + \frac{\partial \mathcal{L}}{\partial \phi} \right] = 0$$

$$\frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} = \left(\frac{m}{a} \right) l^2 \partial_t \phi, \quad \frac{\partial \mathcal{L}}{\partial (\partial_x \phi)} = - (ka) \partial_x \phi \quad \frac{\partial \mathcal{L}}{\partial \phi} = - \frac{m}{a} g l \sin \phi$$

$$\Rightarrow - \left(\frac{m}{a} \right) l^2 \partial_t^2 \phi + (ka) \partial_x^2 \phi - \frac{m}{a} g l \sin \phi = 0 \quad (EOM)$$

Hamiltonian density $\mathcal{H} = \pi \partial_t \phi - \mathcal{L}$ with $\pi = \frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} = \frac{m}{a} l^2 \partial_t \phi \Rightarrow \partial_t \phi = \frac{a}{ml^2} \pi$

$$\mathcal{H} = \frac{1}{2} \frac{a}{ml^2} \pi^2 - \frac{m}{a} g l \cos \phi + \frac{1}{2} (ka) \left(\frac{\partial \phi}{\partial x} \right)^2$$

(iv) We want to insist that $\mathcal{L}(\phi') = \mathcal{L}(\phi)$ where $\phi'(x) = \phi(\Lambda x)$, where Λ is a Lorentz transformation, $(\Lambda x)^m = \begin{pmatrix} \gamma & \gamma \beta \\ \gamma \beta & \gamma \end{pmatrix} \begin{pmatrix} x^0 \\ x' \end{pmatrix}$ with $\gamma^2 = \frac{1}{1-\beta^2}$ and $x^0 = ct$. That is

$$t' = \gamma(t + \beta \frac{x}{c}) \quad . \quad \text{We need to compute } \frac{\partial \phi'}{\partial t} \text{ and } \frac{\partial \phi'}{\partial x} :$$

$$x' = \gamma(\beta c t + x)$$

$$\frac{\partial \phi'}{\partial t} = \frac{\partial t}{\partial t} \frac{\partial \phi(t', x)}{\partial t} + \frac{\partial x}{\partial t} \frac{\partial \phi(t', x)}{\partial x}$$

$$= \gamma \partial_t \phi + c \gamma \beta \partial_x \phi$$

$$\frac{\partial \phi'}{\partial x} = \frac{\partial t}{\partial x} \frac{\partial \phi(t', x')}{\partial t} + \frac{\partial x}{\partial x} \frac{\partial \phi(t', x')}{\partial x'}$$

$$= \frac{1}{c} \gamma \beta \partial_t \phi + \gamma \partial_x \phi$$

$$S_0 \quad \mathcal{L}(\phi) = \frac{1}{2} \frac{m l^2}{a} \left(\frac{\partial \phi}{\partial t} \right)^2 - \frac{1}{2} k a \left(\frac{\partial \phi}{\partial x} \right)^2 + \frac{m}{a} g l \cos \phi'$$

$$= \frac{1}{2} \frac{m l^2}{a} \left[\gamma \partial_t \phi + c \gamma \beta \partial_x \phi \right]^2 - \frac{1}{2} k a \left[\frac{1}{c} \gamma \beta \partial_t \phi + \gamma \partial_x \phi \right]^2 + \frac{m}{a} g l \cos \phi \quad (\text{all } \phi \text{ & } \partial \phi \text{ even terms dropped at } x' \rightarrow \infty)$$

$$= \frac{1}{2} \left(\frac{m l^2}{a} \gamma^2 - k a \left(\frac{\gamma \beta}{c} \right)^2 \right) \left(\partial_t \phi \right)^2 - \frac{1}{2} \left(k a \gamma^2 - \frac{m l^2}{a} \left(c \gamma \beta \right)^2 \right) \left(\partial_x \phi \right)^2$$

$$+ \left(\frac{m l^2}{a} \gamma \left(c \gamma \beta \right) - k a \left(\frac{\gamma \beta}{c} \right) \gamma \right) \partial_t \phi \partial_x \phi + \frac{m}{a} g l \cos \phi$$

This is of the form $A \left(\frac{1}{c^2} (\partial_t \phi)^2 - (\partial_x \phi)^2 \right)$ with A a constant, provided

$$\frac{m l^2}{a} c \gamma \beta - k a \frac{\gamma \beta}{c} = 0 \text{ and } \frac{k a \gamma^2 - \frac{m l^2}{a} (c \gamma \beta)^2}{\frac{m l^2}{a} \gamma^2 - k a \left(\frac{\gamma \beta}{c} \right)^2} = c^2.$$

$$\Rightarrow \frac{m l^2}{a} = \left(\frac{1}{c^2} \right) k a. \text{ This gives}$$

$$A = (k a) \left[\frac{1}{c^2} \left(\frac{\partial \phi}{\partial t} \right)^2 - \left(\frac{\partial \phi}{\partial x} \right)^2 \right] + \frac{m}{a} g l \cos \phi = (k a) g m v^2 \partial_t \phi \partial_x \phi + \frac{m}{a} g l \cos \phi$$

which is explicitly Lorentz invariant.

2. The point here is, that with $\hbar=c=1$ one has $[E_{\text{neg}}]=[m_{\text{ass}}]=1$
 $[L]=[\text{time}]=-1$. So we can get $[L]$ and then $[\phi]$ (from $L = \frac{1}{2} \partial_\mu \phi (\partial^\mu \phi) + \dots$).

(i) Clearly, $[E]=[Lag]=[H_{\text{amplin}}]=1$, $L = \int d^3x L$ and $[d_x^3] = -3$

$$\Rightarrow [L] = [L] - [d_x^3] = 1 - (-3) = 4$$

$$\text{Now } [\partial_\mu] = -[x^\mu] = 1 \text{ so } [\partial_\mu \phi \partial_\nu \phi] = 4 \Rightarrow 2[\phi] + 2[\partial_\mu \phi] = 4 \Rightarrow [\phi] = 1$$

$$L = \frac{1}{2} (\partial_\mu \phi)^2 + \frac{1}{2} [(\partial_\mu \phi)']^2 - \frac{m^2}{2} \phi^2 - g \phi^3 - \lambda \phi^4 - \sigma \phi^5$$

$$\text{so } [K] + 2[\partial_\mu \phi'] = [L] \Rightarrow [K] = -4$$

$$[m^2 \phi^2] = 4 \Rightarrow [m] = 1 \quad (\text{no surprise here})$$

$$[g \phi^3] = 4 \Rightarrow [g] = 1$$

$$[\lambda \phi^4] = 4 \Rightarrow [\lambda] = 0$$

$$[\sigma \phi^5] = 4 \Rightarrow [\sigma] = -2$$

$$(ii) [L] = 1 - [\int d^3x] = 3, 2[\phi] + 2[\partial_\mu \phi] = 3 \Rightarrow [\phi] = \frac{1}{2} \Rightarrow [K] = -3$$

$$[m] = 1 \quad (\text{in any number of dimensions, since } [(\partial_\mu \phi)'] = [m^2 \phi^2] \text{ and } [\partial_\mu] = 1)$$

$$[g] = 3 - 3[\phi] = \frac{3}{2}$$

$$[\lambda] = 1$$

$$[\sigma] = 0$$

$$(iii) [L] = 1 - [\int d^3x] = 6, [\phi] = \frac{6-2}{2} = 2, [m] = 1$$

$$[g] = 6 - 3[\phi] = 0$$

$$[\lambda] = 6 - 4[\phi] = -2$$

$$[\sigma] = 6 - 6[\phi] = -6$$

3. (ii) Since $\Lambda^\mu_\rho \Lambda^\nu_\sigma \eta^{\rho\sigma} = \eta^{\mu\nu}$

we have $(\delta^\mu_\rho + \omega^\mu_\rho)(\delta^\nu_\sigma + \omega^\nu_\sigma) \eta^{\rho\sigma} = \eta^{\mu\nu}$ to order ω

$$\Rightarrow \omega^\mu_\rho \delta^\nu_\sigma \eta^{\rho\sigma} + \omega^\nu_\sigma \delta^\mu_\rho \eta^{\rho\sigma} = 0$$

Using $\omega^{\mu\sigma} = \omega^\mu_\rho \eta^{\rho\sigma}$ this is

$$\omega^{\mu\nu} + \omega^{\nu\mu} = 0 \Rightarrow \omega^{\mu\nu} = -\omega^{\nu\mu} \Rightarrow \omega_{\mu\nu} = -\omega_{\nu\mu}$$

$$(iii) \text{ Exprd } X^\alpha_\mu X^\beta_\nu X^\gamma_\rho X^\delta_\sigma = -X^0_\mu X^1_\nu X^2_\rho X^3_\sigma + X^1_\mu X^0_\nu X^2_\rho X^3_\sigma + \dots$$

where the terms ... are permutations of 0123 upper indices, with (-1) for even permutations and (+1) for odd permutations. Note that

$$\epsilon_{0123} = -1 \quad \text{since } \epsilon_{0123} = \eta_{00} \eta_{11} \eta_{22} \eta_{33} \epsilon^{0123} = (+1)(-1)^3 (+1) = -1$$

Now, clearly the above vanishes if any two of the indices $\mu, \nu, \lambda, \sigma$ are equal. So, take $\mu=0, \nu=1, \lambda=2, \sigma=3$. Then

$$\text{Exprd } X^0_\mu X^1_\nu X^2_\lambda X^3_\sigma = -X^0_0 X^1_1 X^2_2 X^3_3 + \text{permutations}$$

is precisely $(-1) \times \det(X^\mu_\nu)$, by definition of determinant. So

$$\text{Exprd } X^0_\mu X^1_\nu X^2_\lambda X^3_\sigma = -\det(X)$$

Since $\mu, \nu, \lambda, \sigma$ have to be all different, and the result is completely antisymmetric under exchange of them, it is proportional to $\epsilon_{\mu\nu\rho\sigma}$. Hence

$$\text{Exprd } X^0_\mu X^1_\nu X^2_\lambda X^3_\sigma = \epsilon_{\mu\nu\rho\sigma} \det(X)$$

(iii) Let's do the finite transformations first: the infinitesimal ones will follow.

$$\delta_\nu^\mu \rightarrow \Lambda^\mu_\rho \Lambda_\nu^\sigma \delta_\sigma^\rho = \Lambda^\mu_\rho \Lambda_\nu^\rho = \delta_\nu^\mu$$

The last step follows from the eq. below (13) in my course notes:

Λ_ν^ρ is the inverse of Λ^μ_ρ .

Since for finite transformations $\delta_\nu^\mu \rightarrow \delta_\nu^\mu$, the same holds for infinitesimal ones.

$$\text{Now } \epsilon^{\mu\nu\lambda\sigma} \rightarrow \Lambda^\mu_\alpha \Lambda^\nu_\beta \Lambda^\lambda_\gamma \Lambda^\sigma_\delta \epsilon^{\alpha\beta\gamma\delta} = \epsilon^{\mu\nu\lambda\sigma} \det(\Lambda)$$

by the previous item in this problem. So $\epsilon^{\mu\nu\lambda\sigma} \rightarrow \pm \epsilon^{\mu\nu\lambda\sigma}$ with the sign given by whether $\Lambda \in O^+(1,3)$ or not.

An infinitesimal transformation is in $O^+(1,3)$, so $\epsilon^{\mu\nu\lambda\sigma} \rightarrow \epsilon^{\mu\nu\lambda\sigma}$ for infinitesimal transformations.

Note that for more general coordinate transformations, $\Lambda^\mu_\nu = \frac{\partial x^\mu}{\partial y^\nu}$

where x^μ, y^ν are not necessarily cartesian, so that $g^{\mu\nu} \rightarrow g^{\mu\nu}$ a metric with the same signature as $g^{\mu\nu}$ but with components not necessarily ± 1 's,

we still have $\delta^\mu_\nu \rightarrow \delta^\mu_\nu$, but not $\epsilon^{\mu\nu\lambda\sigma} \rightarrow \epsilon^{\mu\nu\lambda\sigma} \det(\Lambda)$ with $\det(\Lambda)$

non-trivial: $g^{\mu\nu} = \Lambda^\mu_\alpha \Lambda^\nu_\beta g^{\alpha\beta}$ connects cartesian to general coordinates and

$$(\det \Lambda)^2 = \det(g), \rightarrow \det(\Lambda) = \pm \sqrt{\det(g)}. \text{ So, up to sign, it is } \frac{\epsilon^{\mu\nu\lambda\sigma}}{\sqrt{\det(g)}} \text{ that is}$$

invariant.