

Establishing Relationships

Linear Least Squares Fitting

Lecture 6

Physics 2CL

Summer 2010

Outline

- Determining the relationship between measured values
- Physics for experiment # 3
 - Oscillations & resonance
- Overview of last set of three labs

Schedule

Meeting	Experiment
1 (Aug. 3 or 4)	none
2 (Aug. 5 or 6)	0
3 (Aug. 10 or 11)	1
4 (Aug. 12 or 13)	1
5 (Aug. 17 or 18)	2
6 (Aug. 19 or 20)	3
7 (Aug. 24 or 25)	4
8 (Aug. 26 or 27)	5
9 (Aug. 31 or Sept. 1)	6

Relationships

- So far, we've talked about measuring a single quantity
- Often experiments measure two variables, both varying simultaneously
- Want to know mathematical relationship between them
- Want to compare to models
- How to analyze quantitatively?

Principle of Maximum Likelihood

- Best estimates of X and σ from N measurements $(x_1 - x_N)$ are those for which $\text{Prob}_{X,\sigma}(x_i)$ is a maximum

The Principle of Maximum Likelihood

Recall the probability density for measurements of some quantity x (distributed as a Gaussian with mean X and standard deviation σ)

$$P_{X,\sigma}(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-X)^2}{2\sigma^2}}$$

Normal distribution is one example of $P(x)$.

Now, let's make repeated measurements of x to help reduce our errors.

$$x_1, x_2, x_3, \dots, x_n$$

We define the Likelihood as the product of the probabilities. The larger L , the more likely a set of measurements is.

$$L = P(x_1)P(x_2)P(x_3)\dots P(x_n)$$

Is L a Probability?

Why does $\max L$ give the best estimate?

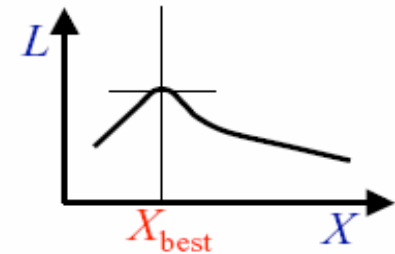
The best estimate for the parameters of $P(x)$ are those that maximize L .

Using the Principle of Maximum Likelihood:

Prove the mean is best estimate of X

Assume X is a parameter of $P(x)$.

When L is maximum, we must have: $\frac{\partial L}{\partial X} = 0$



Lets assume a Normal error distribution and find the formula for the best value for X .

$$L = P(x_1)P(x_2)...P(x_n) = \prod_{i=1}^n P(x_i)$$

$$L = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x_i - X)^2}{2\sigma^2}} = \frac{1}{(2\pi)^{\frac{n}{2}} \sigma^n} e^{-\sum_{i=1}^n \frac{(x_i - X)^2}{2\sigma^2}}$$

$$L = C e^{-\chi^2/2}$$

$$\chi^2 = \sum_{i=1}^n \frac{(x_i - X)^2}{\sigma^2} \quad \text{Definition}$$

$$\frac{\partial L}{\partial X} = 0 = C e^{-\chi^2/2} \frac{-1}{2} \frac{\partial \chi^2}{\partial X}$$

$$\Rightarrow \frac{\partial \chi^2}{\partial X} = 0 \quad \leftarrow$$

$$\frac{\partial \chi^2}{\partial X} = \frac{1}{\sigma^2} \sum_{i=1}^n 2(x_i - X) = 0$$

$$\sum_{i=1}^n (x_i - X) = 0$$

$$\sum_{i=1}^n x_i - nX = 0$$

$$X = \frac{1}{n} \sum_{i=1}^n x_i \quad \text{Q.E.D. the mean}$$

What is the Error on the Mean

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$

Formula for mean of measurements. (We just proved that this is the best estimate of the true x .)

Now, use propagation of errors to get the error on the mean.

$$\sigma_{\bar{x}} = \frac{\partial \bar{x}}{\partial x_1} \sigma_{x_1} \oplus \frac{\partial \bar{x}}{\partial x_2} \sigma_{x_2} \oplus \dots \oplus \frac{\partial \bar{x}}{\partial x_n} \sigma_{x_n}$$

$$\frac{\partial \bar{x}}{\partial x_i} = \frac{1}{n}$$

$$\sigma_{\bar{x}} = \sqrt{\sum_{i=1}^n \left(\frac{\sigma_{x_i}}{n} \right)^2} = \sqrt{n \left(\frac{\sigma}{n} \right)^2} = \frac{\sigma}{\sqrt{n}}$$

What would you do if the x_i had different errors?

We got the error on the mean (SDOM) by propagating errors.

Weighted averages (Chapter 7)

We can use maximum Likelihood (χ^2) to average measurements with different errors.

$$\chi^2 = \sum_{i=1}^n \left(\frac{x_i - X}{\sigma_i} \right)^2$$

We derived the result that:

$$X = \frac{\sum_{i=1}^n w_i x_i}{\sum_{i=1}^n w_i}$$

Using error propagation, we can determine the error on the weighted mean:

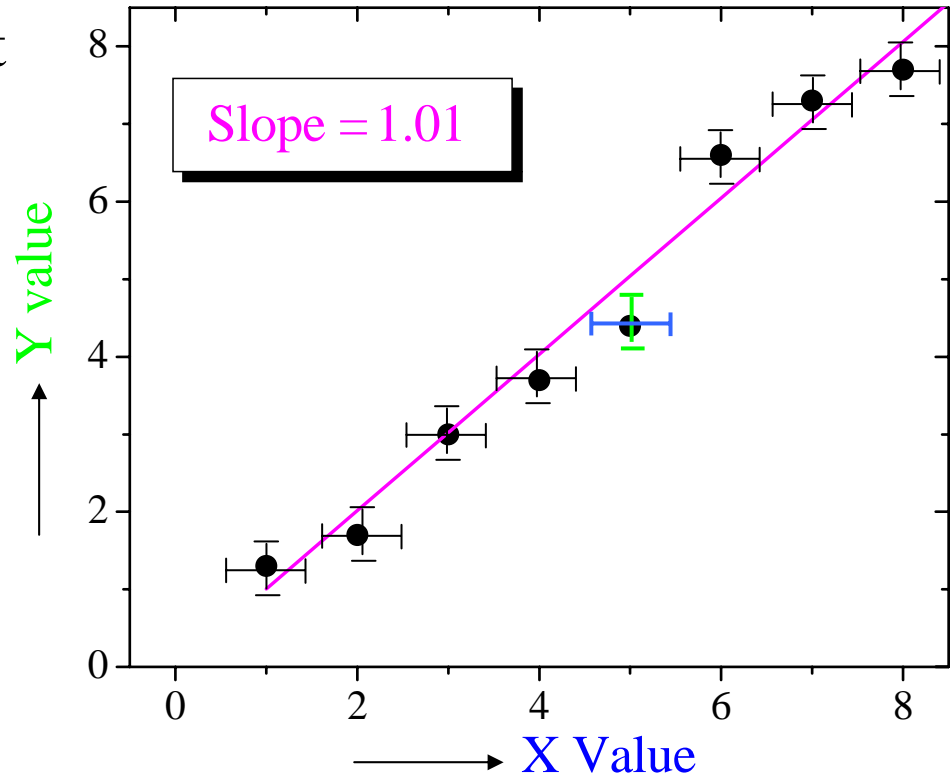
$$\sigma_x = \frac{1}{\sqrt{\sum_{i=1}^n w_i}}$$

What does this give in the limit where all errors are equal?

$$\begin{aligned} \frac{\partial \chi^2}{\partial X} &= 0 = -2 \sum_{i=1}^n \frac{x_i - X}{\sigma_i^2} \\ \sum_{i=1}^n \frac{x_i}{\sigma_i^2} - X \sum_{i=1}^n \frac{1}{\sigma_i^2} &= 0 \\ w_i &\equiv \frac{1}{\sigma_i^2} \\ \sum_{i=1}^n w_i x_i &= X \sum_{i=1}^n w_i \\ X &= \frac{\sum_{i=1}^n w_i x_i}{\sum_{i=1}^n w_i} \end{aligned}$$

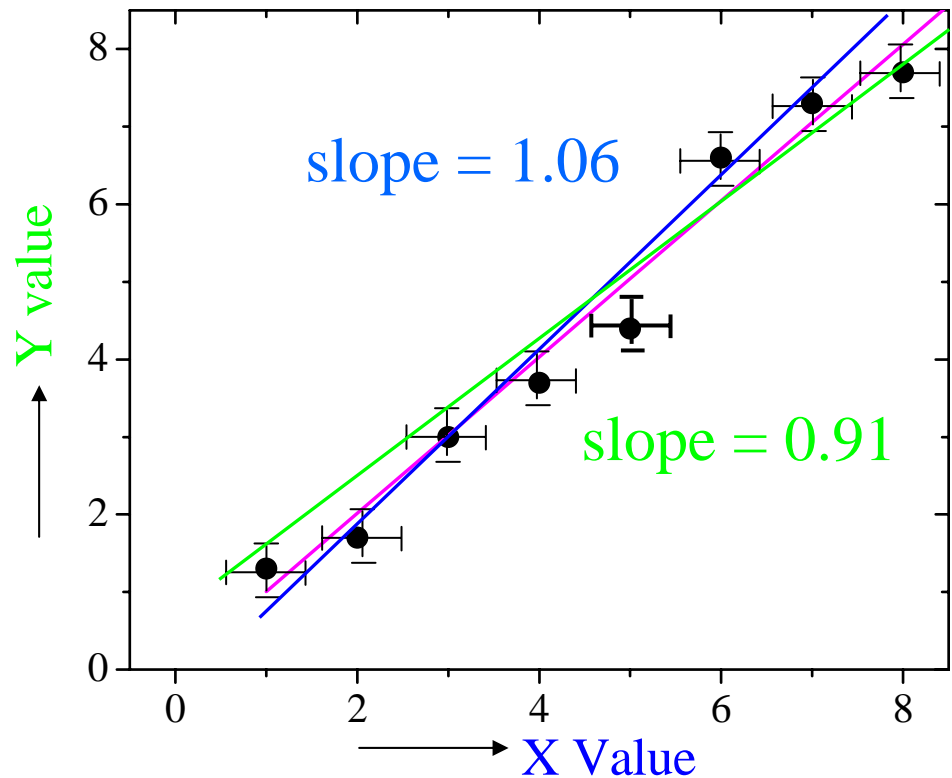
Linear Relationships: $y = A + Bx$

- Data would lie on a straight line, except for errors
- What is 'best' line through the points?
- What is uncertainty in constants?
- How well does the relationship describe the data?
- Velocity vs. time @ constant acceleration
- Ohms law



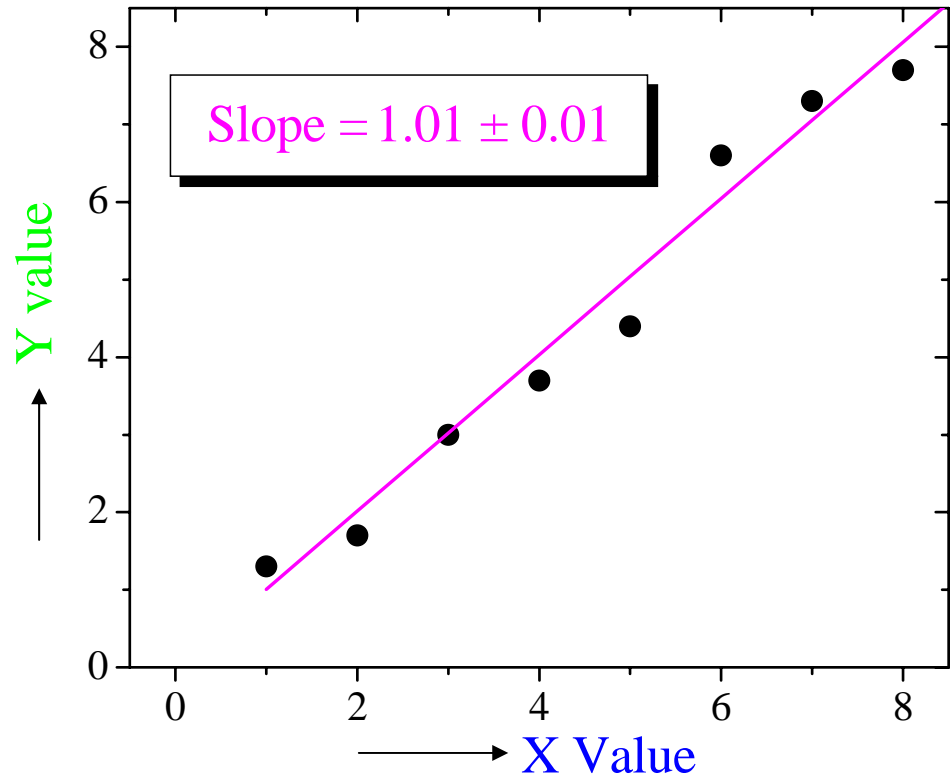
A Rough Cut

- Best means ‘line close to all points’
- Draw various lines that pass through data points
- Estimate error in constants from range of values
- Good fit if points within error bars of line
slope = 1.01 ± 0.07

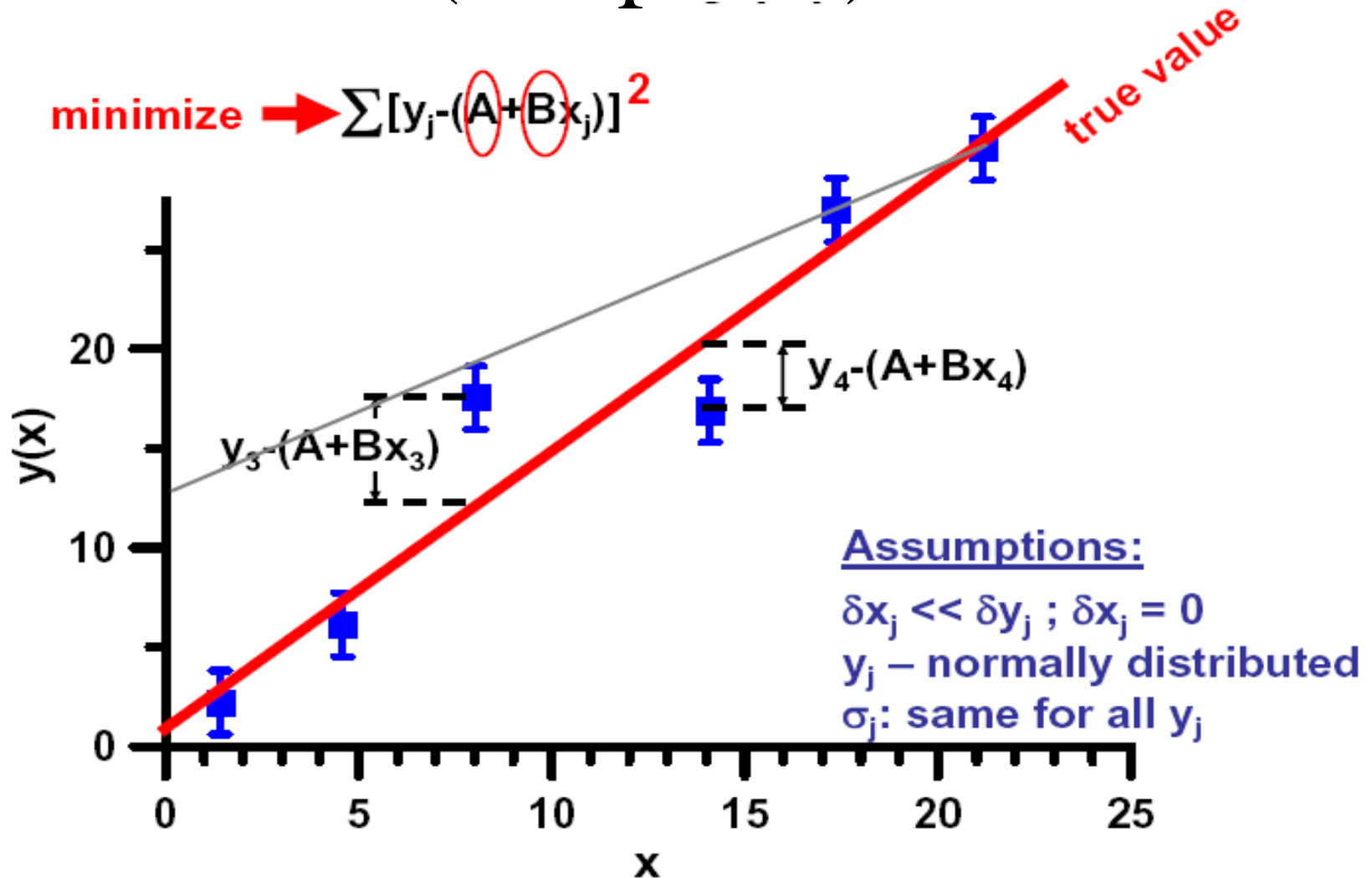


More Analytical

- Best means ‘minimize the square of the deviations between line and points’
- Can use error analysis to find constants, error

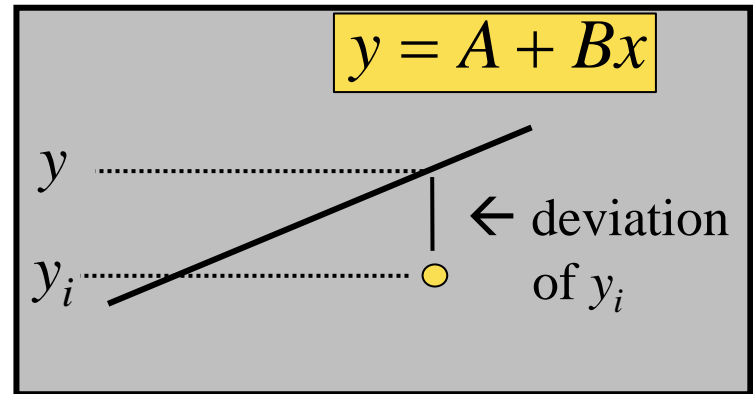


The Details of How to Do This (Chapter 8)



Finding the coefficients A and B

- Want to find A , B that minimize difference between data and line
- Since line above some data, below other, minimize sum of squares of deviations
- Find A , B that minimize this sum



$$y_i - y = y_i - A - Bx_i$$

$$\sum_{i=1}^N (y_i - A - Bx_i)^2$$

$$\frac{\partial}{\partial A} = \sum y_i - AN - B \sum x_i = 0$$

$$\frac{\partial}{\partial B} = \sum x_i y_i - A \sum x_i + B \sum x_i^2 = 0$$

Finding A and B

- After minimization, solve equations for A and B
- Looks nasty, not so bad...
- See Taylor, example 8.1

$$\begin{aligned}\frac{\partial}{\partial A} &= \sum y_i - AN - B \sum x_i = 0 \\ \frac{\partial}{\partial B} &= \sum x_i y_i - A \sum x_i + B \sum x_i^2 = 0\end{aligned}$$

$$\begin{aligned}A &= \frac{\sum x_i^2 \sum y_i - \sum x_i \sum x_i y_i}{\Delta} \\ B &= \frac{N \sum x_i y_i - \sum x_i \sum y_i}{\Delta} \\ \Delta &= N \sum x_i^2 - \left(\sum x_i \right)^2\end{aligned}$$

Uncertainty in Measurements of y

- Before, measure several times and take standard deviation as error in y
- Can't now, since y_i 's are different quantities
- Instead, find standard deviation of deviations

$$\sigma_x = \sqrt{\frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{x})^2}$$

$$\sigma_y = \sqrt{\frac{1}{N-2} \sum_{i=1}^N (y_i - A - Bx_i)^2}$$

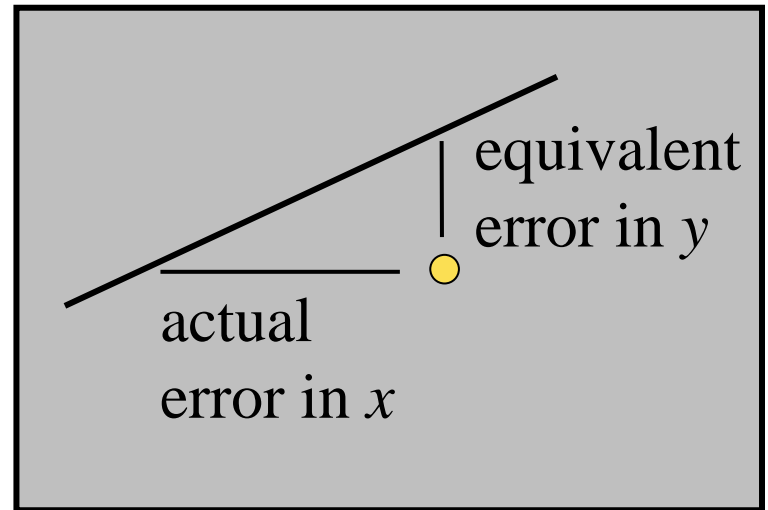
Uncertainty in A and B

- A, B are calculated from x_i, y_i
- Know error in x_i, y_i ; use error propagation to find error in A, B
- A distant extrapolation will be subject to large uncertainty

$$\sigma_A = \sigma_y \sqrt{\frac{\sum x_i^2}{\Delta}}$$
$$\sigma_B = \sigma_y \sqrt{\frac{N}{\Delta}}$$
$$\Delta = N \sum x_i^2 - \left(\sum x_i \right)^2$$

Uncertainty in x

- So far, assumed negligible uncertainty in x
- If uncertainty in x , not y , just switch them
- If uncertainty in both, convert error in x to error in y , then add errors



$$\Delta y = B \Delta x$$

$$\sigma_y(\text{equiv}) = B \sigma_x$$

$$\sigma_y(\text{equiv}) = \sqrt{\sigma_y^2 + (B \sigma_x)^2}$$

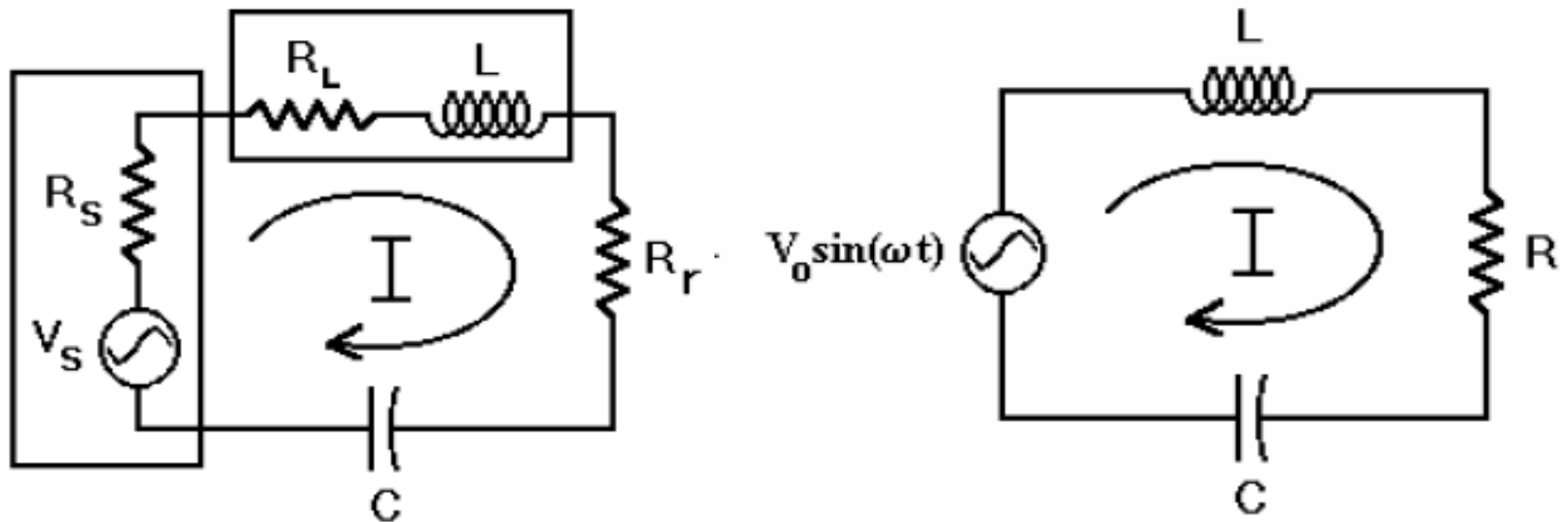
Other Functions

$$y = Ae^{Bx}$$

- Convert to linear
- Can now use least squares fitting to get $\ln A$ and B

$$y = Ae^{Bx}$$
$$\ln y = \ln A + Bx$$

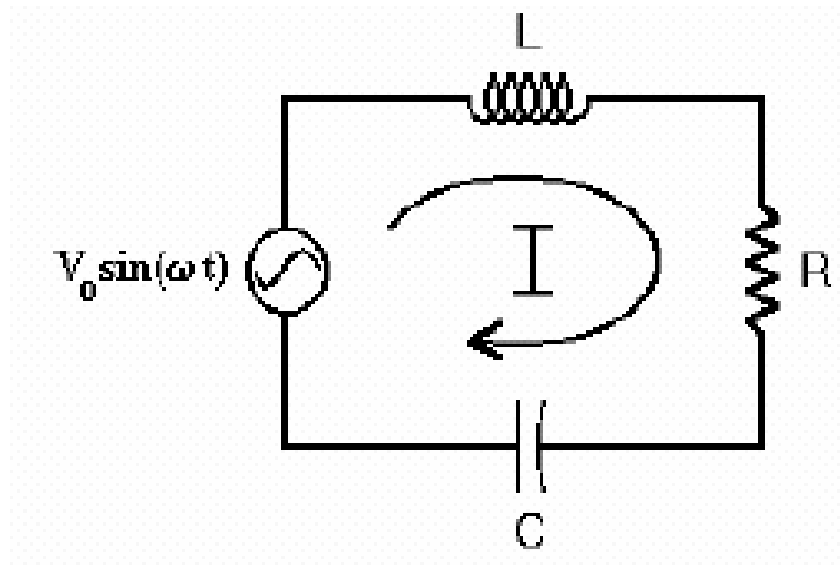
Lab 3 Resonance – Sinusoidal Response



Complete circuit

Model circuit

Lab 3 Resonance



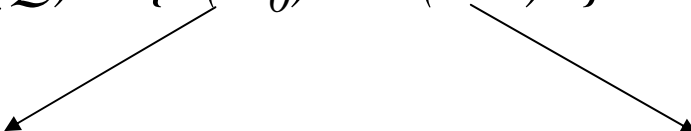
$$V_r = R_r I = V_0 \frac{R_r}{R} \frac{e^{i(\omega t + \phi)}}{\sqrt{1 + Q^2 \left[\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right]^2}}$$

$$Q = \frac{\omega_0}{\omega_2 - \omega_1}$$

Uncertainty in Q

$$Q = \omega_0 / (\omega_2 - \omega_1)$$

$$Q = \omega_0 / (\Delta\omega) \quad \text{where } \Delta\omega = \omega_2 - \omega_1$$

$$\varepsilon(Q) = \{ \varepsilon(\omega_0)^2 + \varepsilon(\Delta\omega)^2 \}^{1/2}$$


$$\varepsilon(\omega_0) = \delta(\omega_0) / \omega_0$$

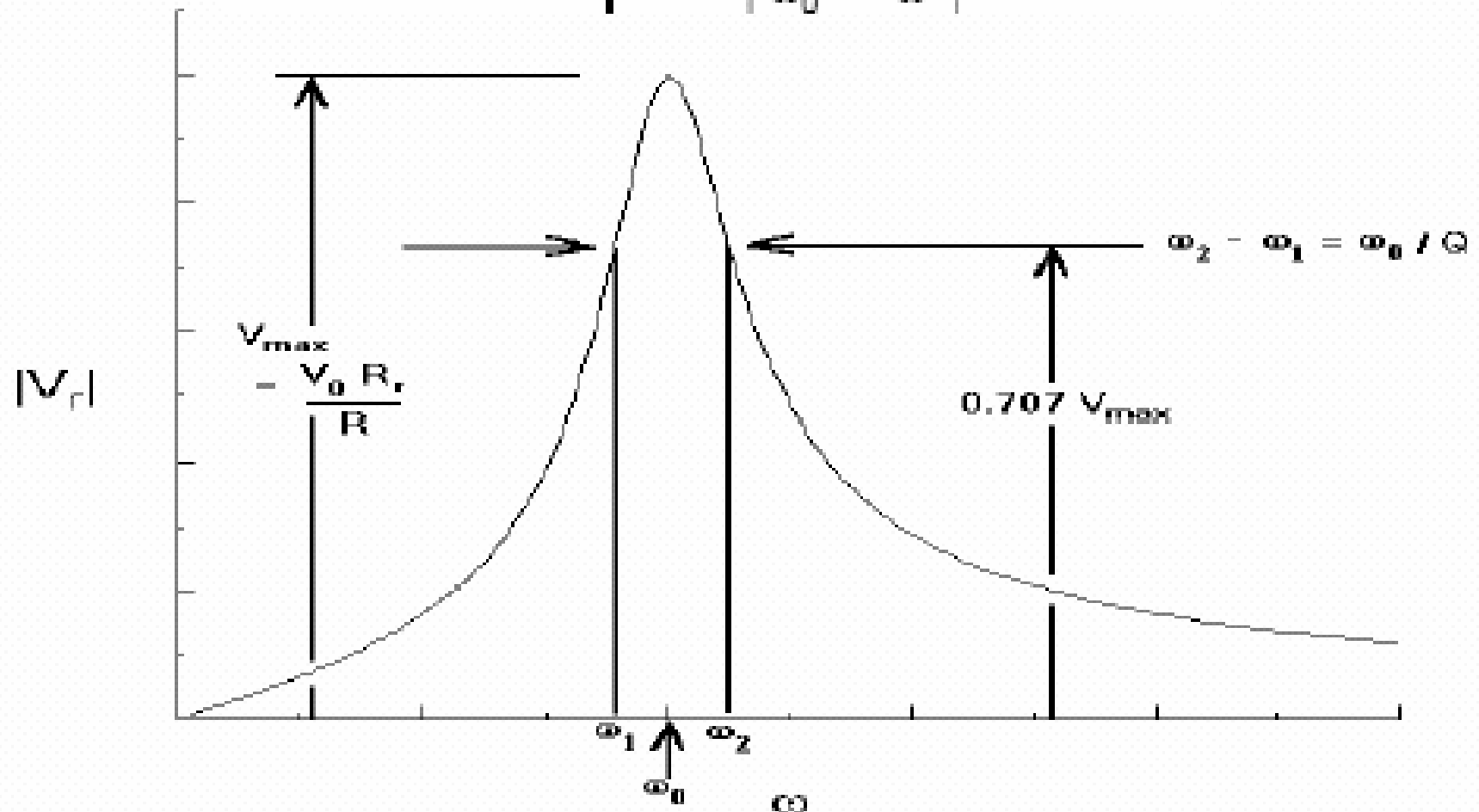
$$\varepsilon(\Delta\omega) = \delta(\Delta\omega) / \Delta\omega$$

$$\varepsilon(\omega_2 - \omega_1) = \delta(\omega_2 - \omega_1) / (\omega_2 - \omega_1)$$

$$\delta(\omega_2 - \omega_1) = \{ \delta(\omega_2)^2 + \delta(\omega_1)^2 \}^{1/2}$$

Voltage Response

$$|V_r| = \frac{V_0 R_r}{R} \frac{1}{\sqrt{1 + Q^2 \left[\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right]^2}}$$



Origin and Voltage Response

Derived Equation

$$|V_R| = |I||Z_R| = V_0 \frac{|Z_R|}{|Z_{Total}|}$$

$$= \frac{V_0 R_R}{R \sqrt{1 + Q^2 \left(\frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right)^2}}$$

Origin fit Equation

$$y = \frac{A}{\sqrt{1 + B^2 \left(\frac{x}{C} - \frac{C}{x} \right)^2}}$$

$y =$

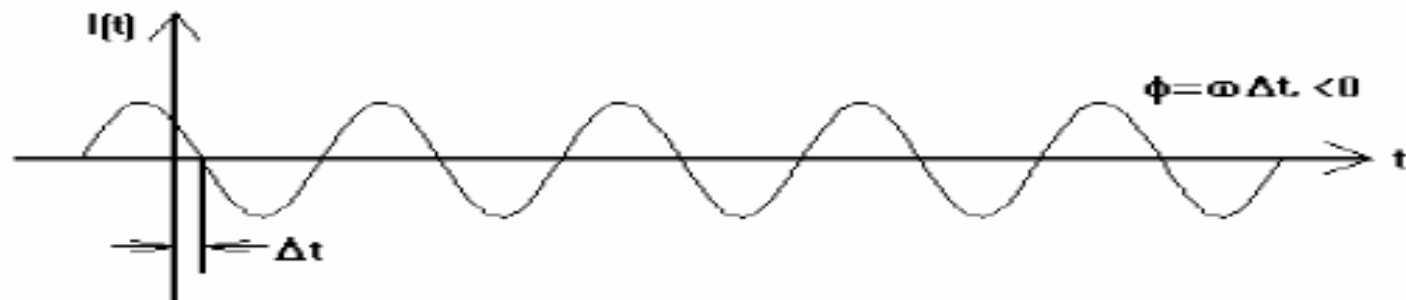
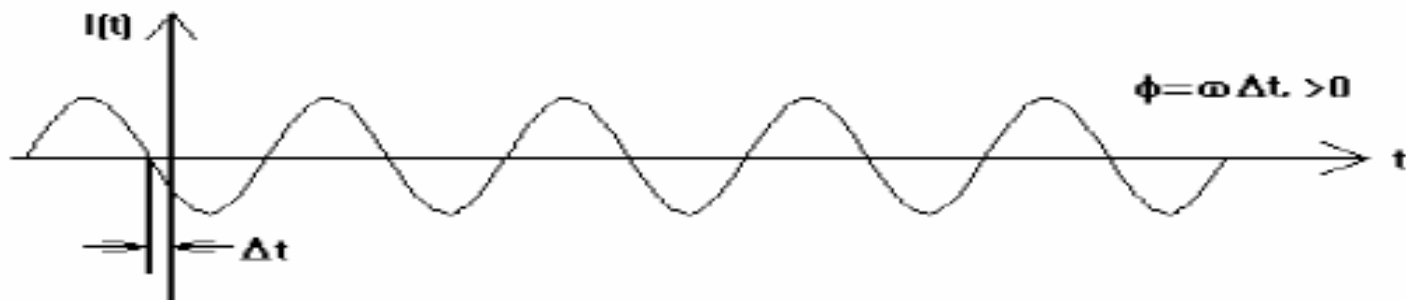
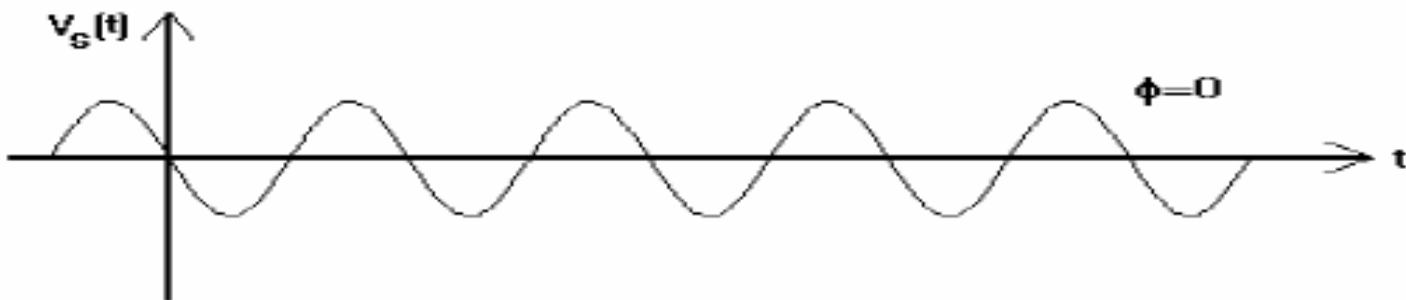
$x =$

$A =$

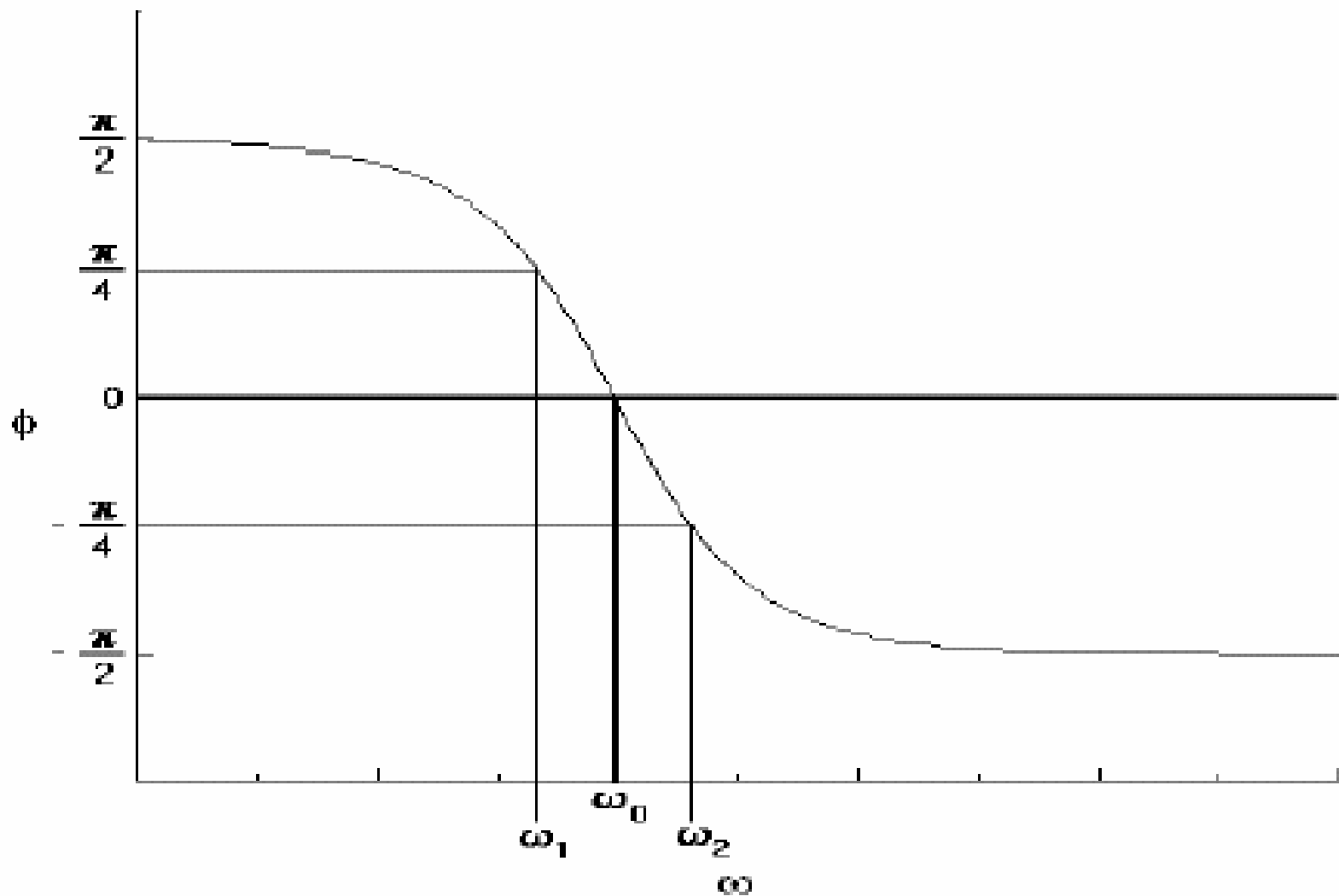
$B =$

$C =$

Phase Shifts



Phase Response



Q-Multiplier

$$\frac{V_{C0}}{V_0} = Q$$

Maximum voltage across capacitor is Q
times driving voltage V_0

Outline Lab # 3

- 1). Preliminary calculations of ω_0 and Q
- 2). Measure ω_0 and Q
- 3). Graph Frequency Response
- 4). Measure Phase Shifts
- 5). Q -Multiplier
- 6). Phase of V_C
- 7). Dependence of Q on R

Last set of labs

- Topics include:
 - Exp. 4: Microwaves: refraction & interference
 - Exp. 5: Laser: interference, diffraction
 - Exp. 6: Human eye: lens equation, lens in series

Exp. 4 –Microwave refraction and interference

- Measure index of refraction (n) for wax
- Make use of refraction and reflection
- Interference theory

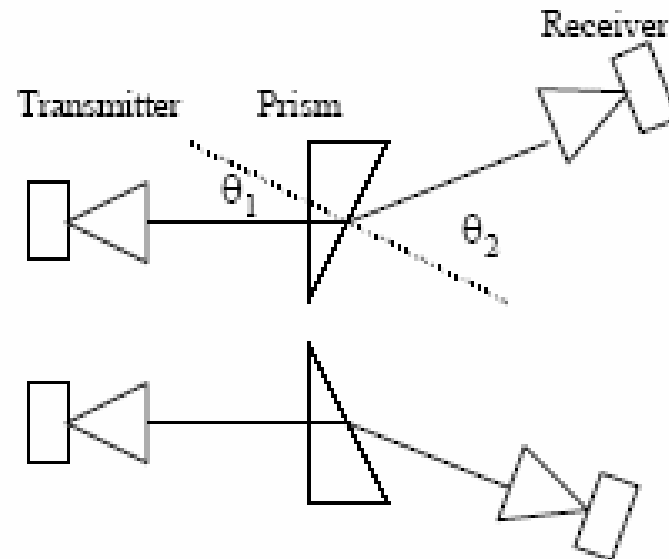


Figure 6. Setup for Part E.

Exp. 5 – Laser diffraction & interference

- Use light from visible range
- λ is relatively small so objects are similarly small
- Interference phenomena
- Lithography
- Basic ideas for X-ray diffraction

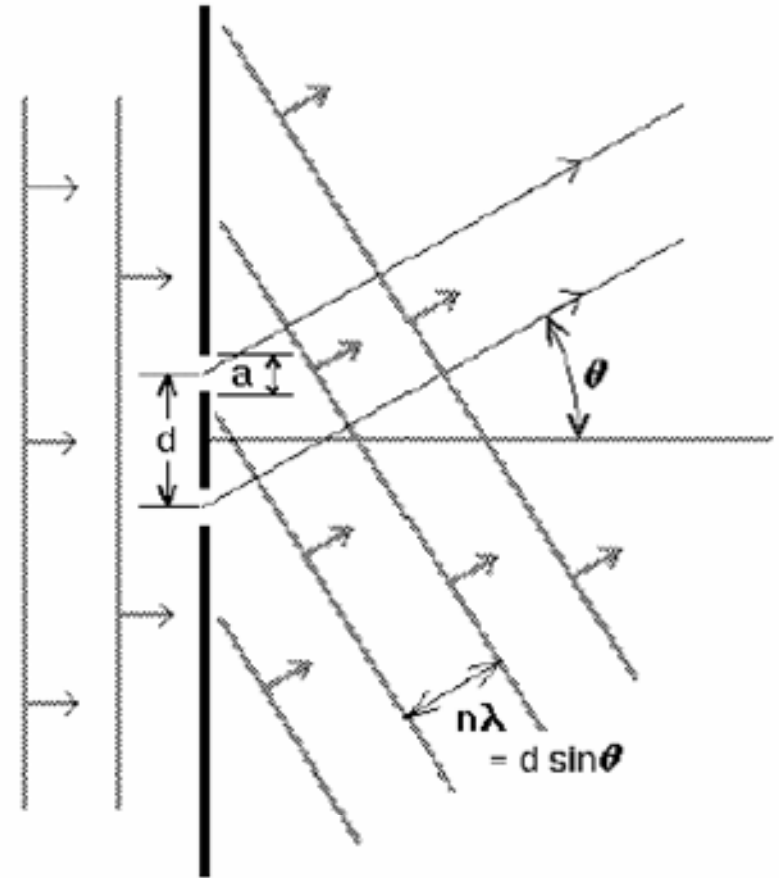
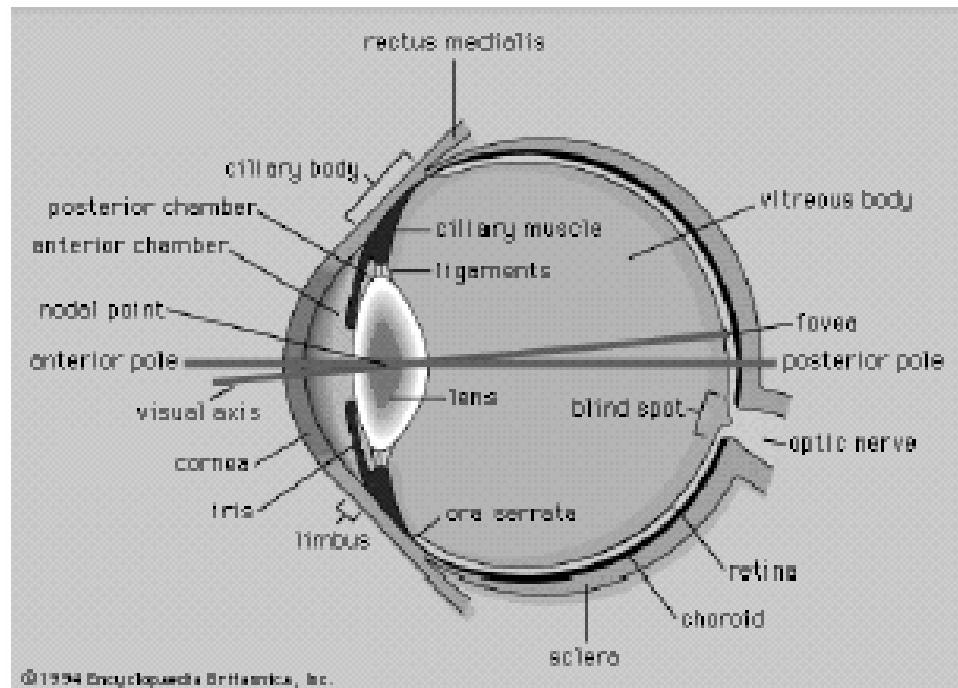


Figure 6 The two-slit interference geometry.

Exp. 6 – Lenses & Human Eye

- Model for lens of the human eye
- Thin lens equation
- Combination of lenses
- Detection of blind spot
- microscopy



Remember

- Lab Writeup
- CAPE evaluations
- Sign-up sheet for last set of labs
- Read next week's lab descriptions, do prelab
- Homework 6 (Taylor 8.1, 8.6, 8.10)