

→ Magnetic Helicity

- another conserved quantity in ideal MHD is magnetic helicity K

$$K = \int_V d^3x \underline{A} \cdot \underline{B}$$

V is taken to be the volume of a 'flux tube'.

- what, yet another invariant! Π

→ K is different \Rightarrow has topological interpretation

$$K = \int_V d^3x \underline{A} \cdot \underline{\nabla} \times \underline{A}$$

→ $\underline{x} \rightarrow -\underline{x}$ flips sign of K

→ K is a pseudo-scalar
 "has orientation or 'handedness' ..."

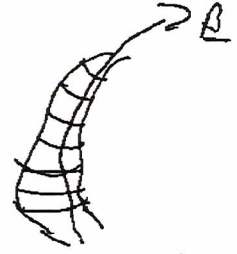
Proceed via:

- show K conservation
- discuss interpretation of K
- comment on utility \Rightarrow Taylor Relaxation

N.B.: Important $\Rightarrow K$ is gauge invariant

i.e. if $\underline{A} \rightarrow \underline{A} + \underline{\nabla}\chi$

$$\begin{aligned}
 K &\rightarrow K + \int_V d^3x \underline{\nabla} \underline{x} \cdot \underline{B} \\
 &= K + \int_V d^3x \underline{\nabla} \cdot (\underline{B} \underline{x}) \\
 &= 0, \text{ to surface term. } \left\{ \begin{array}{l} \underline{B} \cdot \underline{\hat{n}} = 0 \text{ on surface of} \\ \text{tube} \end{array} \right.
 \end{aligned}$$



Now, consider a blob of MHD fluid in motion



can show $\frac{dK}{dt} =$

$$\underline{E} + \frac{\underline{v} \times \underline{B}}{c} = \eta \underline{J}$$

$$\underline{E} = -\frac{1}{c} \frac{\partial A}{\partial t} - \underline{\nabla} \phi$$

\Rightarrow

$$\frac{\partial \underline{A}}{\partial t} = \underline{v} \times \underline{\nabla} \times \underline{A} - c \underline{\nabla} \phi - c \eta \underline{J}$$

$$\frac{\partial \underline{B}}{\partial t} = -\underline{v} \cdot \underline{\nabla} \underline{B} + \underline{B} \cdot \underline{\nabla} \underline{v} - \underline{B} \underline{\nabla} \cdot \underline{v} + \eta \underline{\nabla}^2 \underline{B}$$

$$\frac{dK}{dt} = \frac{d}{dt} \int_V d^3x (\underline{A} \cdot \underline{B})$$

$$= \int_V d^3x \left(\frac{d\underline{A}}{dt} \cdot \underline{B} + \underline{A} \cdot \frac{d\underline{B}}{dt} \right) + \int_V \underline{A} \cdot \underline{B} \frac{d}{dt} d^3x$$

$$\frac{dK}{dt} = \int d^3x \left(\frac{\partial \underline{A}}{\partial t} \cdot \underline{B} + (\underline{V} \cdot \nabla \underline{A}) \cdot \underline{B} + \underline{A} \cdot \frac{\partial \underline{B}}{\partial t} + \underline{A} \cdot (\underline{V} \cdot \nabla \underline{B}) + \underline{A} \cdot \underline{B} \nabla \cdot \underline{V} \right)$$

where $\frac{d}{dt} d^3x = \nabla \cdot \underline{V}$

i.e. $\frac{d}{dt} dV = \frac{d}{dt} d\underline{V} \cdot d\underline{l} + d\underline{V} \cdot \frac{d}{dt} d\underline{l}$
 $= -d\underline{l} \cdot \nabla \underline{V} \cdot d\underline{V} + (\nabla \cdot \underline{V})(d\underline{V} \cdot d\underline{l}) + d\underline{l} \cdot \nabla \underline{V} \cdot d\underline{V}$

$= \nabla \cdot \underline{V} d^3x$ s.t. and $\underline{B} \cdot \underline{n}$ on surface of tube.

$$\frac{dK}{dt} = \int d^3x \left[(\underline{B} \cdot \underline{V} \times \underline{B} - c \underline{B} \cdot \nabla \phi - c \underline{M} \cdot \underline{J} \cdot \underline{B}) \right]$$

$$+ \underline{A} \cdot \left(\nabla \times (\underline{V} \times \underline{B}) + \nabla \cdot ((\underline{A} \cdot \underline{B}) \underline{V}) + \underline{A} \cdot \nabla \nabla^2 \underline{B} \right)$$

where $\underline{A} \cdot (\underline{V} \cdot \nabla \underline{B}) + \underline{B} \cdot (\underline{V} \cdot \nabla \underline{A}) + \underline{A} \cdot \underline{B} \nabla \cdot \underline{V} = \nabla \cdot (\underline{V} \underline{A} \cdot \underline{B})$

$$\frac{dK}{dt} = \int d^3x \left[\nabla \cdot ((\underline{A} \cdot \underline{B}) \underline{V}) + \nabla \cdot ((\underline{V} \times \underline{B}) \times \underline{A}) + (\underline{V} \times \underline{B}) \cdot (\nabla \times \underline{A}) \right]$$

$$- c \underline{M} \cdot \underline{B} - \nabla \cdot (\underline{A} \cdot \nabla \times \underline{J}) c$$

$$\Rightarrow \frac{dK}{dt} = \int d^3x \left\{ \underline{v} \cdot \left[(\underline{A} \cdot \underline{B}) \underline{v} + (\underline{v} \times \underline{B}) \times \underline{A} + c\mu (\underline{A} \times \underline{J}) \right] - c\mu \underline{J} \cdot \underline{B} - c\mu \underline{J} \cdot \underline{B} \right\}$$

$$= \int dS \cdot \left[(\underline{A} \cdot \underline{B}) \underline{v} + (\underline{v} \times \underline{B}) \times \underline{A} + c\mu \underline{A} \times \underline{J} \right]$$

$$- 2 \int d^3x \left[c\mu \underline{J} \cdot \underline{B} \right]$$

$$= \int dS \cdot \left[\cancel{(\underline{A} \cdot \underline{B}) \underline{v}} - \cancel{(\underline{A} \cdot \underline{B}) \underline{v}} + (\underline{A} \cdot \underline{v}) \underline{B} \right] - c\mu \int dS \cdot \underline{J} \times \underline{A}$$

$$- 2c\mu \int d^3x (\underline{J} \cdot \underline{B}) \quad \underline{B} \cdot \underline{n} = c, \text{ on tube}$$

$$= - \int c\mu dS \cdot \left[\underline{v} \cdot \underline{B} \cdot \underline{A} - \underline{A} \cdot \underline{v} \cdot \underline{B} \right] - 2c\mu \int d^3x \underline{J} \cdot \underline{B}$$

$$= - 2c\mu \int d^3x (\underline{J} \cdot \underline{B})$$

\Rightarrow have shown:

$$\boxed{\frac{dK}{dt} = - 2c\mu \int d^3x (\underline{J} \cdot \underline{B})}$$

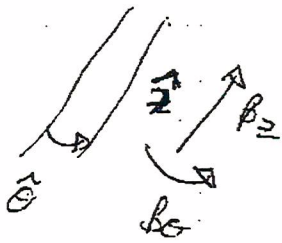
and clearly! $\frac{dK}{dt} \rightarrow 0$ as $\eta \rightarrow 0$
(non-singular \underline{J})

Magnetic Helicity is conserved in ideal MHD.

→ Magnetic Helicity conserved, but what does it mean?

- helicity is non-trivial \Rightarrow more than just helical field lines.

interesting to note: $g(r) = \frac{r B_z}{R B_0(r)} = \frac{1}{R u(r)}$



$u(r) = \frac{B_0(r)}{r B_z} \rightarrow$ Field line pitch.

(length scale at which winding varies)

cylindrical plasma $\Rightarrow \underline{B} = \underline{B}(r)$

$$\text{Now, } A_\theta = \frac{1}{r} \int_0^r r' B_z dr'$$

$$A_z = - \int_0^r B_\theta dr'$$

$$\begin{aligned} \underline{\text{so}} \quad \underline{A} \cdot \underline{B} &= B_z \int_0^r B_z dr - B_z \int_0^r B_\theta dr \\ &= \mu B_z \int_0^r \frac{B_\theta}{\mu} dr - B_z \int_0^r B_\theta dr \end{aligned}$$

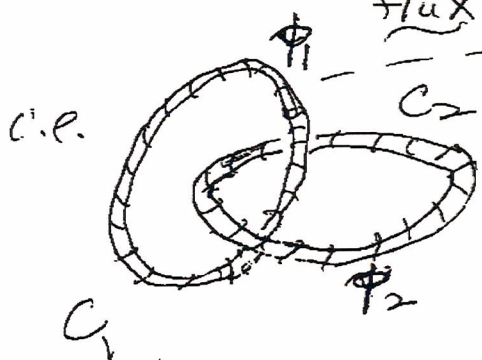
$$\underline{A} \cdot \underline{B} = B_z \left[\mu \int_0^r \frac{B_\theta}{\mu} dr - \int_0^r B_\theta dr \right]$$

= 0 for constant μ

∴ non-zero helicity requires $\mu = \mu(r)$
i.e. - pitch varies with radius

⇒ magnetic shear / twist

- physically → helicity means self-linkage of 2 flux tubes



tube 1: flux

$$\Phi = \int_{\text{x-section area}} dA \cdot \underline{B} = \oint \underline{B} \cdot d\underline{l}$$

∫_{x-section area} ∫_{const}

tube 2: $\Phi = \Phi_2$

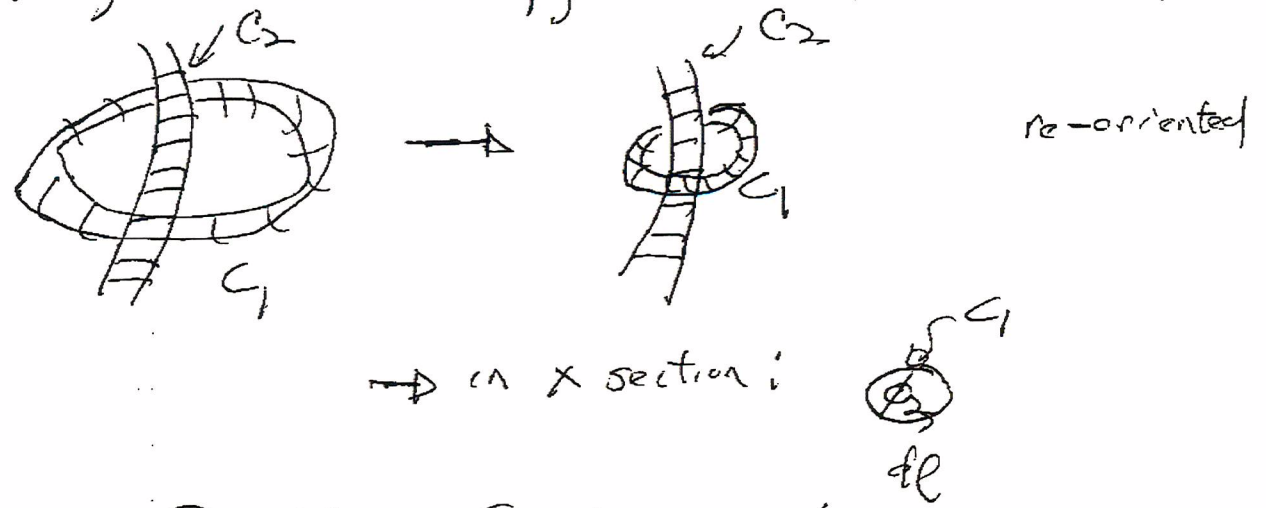
field in loops, only

Now, for volume V_1 of tube 1

$$\begin{aligned}
 K &= \int_{V_1} \underline{A} \cdot \underline{B} \, d^3x = \oint_{C_1} d\ell \int_{S_1} dS \, \underline{A} \cdot \underline{B} \\
 &= \oint_{C_1} \underline{A} \cdot d\ell \int_{S_1} \underline{B} \cdot \hat{n} \, dA \\
 &= \oint_{C_1} \oint_{C_2} \underline{A} \cdot d\ell
 \end{aligned}$$

$\left. \begin{array}{l} C_1 \\ \text{elong} \\ \text{loop} \end{array} \right\}$
 $\left. \begin{array}{l} A_1 \\ \text{X-section} \\ \text{area} \end{array} \right\}$

Now, can shrink C_1 , as no field outside loops



but $\int_{C_1} \underline{A} \cdot d\ell = \int_{A \text{ enclosed}} \underline{B} \cdot dS = \Phi_2$

so... $k_1 = \phi_1 \phi_2 \rightarrow$ product of fluxes

similarly $k_2 = \phi_2 \phi_1$

$$\therefore k = 2\phi_1 \phi_2$$

if n windings $k = k_1 + k_2 = \pm 2n\phi_1 \phi_2$

\Rightarrow helicity is measure of self-linkage of magnetic configuration.

Why care \rightarrow Taylor Conjecture (1974) (J.B. Taylor)

- in magnetic confinement, of great interest to determine how fields, currents self-organize

- RFP  \rightarrow toroid
 \rightarrow toroidal current

well fit by $B_z = B_0 \bar{J}_0(\alpha r)$ $\bar{J} \times B = 0$
 $B_\theta = B_0 \bar{J}_1(\alpha r)$ \bar{E}

\Rightarrow why so robust? especially since RFP so turbulent force free

- Taylor conjectured conservation of magnetic helicity constrains relaxation to force-free state.

Key Point - helicity conserved in flux tubes, to ∞
 - toroidal plasma \rightarrow many small tubes



etc.

- recall Sweet-Parker model: magnetic reconnection/resistive dissipation effective on small scales.

\Rightarrow Taylor Conjecture: At finite η , helicity of small tubes dissipated but global helicity conserved.

$$\underline{\underline{\text{c.e.}}} \quad \int_{\text{plasma volume}} \underline{A} \cdot \underline{B} \, d^3x = K_0 \rightarrow \text{c.e. conserved.}$$

\therefore Taylor conjectured that actual magnetic configuration could be explained by minimum principle:

$$\int d^3x \left[\frac{B^2}{8\pi} + \lambda \underline{A} \cdot \underline{B} \right] = \text{const}$$

i.e. minimize magnetic energy subject to constraint of conserved global helicity,

Comments:

→ it works! - indeed amazingly well - for

RFPs, spheromaks, etc. Departures only recently being discovered

→ inspired idea of helicity injection as way to maintain configurations

→ it is a conjecture → no proof.

Hypothesis: Selective Decay

- energy cascades → small scale
- helicity cascades → large scale (less dissipation)

- Relevance to driven system?
i.e. in real RFP, transformer on.

→ dynamics? - how does relaxation occur

→ more in discussion of kinks, tearing.