*Closed book. No work needs to be shown for multiple-choice questions.*

**1**. Lonnie pitches a baseball of mass 0.20 kg. The ball arrives at home plate with a speed of 40 m/s and is batted straight back to Lonnie with a return speed of 60 m/s. If the bat is in contact with the ball for 0.050 s, what is the magnitude of the impulse experienced by the ball?

a. 360 N⋅s. b.  $20 N·s$ . c.  $400 N·s$ . d.  $9.0 N·s.$ e. 240 N⋅s.

- **2**. A ball with a mass of 0.25 kg moving at +5.0 m/s makes a head-on collision with a second ball of mass 0.50 kg that is initially at rest. We define the direction of motion of the first ball as the positive x-direction. If the collision is elastic, what is the velocity of the first ball after the collision?
	- $a. -1.7$  m/s.  $b. -2.2$  m/s.  $c. -3.8$  m/s. d.  $2.5 \text{ m/s}$ . e. 3.8 m/s.
- **3**. Blocks A and B are moving toward each other. Block A has a mass of 2.0 kg and a velocity of 50 m/s, while block B has a mass of 4.0 kg and a velocity of –25 m/s. The blocks stick together after the collision. The kinetic energy lost during the collision is:
	- a. 0. b. 1250 J. c. 3750 J. d. 5000 J. e. 5600 J.
- **4**. Consider two vehicles approaching a right angle intersection and colliding. After the collision, they become entangled. Initially, car A has a mass of *M* and a velocity of (14.0 m/s) in the positive *x*-direction. Initially, car B has a mass of 3*M* and a velocity of (13.0 m/s) in the positive *y*-direction. What is the direction of the final velocity of the wreck with respect to the +*x* axis?
	- a.  $19.7^{\circ}$ . b.  $21.0^{\circ}$ .
	- c.  $47.1^{\circ}$ .
	- d.  $69.0^{\circ}$ .
	- e.  $70.3^{\circ}$ .
- **5**. A 20-N crate starting at rest slides down a rough 5.0-m long ramp, inclined at 25° with the horizontal. 20 J of energy is lost to friction. What will be the speed of the crate at the bottom of the incline?
	- a. 7.8 m/s. b. 1.9 m/s. c. 5.5 m/s. d. 4.7 m/s. e. 6.4 m/s.



- **6**. A particle experiences a force given by  $F = \alpha \beta x^3$  in the x direction. Find the potential energy the particle is in. (Assume that the zero potential energy is located at  $x = 0$ .)
	- a.  $\Delta U(x) = 3\beta x^2$ . b.  $\Delta U(x) = -\alpha x + \frac{\beta}{4} x^4$ . 4 c.  $\Delta U(x) = \alpha x - \frac{\beta}{4}$ 4  $x^4$ . d.  $\Delta U(x) = -3\beta x^2$ . e.  $\Delta U(x) = -6\beta x$ .
- € **7**. A satellite of the Earth has a mass of 200 kg and is at an altitude equal to the radius of the Earth. What is the potential energy of the satellite-Earth system?
	- a.  $-6.27 \times 10^9$  J. b.  $-1.12 \times 10^9$  J. c.  $-3.14 \times 10^9$  J. d.  $-2.34 \times 10^{10}$  J. e.  $-1.25 \times 10^{10}$  J.
- 8. A 45 kg box is pushed 17.4 m up a frictionless plane at an angle of 37° above the horizontal. −<br>. 1 Calculate its increase in potential energy.
	- a. 560 J. b. 2900 J. c. 3100 J. d. 4600 J. e. 1120 J.

Equations and constants:

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\begin{aligned}\n\begin{Bmatrix}\nx = r\cos\theta \\
y = r\sin\theta\n\end{Bmatrix}; \quad & \begin{Bmatrix}\nr = \sqrt{x^2 + y^2} \\
y = r\sin\theta\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial x} = \frac{1}{2}(v_{ox} + v_x)t \\
y = r\sin\theta\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial y} = \tan^{-1}\left(\frac{y}{x}\right) \\
\frac{y}{x}\right); \\
\begin{Bmatrix}\n\frac{\partial}{\partial x} = \frac{1}{2}(v_{ox} + v_x)t \\
v_x^2 = (v_{ox})^2 + 2a_x\Delta x\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial y} = v_{ox}t + \frac{1}{2}a_xt^2 \\
v_y^2 = (v_{ox})^2 + 2a_x\Delta y\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial y} = v_{ox}t + \frac{1}{2}a_xt^2 \\
v_y^2 = (v_{ox})^2 + 2a_x\Delta y\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial y} = \frac{\Delta v}{\Delta t} \\
v_{avg} = \frac{\Delta x}{\Delta t}\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial x} = \frac{\Delta v}{\Delta t} \\
v = \lim_{\Delta x \to 0} \frac{\Delta x}{\Delta t} \\
\frac{\partial}{\partial x} = mg\n\end{Bmatrix}; \\
\begin{Bmatrix}\n\frac{\partial}{\partial y} = \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\
\frac{\partial}{\partial y} = -\frac{\partial}{\partial y} & \frac{\partial}{\partial z}\n\end{Bmatrix}; \\
P_{\text{E}_{\text{gwhig}}} = \frac{\Delta x}{2}k(\Delta x)^2; \quad W = \left|\vec{F}\right|\Delta \vec{x}|\cos\theta; \quad W_{\text{net}} = W_1 + W_2 + W_3...; \quad W_{\text{ne}} = \Delta E_{\text{mec}}; \\
E_{\text{mec}} = KE + PE_{\text{grav}} + PE_{\text{symms}}; \\
\vec{p} = m\vec{v}; \quad \vec{I} = \vec{F}\Delta t = \Delta \vec{p} = m(\vec{v}_f - \vec{v}_i); \quad v_{1i} - v_{2i} = -(\nu_{1f} - \nu_{2f}); \quad \vec{
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