Consider an isolated system, whose total energy is therefore constant, consisting of an ensemble of identical particles that can exchange energy with one another and thereby achieve thermal equilibrium. In order to simplify the numerical derivation, we will assume that the energy $E$ of any individual particle is restricted to one or another of the values $0, \Delta E, 2\Delta E, 3\Delta E, \ldots$ Later, after seeing how the distribution emerges, we can let $\Delta E \rightarrow 0$ so that the permitted energies are continuous. Simply to keep the amount of subsequent calculations manageable, we will assume that the system consists of only six particles (hardly a “large” number!) and that the total energy $E_{\text{total}}$ of the system is $8\Delta E$, both numbers being arbitrarily chosen, the latter of necessity being an integer multiple of $\Delta E$.

It is also convenient at this point to introduce the concept of macrostates and microstates. The term microstate refers to the description of the system in which the state of every individual particle is specified. For classical particles this means specifying the position and momentum, hence energy, for each. In quantum mechanics it means specifying a complete set of quantum numbers for each particle. The macrostate for a system is a less detailed description in which only the number of particles occupying each energy state is specified.

Since the particles can exchange energy with one another, all possible macrostates, that is, divisions of the total energy $E_{\text{total}} = 8\Delta E$ between six particles, can occur. For the example we are considering, there are 20 macrostates, labeled 1 through 20 in Table BD-1. For instance, macrostate 1 has five particles with $E = 0$ and one with $E = 8\Delta E$; macrostate 2 has four particles with $E = 0$, one with $E = \Delta E$, and one with $E = 7\Delta E$; and so on. Notice that there are six different ways we can rearrange the particles in macrostate 1 so as to achieve that particular division of the total energy $8\Delta E$ since any one of the particles can be put into the state $8\Delta E$ with the other five in the state $E = 0$. Each of these six arrangements is different from the other because the classical particles in a microstate are identical in terms of physical properties but distinguishable in terms of position and momentum, hence energy. Thus, the rearrangements of the five particles in the $E = 0$ state are not distinguishable from one another since all five have the same energy. The number of distinguishable rearrangements of the particles within a given macrostate are the microstates.

The way the number of microstates is computed goes as follows: For six particles the rules of statistics tell us that there are $6!$ different rearrangements or permutations possible. For $N$ particles the number is, of course $N!$. However, since rearrangements within the same energy state are not distinguishable, those must be divided out of the total.
Number of microstates = \[ \frac{N!}{n_0! \cdot n_1! \cdot n_2! \cdots n_i!} \]

For macrostate 1 there are five particles in the \( E = 0 \) state, so the 5! rearrangements of those five must be divided out of the 6! total number for all six particles in order to obtain the number \( N \) of distinguishable rearrangements, or microstates, for macrostate 1. Since \( 6! / 5! = 6 \), that is how the number of microstates for macrostate 1 was determined. Example BD-1 following Table BD-1 below illustrates the calculation for macrostate 6 of the system we are using for the derivation.

**EXAMPLE BD-1**

**Number of Microstates**

Compute the number of microstates, that is, distinguishable rearrangements, for macrostate 6 in Table BD-1.

**SOLUTION**

The total number of possible rearrangements of six particles is 6!; however, energy state \( E = 0 \) contains three particles, hence 3! indistinguishable rearrangements, and energy state \( E = \Delta E \) contains two particles, hence 2! more. Therefore, the total number of microstates is

\[ \frac{N!}{n_0! \cdot n_1!} = \frac{6!}{3!2!} = \frac{6 \times 5 \times 4 \times 3 \times 2 \times 1}{(3 \times 2 \times 1) \cdot (2 \times 1)} = 60 \]

If we now make the reasonable assumption that all microstates occur with the same probability, then the relative probability \( P_j \) that macrostate \( j \) will occur is proportional to the number of microstates that exist for that state. For our system there are 1287 total microstates, so the relative probability \( P_j \) of occurrence for each of the 20 macrostates is the number of microstates listed in the column on the right of Table BD-1 divided by 1287. Now we are close to obtaining the approximate form of the Boltzmann distribution. Assuming that the most probable distribution of the particles among the available states is that corresponding to thermal equilibrium, we have only to calculate how many particles \( n(E_i) \) are likely to be found in each of the nine energy states \( E_0 = 0 \) through \( E_8 = 8\Delta E \). Consider the \( E_0 = 0 \) state. For macrostate 1, the probability of occurrence \( P_1 \) is \( 6/1287 \) and there are five particles in the \( E_0 = 0 \) energy state; therefore, macrostate 1 will contribute \( 5 \times (6/1287) = 0.023 \) particles to the total for \( E_0 = 0 \). The number of particles contributed by the other 19 macrostates to the \( E_0 = 0 \) state are computed in an identical manner and, when added, yield a total
\( n(0) = 2.31 \) particles, meaning that an average of 2.31 of the six particles will be found to have \( E = 0 \). Thus, in general the \( n(E) \) values are given by

\[
n(E_i) = \sum_j n_i p_j = g_i f(E_i) \tag{BD-1a}
\]

where \( g_i \) is the statistical weight of state \( i \) and \( f(E_i) \) is the probability of a particle having energy \( E_i \). Clearly, then

\[
N = \sum_i n(E_i) \tag{BD-1b}
\]

The bottom row of Table BD-1 records the result of this calculation for each of the possible energies. Note that the sum of the \( n(E_i) \) values is 6 as you would expect.

In Figure BD-1 the values of \( n(E_i) \) are plotted against \( E \). The curve shown with the solid line is an exponential function fitted to the data where \( B \) and \( E_c \) in Equation BD-2 are constants.

\[
n(E) = B e^{-E/E_c} \tag{BD-2}
\]

If we allow \( \Delta E \) to become smaller while keeping the total energy the same as before, we get more data points on the graph. In the limit as \( \Delta E \to 0, E \) becomes a continuous variable and \( n(E) \) a continuous function. If we also increase the number of particles to a statistically large number, we find that the data points fall exactly on the solid curve in Figure BD-1; that is, the form of the Boltzmann distribution is correctly given by Equation BD-2. Verifying this with an extension of the calculation for six particles and \( E_{\text{total}} = 8 \Delta E \) to a large number of particles and energy states would be a formidable task. Fortunately, there is a much simpler but subtle way to show that it is correct, as has been described by Eisberg and Resnick.\(^2\)

When a particular particle gains energy as the result of an interaction, it does so at the expense of the rest of the particles since the total energy of the system is conserved. Except for this conservation requirement, the particles are independent of one another and, in particular, there is no prohibition or constraint on more than one particle occupying the exact same energy state, as Table BD-1 illustrates. Consider just two particles from the ensemble. Let the probability of finding one of them in the energy state \( E_1 \) be given by \( f(E_1) \). Since the distribution function is the same for all of the particles (because they are identical), the probability of finding the second one in an energy state \( E_2 \) is found by evaluating that function at \( E_2 \), that is, \( f(E_2) \). Since the particles are independent of one another, so are their probabilities. Consequently, according to probability theory, the probability of both occurrences, that is, of finding one particle with energy \( E_1 \) and the other with energy \( E_2 \), is the product of the probabilities \( f(E_1) \times f(E_2) \). (This is equivalent to the probability of obtaining heads on two successive coin tosses. The probability of getting heads is \( 1/2 \) on each toss and the tosses, like the particles, are independent, so the probability of getting heads twice is \( 1/2 \times 1/2 = 1/4 \).)

Now consider all of the macrostates of the system for which the sum of the energies of the two particles totals \( E_1 + E_2 \), as was just discussed but for which the two particles share the total differently than before.\(^3\) Since the energy is conserved, the remainder of the system has the same amount of energy (and the same number of particles) for each of these macrostates, namely \( E_{\text{total}} - (E_1 + E_2) \). All of these remainders have the same number of ways to divide their energy among their constituent particles. Therefore, the probability for those microstates in which \( E_1 + E_2 \) is shared between the two particles in a certain way can differ from the probability for those
Table BD-1  States and occupation probabilities for six particles with total energy $8\Delta E$

<table>
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<tr>
<th>Macrostate $j$</th>
<th>$\Delta E$</th>
<th>$2\Delta E$</th>
<th>$3\Delta E$</th>
<th>$4\Delta E$</th>
<th>$5\Delta E$</th>
<th>$6\Delta E$</th>
<th>$7\Delta E$</th>
<th>$8\Delta E$</th>
<th>Number of microstates</th>
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<tr>
<td>$n(E_i)$</td>
<td>2.31</td>
<td>1.54</td>
<td>0.98</td>
<td>0.59</td>
<td>0.33</td>
<td>0.16</td>
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</table>

Microstates in which $E_1 + E_2$ is shared differently only if the different ways $E_1 + E_2$ can be shared occur with different probabilities. However, we have already assumed that all microstates occur with the same probability; therefore, we must conclude that all microstates in which $E_1 + E_2$ is shared differently between the two particles occur with the same probability. This means that the probability for such microstates occurring is some function of the sum $E_1 + E_2$, say $h(E_1 + E_2)$. The original sharing of energy, $E_i$ to one particle and $E_j$ to the other, is certainly one of these, and, hence, has probability $h(E_1 + E_2)$. But we have already shown that particular sharing to occur with probability $f(E_1) \times f(E_2)$ and we must conclude, therefore, that
Thus, the probability distribution \( f(E) \) that we seek has the property that the product of the results of evaluating the function \( f(E) \) at two different energies is a function of the sum of those energies. The only mathematical function that has this property is the exponential function. \(^4\) If we take \( n(E_i) \), the average number of particles with energy \( E_i \) (again, see Table BD-1), to be proportional to \( f(E_i) \), as would be expected, then we have from Equation BD-2 that

\[
f(E) = Ae^{-E/E_c}
\]

from which we conclude that the exponential form used to fit the data in Figure BD-1 is the only correct form of the distribution of identical, distinguishable particles among the available energy states of a classical system. \(^5\)

Boltzmann used calculus of variations to do a much more general derivation of Equation BD-3 than we have done here, obtaining for the constant \( E_c \), independent of the nature of the particles, the value

\[
E_c = kT
\]

where \( k = 1.381 \times 10^{-23} \text{ J/K} \) is the Boltzmann constant and \( T \) is the absolute temperature. Inserting \( E_c \) from Equation BD-4 into Equation BD-3 gives the Boltzmann distribution \( f_B \), the probability that a state with energy \( E \) is occupied at temperature \( T \):

\[
f_B(E) = Ae^{-E/kT}
\]

In a wave-mechanical treatment of the example system of six identical particles that we used in the derivation of the Boltzmann distribution above, the individual microstates that were identified for a particular macrostate cannot be distinguished from one another. Thus, rather than the 1287 distinguishable microstates listed in Table BD-1, the system of six identical, indistinguishable particles with a total energy \( 8\Delta E \) has only the 20 macrostates (Bose-Einstein statistics). Again assuming that each of these states occurs with equal probability as we did with the distinguishable microstates earlier, we find that the average number of particles in each energy state is computed just as illustrated in that example. For example, for the \( E = 0 \) state, state 1 contributes (see Table BD-1)

Number of particles in state 1 with \( E = 0 \)  
Number of states = \( \frac{5}{20} \)

and the average number of particles \( n_{BE}(0) \) in energy state \( E = 0 \) is, therefore,

\[
n_{BE}(0) = \frac{[5 + (4 \times 4) + (5 \times 3) + (5 \times 2) + (3 \times 1)]}{20} = 2.45
\]

Table BD-2 lists the average number of such particles \( n_{BE}(E) \) in each energy state computed in the same manner as the example above. Note that the number of particles totals 6, as expected.

There is yet another condition that limits the way quantum-mechanical particles that obey the Pauli exclusion principle can be distributed among the energy states (Fermi-Dirac statistics). If our six particles were electrons, the exclusion principle would prevent more than two (one with spin up and one with spin down) from occupying any particular energy. Since the exclusion principle applies to all particles that, like electrons, have \( \frac{1}{2} \)-integral spins, such as protons, neutrons, muons, and quarks, this limitation in number per energy state applies to them also. Examining Table BD-2, we see that only the three macrostates marked with asterisks (12, 13, and 14)
conform to this limitation. Thus, particles that obey the exclusion principle can only occupy those three states. Once again assuming that each is occupied with equal probability, we find that the average number of particles \( n_{FD}(E) \) in each energy state is computed as before. For example, the average number of particles in the \( E = 0 \) state, \( n_{FD}(0) \), is

\[
n_{FD}(0) = \frac{\text{Number of particles with } E = 0}{\text{Number of states}} = \frac{(2 + 2 + 2)}{3} = 2
\]

### Notes for Derivation of the Boltzmann Distribution

1. We use the term *particles* here as a specific example. They could be molecules, grains of dust, coil springs, and so on, just as long as they are all identical and can contain energy.


3. Using the particles in Table BD-1 as an example, suppose \( E_1 + E_2 = 5\Delta E \). Then macrostates 4, 8, 9, 10, 13, 14, 15, 16, and 17 are all ones in which two particles have total energy \( 5\Delta E \), although each particle’s share varies between the macrostates.

4. Recall that \( e^a \times e^b = e^{(a+b)} \).

5. This argument allows both positive and negative exponentials. The positive exponential is ruled out on physical grounds since it predicts an infinite probability that a particle will have infinite energy, which is in obvious disagreement with experimental observation.