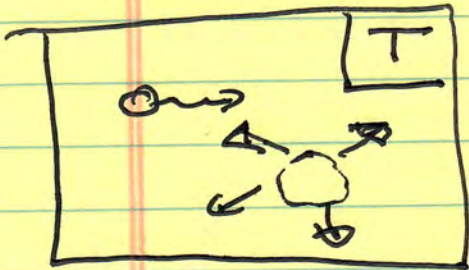


Physics 240 B

II-2-a → Fokker-Planck I

- Back to R.M.;

Statistical
Dynamics
Problem



(i) how does Pdf
- Probability Distribution
Function - evolve for
Brownian Particle

d.e. $f(\underline{v}, \underline{x}, t)$

→ more interesting/useful than
 $\langle x^2 \rangle, \langle v^2 \rangle$ etc.

and

(ii) If initial cloud of particles, how
does it evolve in time.

d.e. $n(\underline{r}, t=0) = n_0 \delta(\underline{r} - \underline{r}_0)$

$n(\underline{r}, t) ?$

- of course, will involve diffusion

$$\langle \Delta x^2 \rangle = 2D_x t$$

⇒ Fokker-Planck Equation

- calculate $F(x, y, t)$; $P(x, t)$, not moments $\langle x^n \rangle$
- applies to dynamics with \approx no memory / short memory
- Evolution as result of sequentially, uncorrelated small steps.

⇒ closely related to Central Limit Theorem - background

Aside

N.B.: Central Limit Theorem

- Consider a sum of n independent random variables $\Delta X_1, \Delta X_2, \dots, \Delta X_n$ ($n \gg 1$).

$$- X_n = \Delta X_1 + \Delta X_2 + \dots + \Delta X_n$$

[sum of independent increments]

- For ΔX_i $\langle \Delta X_i \rangle = 0$

$$\langle \Delta X_j^2 \rangle = \sigma_i^2$$

N.B.: \Rightarrow Variance (only) - second moment - exists (i.e. finite)

$$\langle \Delta X_j^2 \rangle < \infty, \text{ all } j$$

~~no~~ \Rightarrow no outliers among $\langle \Delta X_j^2 \rangle$, all finite

Then
$$\sigma_n^2 = \sigma_1^2 + \sigma_2^2 + \dots + \sigma_n^2$$

$$\cong n \sigma^2$$

and Pdf $(y) \rightarrow \frac{1}{\sqrt{2\pi}}$ $e^{-y^2/2}$

$$\rightarrow \text{Pdf}(x_n) \rightarrow \frac{1}{\sqrt{2\pi\sigma_n^2}} \exp\left[-x_n^2/2\sigma_n^2\right]$$

$[n \gg 1]$

$$\rightarrow \frac{1}{\sqrt{2\pi N \sigma^2}} \exp\left[-x_n^2/N\sigma^2\right]$$

c.e. Pdf of sum of δx 's is Gaussian, with variance $N\tau^2$

Key Points:

→ Variance of step finite $\langle \Delta x_j^2 \rangle < \infty$.

→ convergence $\langle \Delta x_j^2 \rangle < \infty \not\rightarrow$

say, $\langle \Delta x_j^4 \rangle < \infty \Rightarrow$ higher

moments can induce "heavy tails" on pdf.

Will discuss further.

→ Continuing with Fokker-Planck Theory

- consider a system with short/no

no memory

→ every step in \mathcal{T} independent of prior history (Markov Process)

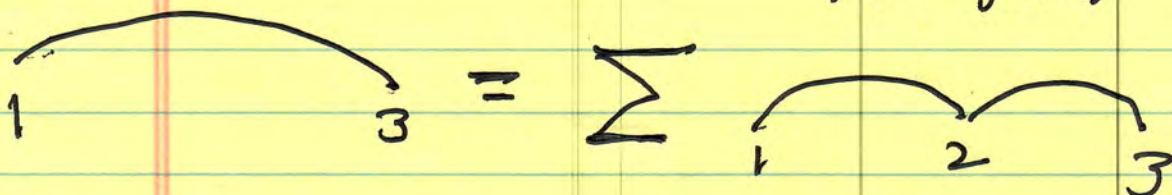
50 $x_1, t_1 \rightarrow x_3, t_3$
with intermediate stop
at x_2, t_2

$$P_{\text{rob.}}(x_3, t_3; x_1, t_1) = \int dx_2 P(x_3, t_3 | x_2, t_2) P(x_2, t_2 | x_1, t_1)$$


Prob at x_3, t_3 starting from x_1, t_1 integrate over intermediate 2-3 jump

$$P(x_2, t_2 | x_1, t_1)$$

1-2 jump



i.e.


each step independent
all possible intermediates

$$P(x_3, t_3; x_1, t_1) = \int dx_2 P(x_3, t_3 | x_2, t_2) P(x_2, t_2 | x_1, t_1)$$

Chapman - Kolmogorov Eqn.

Now, re-write for small step Δx
 (how small is small?) in
 short/small time increment τ ;
 (how short ... ?)

Take: $P(x_2, t_2 | x_1, t_1) = T(x, \Delta x, \tau)$

Transition
Probability

at x step Δx in time

$$t_2 - t_1 \rightarrow \tau$$

$$x_2 - x_1 \rightarrow \Delta x$$

then

$$P(x, t + \tau) = \int d(\Delta x) P(x - \Delta x, t) T(x, \Delta x, \tau)$$

1 step away, etc.

Now expand \rightarrow lowest odd, even:
 (Kramers - Moyal Expansion)

\downarrow
 truncation \rightarrow C. L. T.

$$P(x, t) + \gamma \frac{\partial P(x, t)}{\partial t}$$

$$= \int d(\Delta x) \left\{ \begin{array}{l} \textcircled{1} \\ P(x, t) T(x, \Delta x, \tau) \end{array} \right.$$

$$- \frac{\partial}{\partial x} \cdot \left(\begin{array}{l} \textcircled{2} \\ \Delta x P(x, t) T(x, \Delta x, \tau) \end{array} \right)$$

$$+ \frac{1}{2} \frac{\partial}{\partial x} \cdot \frac{\partial}{\partial x} \left(\begin{array}{l} \textcircled{3} \\ \Delta x \Delta x P(x, t) T(x, \Delta x, \tau) \end{array} \right) \}$$

$$+ \text{h.o.}$$

① Normalization:

$$\int d(\Delta x) T(x, \Delta x, \tau) = 1$$

τ must be normalizable

$$\textcircled{2} - \int d(\Delta x) \frac{\partial}{\partial x} \cdot \left(\Delta x P(x, t) T(x, \Delta x, \tau) \right)$$

$$= - \frac{\partial}{\partial x} \cdot \left(\langle \Delta x \rangle P(x, t) \right)$$

vector form

Order of Derivatives Matters!

$$\langle \underline{\Delta x} \rangle = \int d(\underline{\Delta x}) \underline{\Delta x} T(x, \underline{\Delta x}, t)$$

mean step \rightarrow drift

$$\textcircled{3} \int d(\underline{\Delta x}) \frac{\partial}{\partial x} \cdot \frac{\partial}{\partial x} \cdot \left(\frac{\underline{\Delta x} \underline{\Delta x}}{2} \right) P(x, t) T(x, \underline{\Delta x}, T)$$

$$= \frac{\partial}{\partial x} \cdot \frac{\partial}{\partial x} \cdot \left[\frac{\langle \underline{\Delta x} \underline{\Delta x} \rangle}{2} P(x, t) \right]$$

$$\langle \underline{\Delta x} \underline{\Delta x} \rangle = \int d(\underline{\Delta x}) \underline{\Delta x} \underline{\Delta x} T(x, \underline{\Delta x}, T)$$

\leadsto mean square step

\leadsto tensor \rightarrow cross terms \downarrow

\Rightarrow will become different.

then; dividing thru by ρ :

$$\begin{aligned} \frac{\partial \rho(x,t)}{\partial t} &= - \frac{\partial}{\partial x} \cdot \left\{ \frac{\langle \Delta x \rangle}{\tau} \rho(x,t) \right. \\ &\quad \left. - \frac{\partial}{\partial x} \cdot \left(\frac{\langle \Delta x \Delta x \rangle}{2\tau} \rho(x,t) \right) \right\} \\ &= - \frac{\partial}{\partial x} \cdot \left\{ v \rho(x,t) - \frac{\partial}{\partial x} \cdot (D \rho(x,t)) \right\} \end{aligned}$$

$$v = \frac{\langle \Delta x \rangle}{\tau} \rightarrow \text{drift velocity}$$

$$D = \frac{\langle \Delta x \Delta x \rangle}{2\tau} \rightarrow \text{diffusion (tensor)}$$

Welcome to Fokker-Planck Equation!

(N.B.: Diffusion is special case).

Note: Observations

- F.-P. based on assumption of Markov Process
- coarse grains on scales τ Δx
(minimum resolvable)

$\tau \leftrightarrow \tau_{ac}$ is random process

$$\Delta x \sim \int dt \tilde{v}$$

$$\Delta x^2 \sim 2Dt$$

$$D = \int_0^{\infty} \langle \tilde{v}(t) \tilde{v}(t') \rangle dt \rightarrow |\tilde{v}|^2 \tau_{ac}$$

$$\Delta x \sim \tilde{v} \tau_{ac}$$

- can write in form:

$$\frac{\partial p}{\partial t} = - \frac{\partial}{\partial x} \cdot \underline{\Gamma} p$$

\downarrow
probability flux

manifestly
conserved
probability

\downarrow
write as divergence

$$\Gamma_p = \nabla P(x,t) - \frac{\partial}{\partial x} \left(\frac{D}{\hbar} P(x,t) \right)$$

Probability flux

- describes dynamics where macro evolution set by accumulation of many small steps.

Buried Bodies

① - no long time, long range correlations

②* assumes $\langle AX^2 \rangle = \int dx P(x) (Ax)^2 T$
 $< \infty$!

not guaranteed by T normalization.

→ ② near equilibrium
 Gaussian

⇒ $\int (Ax)^2 T < \infty$ ✓

→ exponential ✓

(Gamma)

→ Power Law ?

→ self-similar processes → scaling
→ reality

$$T \sim I / \left[1 + \frac{(\Delta X)^2}{L} \right]$$

infrared control

⇒ need $\alpha > 3$, or

[expansion factor, and G.L.Th. violated.]

③ → γ not uniform?!

i.e. assume: | | | | | |
clock-like regularity

but | || |
sticking

②, ③ \Rightarrow $\left\{ \begin{array}{l} \text{Fractional kinetics} \\ \text{CTRW} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \text{Levy} \\ \text{Walk} \end{array} \right\}$

Central Limit Thm. violated \Rightarrow
Levy Distribution, not Gaussian.

Will discuss.

Light Reading:

- R. Lowenstein, "When Genius Failed"
 \rightarrow LTCM

- B. Mandelbrot, "The (Mis) Behavior of Markets",

Examples:

- trivial \rightarrow Brownian Motion

- Aside: Stochastic Liouville

- Useful \rightarrow Schmoluchowski and Sedimentation
 Kramers 1

- trickier \rightarrow Logistics with
Multiplicative Noise

(a.) Brownian Motion

both at
T.

- What is $f(v, t)$?
 $t \rightarrow \infty$

Obviously a Gaussian, with
variance v_{th}^2 !

How show ?

\rightarrow Fokker-Planck Eqn

\rightarrow Stationarity: $\partial f / \partial t \rightarrow 0$

$\Rightarrow \Gamma_v \rightarrow 0.$

Of course, have:

$$m \frac{\partial v}{\partial t} = -\beta v + f^2$$

$$\langle \tilde{F}(t) \tilde{F}(t') \rangle = |\tilde{F}|^2 T_{ac} \delta(t-t')$$

So, can set up F-P Egn, in v ?

$$F(v, t+\tau) = \int d(\underline{\Delta v}) f(\underline{v}-\underline{\Delta v}, t) T(\underline{\Delta v}, \tau)$$

expand as before gives:

$$\frac{d}{dt} F(v, t) = -\frac{\partial}{\partial v} \cdot \underline{\Gamma}_v$$

$$\underline{\Gamma}_v = \left\{ \langle \underline{\Delta v} \rangle F(v, t) - \frac{\partial}{\partial v} \cdot \left(\frac{\langle \underline{\Delta v} \underline{\Delta v} \rangle}{2\tau} F(v, t) \right) \right\}$$

$$= \left\{ \underline{V} F(v, t) - \frac{\partial}{\partial v} \cdot \underline{D} F(v, t) \right\}$$

To calculate drift, diffusion:

use Langevin Egn.

$$\frac{d\mathbf{v}}{dt} = -\frac{\beta}{m} \mathbf{v} + \tilde{\mathbf{a}}(t)$$

then avg:

$$\left\langle \frac{\Delta \mathbf{v}}{T} \right\rangle = -\mathbf{v} = -\frac{\beta}{m} \mathbf{v}$$

→ drift opposite motion,
 $\sim \beta/m$

For velocity diffusion:

$$D_v = \left\langle \frac{\Delta \mathbf{v} \Delta \mathbf{v}}{2T} \right\rangle = \int_0^T \langle \tilde{\mathbf{a}}(t) \tilde{\mathbf{a}}(t') \rangle dt$$

$$= \frac{|\tilde{\mathbf{f}}_0|^2}{m^2} \tilde{\tau}_{ac}$$

but FDT:

$$|\tilde{\mathbf{f}}_0|^2 \tilde{\tau}_{ac} = \beta m \langle \tilde{v}^2 \rangle = \frac{\beta}{m} m^2 \frac{T}{m}$$

$$D_v = \frac{\beta T}{m^2} = \left(\frac{\beta}{m} \right) v_{th}^2 \quad \checkmark$$

(dims./expected)

$$D_v = \frac{\beta}{m} v_{th}^2 \left[\frac{I}{\equiv} \right]$$

$$\underline{V} = -\frac{\beta}{m} \underline{v}$$

LD

$$\Gamma_v = \underline{V} f - \frac{\partial}{\partial v} (D_v f)$$

$$= -\frac{\beta}{m} \underline{v} f - \frac{\partial}{\partial v} \left(\frac{\beta}{m} v_{th}^2 f \right)$$

$$\Gamma_v = 0$$

$$f = \# \exp \left[-\frac{v^2}{2 v_{th}^2} \right]$$

$$= \# \exp \left[-\frac{\beta}{m} \frac{v^2}{2 D_v} \right]$$

Gaussian results from balance of drag with drift diffusion

$$D_v = \frac{\beta}{m} v_{th}^2$$