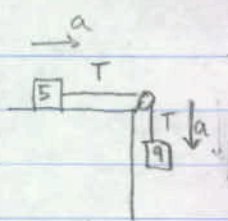
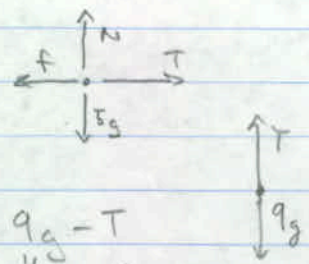


Quiz #3 Version A Solutions

#1



Force Diagram:

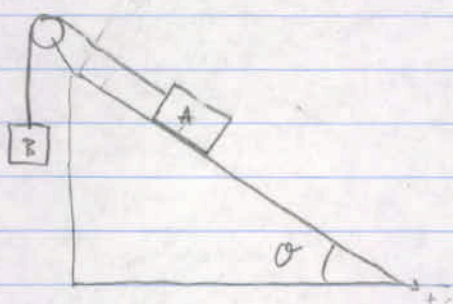


-Accelerations are equal: $5a = T - f$; $9a = 9g - T$
 w/ $f = \mu_k N$ w/ $N = 5g$. Then eliminating "a" +
 solving for "T" we get: $a = \frac{T - f}{5}$

$$9a = \frac{9}{5}(T - f) = 9g - T = \frac{9}{5}T - \frac{9}{5}f; T(\frac{9}{5} + 1) = 9g + \frac{9}{5}f;$$

$$T = \frac{9g + \frac{9}{5}f}{\frac{9}{5} + 1} = \frac{88.2 + 17.64}{2.8} = \boxed{37.8 \text{ N}}$$

#2

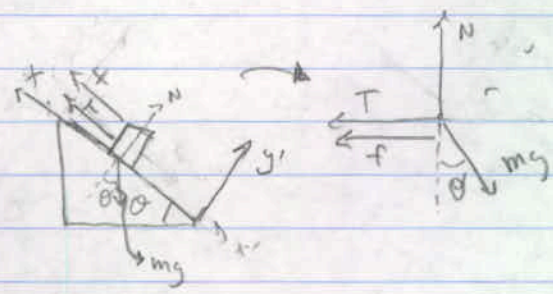


Since it is not moving, we can use two different set of coordinates to determine the net force along the direction of the applied tension.

For mass A:

$$F_x = T + f - m_A g \sin(\theta)$$

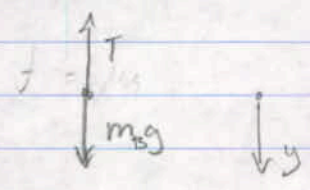
$$F_y = 0 = N - m_A g \cos(\theta).$$



For mass B:

$$F_y = m_B g - T = 0.$$

$$T = m_B g$$



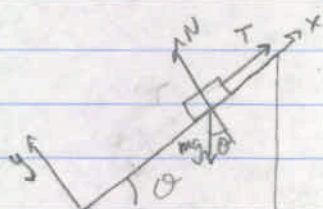
#2-cont. $T = m_A g \sin(\theta) - f = m_B g \Rightarrow f = m_A g \sin(\theta) - m_B g$

Thus, $|f| = |20 \sin(36.9^\circ) - 20| \text{ N} = \boxed{8 \text{ N} = f}$

#3 $W = \Delta KE = KE_f - KE_i = \frac{1}{2} m (v_f^2 - v_i^2)$; then,

$W = \frac{1}{2} (5) (100 - 36) = \boxed{160 \text{ J} = W}$

#4



$P_{\text{motor}} = \vec{T} \cdot \vec{v} = T v$ when

T is the applied tension by the motor. Since we are at constant speed:

$F_x = 0 = T - mg \sin(\theta); T = mg \sin(\theta).$

$P_{\text{motor}} = mg \sin(\theta) \cdot v = \boxed{686 \text{ W}}$

#5

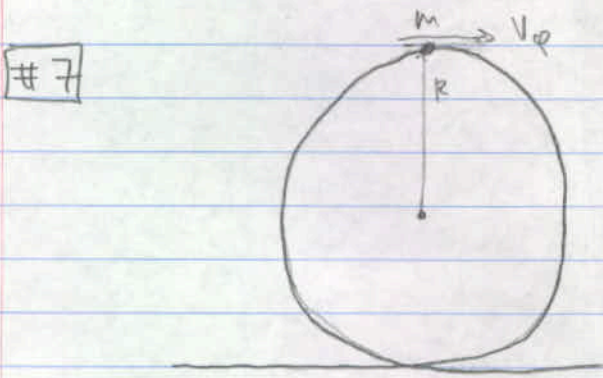
Friction a constant force opposing the motion, thus, $W_{\text{fric}} = -f \Delta x = \Delta KE$ (equals change in KE).

Then, $-f \Delta x = \frac{1}{2} m (v_f^2 - v_i^2) = -\frac{1}{2} m v_i^2 \Rightarrow \Delta x = \frac{\frac{1}{2} m v_i^2}{f}$

$\Delta x = \frac{\frac{1}{2} m v_i^2}{\mu m g} = \frac{\frac{1}{2} v_i^2}{\mu g} = \frac{\frac{1}{2} (2)^2}{(\frac{1}{10})(9.8)} = \frac{2}{0.98} = \boxed{2 \text{ m}}$

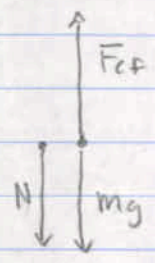
#6
$$W = \int_{x_1}^{x_2} \vec{F} \cdot d\vec{x} = \int_1^4 (8x - 16) dx = \left. \frac{8x^2}{2} - 16x \right|_1^4 =$$

$$= W = 4 \cdot (16 - 1) - 16 \cdot (4 - 1) = 4 \cdot 15 - 16 \cdot 3 = \boxed{12 \text{ J} = W}$$



At the top and in to reference frame of the track, there are three total forces: \vec{N} (by the track), $m\vec{g}$ (gravity), & $\frac{mv^2}{r}$ (centrifugal)

Force Diagram:
In the radial direction:



$$F_r = 0 = \frac{mv^2}{R} - N - mg.$$

Solving for N:
$$N = \frac{mv^2}{R} - mg = 27,000 - 19,600 = \boxed{7400 \text{ N}}$$

#8

$KE_1 = \frac{1}{2} MV^2$ & we are given:

$$M_2 = M/2 \quad \& \quad V_2 = 2V. \quad KE_2 = \frac{1}{2} (M/2) (2V)^2 = \frac{1}{2} \cdot \frac{1}{2} M 4V^2 =$$

$$= \left(\frac{1}{2} MV^2 \right) \cdot 2 = \boxed{2KE = KE_2}$$