## Chapter 2

## Quantum Mechanical Path Integral

### 2.1 The Double Slit Experiment

Will be supplied at later date

### 2.2 Axioms for Quantum Mechanical Description of Single Particle

Let us consider a particle which is described by a Lagrangian $L(\vec{r}, \dot{\vec{r}}, t)$. We provide now a set of formal rules which state how the probability to observe such a particle at some space-time point $\vec{r}, t$ is described in Quantum Mechanics.

1. The particle is described by a wave function $\psi(\vec{r}, t)$

$$
\begin{equation*}
\psi: \mathbb{R}^{3} \otimes \mathbb{R} \rightarrow \mathbb{C} \tag{2.1}
\end{equation*}
$$

2. The probability that the particle is detected at space-time point $\vec{r}, t$ is

$$
\begin{equation*}
|\psi(\vec{r}, t)|^{2}=\overline{\psi(\vec{r}, t)} \psi(\vec{r}, t) \tag{2.2}
\end{equation*}
$$

where $\bar{z}$ is the conjugate complex of $z$.
3. The probability to detect the particle with a detector of sensitivity $f(\vec{r})$ is

$$
\begin{equation*}
\int_{\Omega} d^{3} r f(\vec{r})|\psi(\vec{r}, t)|^{2} \tag{2.3}
\end{equation*}
$$

where $\Omega$ is the space volume in which the particle can exist. At present one may think of $f(\vec{r})$ as a sum over $\delta$-functions which represent a multi-slit screen, placed into the space at some particular time and with a detector behind each slit.
4. The wave function $\psi(\vec{r}, t)$ is normalized

$$
\begin{equation*}
\int_{\Omega} d^{3} r|\psi(\vec{r}, t)|^{2}=1 \quad \forall t, t \in\left[t_{0}, t_{1}\right] \tag{2.4}
\end{equation*}
$$

a condition which enforces that the probability of finding the particle somewhere in $\Omega$ at any particular time $t$ in an interval $\left[t_{0}, t_{1}\right]$ in which the particle is known to exist, is unity.
5. The time evolution of $\psi(\vec{r}, t)$ is described by a linear map of the type

$$
\begin{equation*}
\psi(\vec{r}, t)=\int_{\Omega} d^{3} r^{\prime} \phi\left(\vec{r}, t \mid \vec{r}^{\prime}, t^{\prime}\right) \psi\left(\vec{r}^{\prime}, t^{\prime}\right) \quad t>t^{\prime}, t, t^{\prime} \in\left[t_{0}, t_{1}\right] \tag{2.5}
\end{equation*}
$$

6. Since (2.4) holds for all times, the propagator is unitary, i.e., $\left(t>t^{\prime}, t, t^{\prime} \in\left[t_{0}, t_{1}\right]\right)$

$$
\begin{gather*}
\int_{\Omega} d^{3} r|\psi(\vec{r}, t)|^{2}= \\
\int_{\Omega} d^{3} r \int_{\Omega} d^{3} r^{\prime} \int_{\Omega} d^{3} r^{\prime \prime} \phi\left(\vec{r}, t \mid \vec{r}^{\prime}, t^{\prime}\right) \overline{\phi\left(\vec{r}, t \mid \vec{r}^{\prime \prime}, t^{\prime}\right)} \psi\left(\vec{r}^{\prime}, t^{\prime}\right) \overline{\psi\left(\vec{r}^{\prime \prime}, t^{\prime}\right)} \\
=\int_{\Omega} d^{3} r\left|\psi\left(\vec{r}, t^{\prime}\right)\right|^{2}=1 \tag{2.6}
\end{gather*}
$$

This must hold for any $\psi\left(\vec{r}^{\prime}, t^{\prime}\right)$ which requires

$$
\begin{equation*}
\int_{\Omega} d^{3} r^{\prime} \phi\left(\vec{r}, t \mid \vec{r}^{\prime}, t^{\prime}\right) \overline{\phi\left(\vec{r}, t \mid \vec{r}^{\prime \prime}, t^{\prime}\right)}=\delta\left(\vec{r}^{\prime}-\vec{r}^{\prime \prime}\right) \tag{2.7}
\end{equation*}
$$

7. The following so-called completeness relationship holds for the propagator $\left(t>t^{\prime} t, t^{\prime} \in\right.$ $\left.\left[t_{0}, t_{1}\right]\right)$

$$
\begin{equation*}
\int_{\Omega} d^{3} r \phi\left(\vec{r}, t \mid \vec{r}^{\prime}, t^{\prime}\right) \phi\left(\vec{r}^{\prime}, t^{\prime} \mid \vec{r}_{0}, t_{0}\right)=\phi\left(\vec{r}, t \mid \vec{r}_{0}, t_{0}\right) \tag{2.8}
\end{equation*}
$$

This relationship has the following interpretation: Assume that at time $t_{0}$ a particle is generated by a source at one point $\vec{r}_{0}$ in space, i.e., $\psi\left(\vec{r}_{0}, t_{0}\right)=\delta\left(\vec{r}-\vec{r}_{0}\right)$. The state of a system at time t , described by $\psi(\vec{r}, t)$, requires then according to (2.8) a knowledge of the state at all space points $\vec{r}^{\prime} \in \Omega$ at some intermediate time $t^{\prime}$. This is different from the classical situation where the particle follows a discrete path and, hence, at any intermediate time the particle needs only be known at one space point, namely the point on the classical path at time $t^{\prime}$.
8. The generalization of the completeness property to $N-1$ intermediate points $t>t_{N-1}>$ $t_{N-2}>\ldots>t_{1}>t_{0}$ is

$$
\begin{gather*}
\phi\left(\vec{r}, t \mid \vec{r}_{0}, t_{0}\right)=\int_{\Omega} d^{3} r_{N-1} \int_{\Omega} d^{3} r_{N-2} \cdots \int_{\Omega} d^{3} r_{1} \\
\phi\left(\vec{r}, t_{\mid} \vec{r}_{N-1}, t_{N-1}\right) \phi\left(\vec{r}_{N-1}, t_{N-1} \mid \vec{r}_{N-2}, t_{N-2}\right) \cdots \phi\left(\vec{r}_{1}, t_{1} \mid \vec{r}_{0}, t_{0}\right) . \tag{2.9}
\end{gather*}
$$

Employing a continuum of intermediate times $t^{\prime} \in\left[t_{0}, t_{1}\right]$ yields an expression of the form

$$
\begin{equation*}
\phi\left(\vec{r}, t \mid \vec{r}_{0}, t_{0}\right)=\iint_{\vec{r}\left(t_{0}\right)=\vec{r}_{0}}^{\vec{r}\left(t_{N}\right)=\vec{r}_{N}} d[\vec{r}(t)] \Phi[\vec{r}(t)] . \tag{2.10}
\end{equation*}
$$

We have introduced here a new symbol, the path integral

$$
\begin{equation*}
\iint_{\vec{r}\left(t_{0}\right)=\vec{r}_{0}}^{\vec{r}\left(t_{N}\right)=\vec{r}_{N}} d[\vec{r}(t)] \cdots \tag{2.11}
\end{equation*}
$$

which denotes an integral over all paths $\vec{r}(t)$ with end points $\vec{r}\left(t_{0}\right)=\vec{r}_{0}$ and $\vec{r}\left(t_{N}\right)=\vec{r}_{N}$. This symbol will be defined further below. The definition will actually assume an infinite number of intermediate times and express the path integral through integrals of the type (2.9) for $N \rightarrow \infty$.
9. The functional $\Phi[\vec{r}(t)]$ in $(2.11)$ is

$$
\begin{equation*}
\Phi[\vec{r}(t)]=\exp \left\{\frac{i}{\hbar} S[\vec{r}(t)]\right\} \tag{2.12}
\end{equation*}
$$

where $S[\vec{r}(t)]$ is the classical action integral

$$
\begin{equation*}
S[\vec{r}(t)]=\int_{t_{0}}^{t_{N}} d t L(\vec{r}, \dot{\vec{r}}, t) \tag{2.13}
\end{equation*}
$$

and

$$
\begin{equation*}
\hbar=1.0545 \cdot 10^{-27} \mathrm{erg} \mathrm{~s} \tag{2.14}
\end{equation*}
$$

In (2.13) $L(\vec{r}, \dot{\vec{r}}, t)$ is the Lagrangian of the classical particle. However, in complete distinction from Classical Mechanics, expressions $(2.12,2.13)$ are built on action integrals for all possible paths, not only for the classical path. Situations which are well described classically will be distinguished through the property that the classical path gives the dominant, actually often essentially exclusive, contribution to the path integral (2.12, 2.13). However, for microscopic particles like the electron this is by no means the case, i.e., for the electron many paths contribute and the action integrals for non-classical paths need to be known.

The constant $\hbar$ given in (2.14) has the same dimension as the action integral $S[\vec{r}(t)]$. Its value is extremely small in comparision with typical values for action integrals of macroscopic particles. However, it is comparable to action integrals as they arise for microscopic particles under typical circumstances. To show this we consider the value of the action integral for a particle of mass $m=1 \mathrm{~g}$ moving over a distance of $1 \mathrm{~cm} / \mathrm{s}$ in a time period of 1 s . The value of $S[\vec{r}(t)]$ is then

$$
\begin{equation*}
S_{c l}=\frac{1}{2} m v^{2} t=\frac{1}{2} \operatorname{ergs} \tag{2.15}
\end{equation*}
$$

The exponent of $(2.12)$ is then $S_{c l} / \hbar \approx 0.5 \cdot 10^{27}$, i.e., a very large number. Since this number is multiplied by 'i', the exponent is a very large imaginary number. Any variations of $S_{c l}$ would then lead to strong oscillations of the contributions $\exp \left(\frac{i}{\hbar} S\right)$ to the path integral and one can expect destructive interference betwen these contributions. Only for paths close to the classical path is such interference ruled out, namely due to the property of the classical path to be an extremal of the action integral. This implies that small variations of the path near the classical path alter the value of the action integral by very little, such that destructive interference of the contributions of such paths does not occur.
The situation is very different for microscopic particles. In case of a proton with mass $m=$ $1.6725 \cdot 10^{-24} \mathrm{~g}$ moving over a distance of $1 \AA$ in a time period of $10^{-14} \mathrm{~s}$ the value of $S[\vec{r}(t)]$ is $S_{c l} \approx 10^{-26} \mathrm{erg}$ s and, accordingly, $S_{c l} / \hbar \approx 8$. This number is much smaller than the one for the macroscopic particle considered above and one expects that variations of the exponent of $\Phi[\vec{r}(t)]$ are of the order of unity for protons. One would still expect significant descructive interference between contributions of different paths since the value calculated is comparable to $2 \pi$. However, interferences should be much less dramatic than in case of the macroscopic particle.

### 2.3 How to Evaluate the Path Integral

In this section we will provide an explicit algorithm which defines the path integral (2.12, 2.13) and, at the same time, provides an avenue to evaluate path integrals. For the sake of simplicity we will consider the case of particles moving in one dimension labelled by the position coordinate $x$. The particles have associated with them a Lagrangian

$$
\begin{equation*}
L(x, \dot{x}, t)=\frac{1}{2} m \dot{x}^{2}-U(x) . \tag{2.16}
\end{equation*}
$$

In order to define the path integral we assume, as in (2.9), a series of times $t_{N}>t_{N-1}>t_{N-2}>$ $\ldots>t_{1}>t_{0}$ letting $N$ go to infinity later. The spacings between the times $t_{j+1}$ and $t_{j}$ will all be identical, namely

$$
\begin{equation*}
t_{j+1}-t_{j}=\left(t_{N}-t_{0}\right) / N=\epsilon_{N} . \tag{2.17}
\end{equation*}
$$

The discretization in time leads to a discretization of the paths $x(t)$ which will be represented through the series of space-time points

$$
\begin{equation*}
\left\{\left(x_{0}, t_{0}\right),\left(x_{1}, t_{1}\right), \ldots\left(x_{N-1}, t_{N-1}\right),\left(x_{N}, t_{N}\right)\right\} \tag{2.18}
\end{equation*}
$$

The time instances are fixed, however, the $x_{j}$ values are not. They can be anywhere in the allowed volume which we will choose to be the interval $]-\infty, \infty$. In passing from one space-time instance $\left(x_{j}, t_{j}\right)$ to the next $\left(x_{j+1}, t_{j+1}\right)$ we assume that kinetic energy and potential energy are constant, namely $\frac{1}{2} m\left(x_{j+1}-x_{j}\right)^{2} / \epsilon_{N}^{2}$ and $U\left(x_{j}\right)$, respectively. These assumptions lead then to the following Riemann form for the action integral

$$
\begin{equation*}
S[x(t)]=\lim _{N \rightarrow \infty} \epsilon_{N} \sum_{j=0}^{N-1}\left(\frac{1}{2} m \frac{\left(x_{j+1}-x_{j}\right)^{2}}{\epsilon_{N}^{2}}-U\left(x_{j}\right)\right) . \tag{2.19}
\end{equation*}
$$

The main idea is that one can replace the path integral now by a multiple integral over $x_{1}, x_{2}$, etc. This allows us to write the evolution operator using (2.10) and (2.12)

$$
\begin{gather*}
\phi\left(x_{N}, t_{N} \mid x_{0}, t_{0}\right)=\lim _{N \rightarrow \infty} C_{N} \int_{-\infty}^{+\infty} d x_{1} \int_{-\infty}^{+\infty} d x_{2} \ldots \int_{-\infty}^{+\infty} d x_{N-1} \\
\exp \left\{\frac{i}{\hbar} \epsilon_{N} \sum_{j=0}^{N-1}\left[\frac{1}{2} m \frac{\left(x_{j+1}-x_{j}\right)^{2}}{\epsilon_{N}^{2}}-U\left(x_{j}\right)\right]\right\} . \tag{2.20}
\end{gather*}
$$

Here, $C_{N}$ is a constant which depends on $N$ (actually also on other constant in the exponent) which needs to be chosen to ascertain that the limit in (2.20) can be properly taken. Its value is

$$
\begin{equation*}
C_{N}=\left[\frac{m}{2 \pi i \hbar \epsilon_{N}}\right]^{\frac{N}{2}} \tag{2.21}
\end{equation*}
$$

### 2.4 Propagator for a Free Particle

As a first example we will evaluate the path integral for a free particle following the algorithm introduced above.

Rather then using the integration variables $x_{j}$, it is more suitable to define new integration variables $y_{j}$, the origin of which coincides with the classical path of the particle. To see the benifit of such approach we define a path $y(t)$ as follows

$$
\begin{equation*}
x(t)=x_{c l}(t)+y(t) \tag{2.22}
\end{equation*}
$$

where $x_{c l}(t)$ is the classical path which connects the space-time points $\left(x_{0}, t_{0}\right)$ and $\left(x_{N}, t_{N}\right)$, namely,

$$
\begin{equation*}
x_{c l}(t)=x_{0}+\frac{x_{N}-x_{0}}{t_{N}-t_{0}}\left(t-t_{0}\right) . \tag{2.23}
\end{equation*}
$$

It is essential for the following to note that, since $x\left(t_{0}\right)=x_{c l}\left(t_{0}\right)=x_{0}$ and $x\left(t_{N}\right)=x_{c l}\left(t_{N}\right)=x_{N}$, it holds

$$
\begin{equation*}
y\left(t_{0}\right)=y\left(t_{N}\right)=0 \tag{2.24}
\end{equation*}
$$

Also we use the fact that the velocity of the classical path $\dot{x}_{c l}=\left(x_{N}-x_{0}\right) /\left(t_{n}-t_{0}\right)$ is constant. The action integral ${ }^{1} S\left[x(t) \mid x\left(t_{0}\right)=x_{0}, x\left(t_{N}\right)=x_{N}\right]$ for any path $x(t)$ can then be expressed through an action integral over the path $y(t)$ relative to the classical path. One obtains

$$
\begin{gather*}
S\left[x(t) \mid x\left(t_{0}\right)=x_{0}, x\left(t_{N}\right)=x_{N}\right]=\int_{t_{0}}^{t_{N}} d t \frac{1}{2} m\left(\dot{x}_{c l}^{2}+2 \dot{x}_{c l} \dot{y}+\dot{y}^{2}\right)= \\
\int_{t_{0}}^{t_{N}} d t \frac{1}{2} m \dot{x}_{c l}^{2}+m \dot{x}_{c l} \int_{t_{0}}^{t_{N}} d t \dot{y}+\int_{t_{0}}^{t_{N}} d t \frac{1}{2} m \dot{y}^{2} . \tag{2.25}
\end{gather*}
$$

The condition (2.24) implies for the second term on the r.h.s.

$$
\begin{equation*}
\int_{t_{0}}^{t_{N}} d t \dot{y}=y\left(t_{N}\right)-y\left(t_{0}\right)=0 \tag{2.26}
\end{equation*}
$$

The first term on the r.h.s. of (2.25) is, using (2.23),

$$
\begin{equation*}
\int_{t_{0}}^{t_{N}} d t \frac{1}{2} m \dot{x}_{c l}^{2}=\frac{1}{2} m \frac{\left(x_{N}-x_{0}\right)^{2}}{t_{N}-t_{0}} \tag{2.27}
\end{equation*}
$$

The third term can be written in the notation introduced

$$
\begin{equation*}
\int_{t_{0}}^{t_{N}} d t \frac{1}{2} m \dot{y}^{2}=S\left[x(t) \mid x\left(t_{0}\right)=0, x\left(t_{N}\right)=0\right] \tag{2.28}
\end{equation*}
$$

i.e., due to (2.24), can be expressed through a path integral with endpoints $x\left(t_{0}\right)=0, x\left(t_{N}\right)=0$. The resulting expression for $S\left[x(t) \mid x\left(t_{0}\right)=x_{0}, x\left(t_{N}\right)=x_{N}\right]$ is

$$
\begin{align*}
S\left[x(t) \mid x\left(t_{0}\right)=x_{0}, x\left(t_{N}\right)=x_{N}\right] & =\frac{1}{2} m \frac{\left(x_{N}-x_{0}\right)^{2}}{t_{N}-t_{0}}+0+  \tag{2.29}\\
& +S\left[x(t) \mid x\left(t_{0}\right)=0, x\left(t_{N}\right)=0\right] .
\end{align*}
$$

This expression corresponds to the action integral in (2.13). Inserting the result into (2.10, 2.12) yields

$$
\begin{equation*}
\phi\left(x_{N}, t_{N} \mid x_{0}, t_{0}\right)=\exp \left[\frac{i m}{2 \hbar} \frac{\left(x_{N}-x_{0}\right)^{2}}{t_{N}-t_{0}}\right] \iint_{x\left(t_{0}\right)=0}^{x\left(t_{N}\right)=0} d[x(t)] \exp \left\{\frac{i}{\hbar} S[x(t)]\right\} \tag{2.30}
\end{equation*}
$$

a result, which can also be written

$$
\begin{equation*}
\phi\left(x_{N}, t_{N} \mid x_{0}, t_{0}\right)=\exp \left[\frac{i m}{2 \hbar} \frac{\left(x_{N}-x_{0}\right)^{2}}{t_{N}-t_{0}}\right] \phi\left(0, t_{N} \mid 0, t_{0}\right) \tag{2.31}
\end{equation*}
$$

[^0]
## Evaluation of the necessary path integral

To determine the propagator (2.31) for a free particle one needs to evaluate the following path integral

$$
\begin{gather*}
\phi\left(0, t_{N} \mid 0, t_{0}\right)=\lim _{N \rightarrow \infty}\left[\frac{m}{2 \pi i \hbar \epsilon_{N}}\right]^{\frac{N}{2}} \times \\
\times \int_{-\infty}^{+\infty} d y_{1} \cdots \int_{-\infty}^{+\infty} d y_{N-1} \exp \left[\frac{i}{\hbar} \epsilon_{N} \sum_{j=0}^{N-1} \frac{1}{2} m \frac{\left(y_{j+1}-y_{j}\right)^{2}}{\epsilon_{N}^{2}}\right] \tag{2.32}
\end{gather*}
$$

The exponent $E$ can be written, noting $y_{0}=y_{N}=0$, as the quadratic form

$$
\begin{align*}
E & =\frac{i m}{2 \hbar \epsilon_{N}}\left(2 y_{1}^{2}-y_{1} y_{2}-y_{2} y_{1}+2 y_{2}^{2}-y_{2} y_{3}-y_{3} y_{2}\right. \\
& \left.+2 y_{3}^{2}-\cdots-y_{N-2} y_{N-1}-y_{N-1} y_{N-2}+2 y_{N-1}^{2}\right) \\
& =i \sum_{j, k=1}^{N-1} y_{j} a_{j k} y_{k} \tag{2.33}
\end{align*}
$$

where $a_{j k}$ are the elements of the following symmetric $(N-1) \times(N-1)$ matrix

$$
\left(a_{j k}\right)=\frac{m}{2 \hbar \epsilon_{N}}\left(\begin{array}{rrrrrr}
2 & -1 & 0 & \ldots & 0 & 0  \tag{2.34}\\
-1 & 2 & -1 & \ldots & 0 & 0 \\
0 & -1 & 2 & \ldots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & 2 & -1 \\
0 & 0 & 0 & & -1 & 2
\end{array}\right)
$$

The following integral

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d y_{1} \cdots \int_{-\infty}^{+\infty} d y_{N-1} \exp \left(i \sum_{j, k=1}^{N-1} y_{j} a_{j k} y_{k}\right) \tag{2.35}
\end{equation*}
$$

must be determined. In the appendix we prove

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d y_{1} \cdots \int_{-\infty}^{+\infty} d y_{N-1} \exp \left(i \sum_{j, k=1}^{d} y_{j} b_{j k} y_{k}\right)=\left[\frac{(i \pi)^{d}}{\operatorname{det}\left(b_{j k}\right)}\right]^{\frac{1}{2}} . \tag{2.36}
\end{equation*}
$$

which holds for a $d$-dimensional, real, symmetric matrix $\left(b_{j k}\right)$ and $\operatorname{det}\left(b_{j k}\right) \neq 0$.
In order to complete the evaluation of (2.32) we split off the factor $\frac{m}{2 \hbar \epsilon_{N}}$ in the definition (2.34) of $\left(a_{j k}\right)$ defining a new matrix $\left(A_{j k}\right)$ through

$$
\begin{equation*}
a_{j k}=\frac{m}{2 \hbar \epsilon_{N}} A_{j k} . \tag{2.37}
\end{equation*}
$$

Using

$$
\begin{equation*}
\operatorname{det}\left(a_{j k}\right)=\left[\frac{m}{2 \hbar \epsilon_{N}}\right]^{N-1} \operatorname{det}\left(A_{j k}\right), \tag{2.38}
\end{equation*}
$$

a property which follows from $\operatorname{det}(c \mathbf{B})=c^{n} \operatorname{det} \mathbf{B}$ for any $n \times n$ matrix $\mathbf{B}$, we obtain

$$
\begin{equation*}
\phi\left(0, t_{N} \mid 0, t_{0}\right)=\lim _{N \rightarrow \infty}\left[\frac{m}{2 \pi i \hbar \epsilon_{N}}\right]^{\frac{N}{2}}\left[\frac{2 \pi i \hbar \epsilon_{N}}{m}\right]^{\frac{N-1}{2}} \frac{1}{\sqrt{\operatorname{det}\left(A_{j k}\right)}} \tag{2.39}
\end{equation*}
$$

In order to determine $\operatorname{det}\left(A_{j k}\right)$ we consider the dimension $n$ of $\left(A_{j k}\right)$, presently $N-1$, variable, let say $n, n=1,2, \ldots$ We seek then to evaluate the determinant of the $n \times n$ matrix

$$
D_{n}=\left|\left(\begin{array}{rrrrrr}
2 & -1 & 0 & \ldots & 0 & 0  \tag{2.40}\\
-1 & 2 & -1 & \ldots & 0 & 0 \\
0 & -1 & 2 & \ldots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & 2 & -1 \\
0 & 0 & 0 & & -1 & 2
\end{array}\right)\right|
$$

For this purpose we expand (2.40) in terms of subdeterminants along the last column. One can readily verify that this procedure leads to the following recursion equation for the determinants

$$
\begin{equation*}
D_{n}=2 D_{n-1}-D_{n-2} \tag{2.41}
\end{equation*}
$$

To solve this three term recursion relationship one needs two starting values. Using

$$
D_{1}=|(2)|=2 ; \quad D_{2}=\left|\left(\begin{array}{rr}
2 & -1  \tag{2.42}\\
-1 & 2
\end{array}\right)\right|=3
$$

one can readily verify

$$
\begin{equation*}
D_{n}=n+1 \tag{2.43}
\end{equation*}
$$

We like to note here for further use below that one might as well employ the 'artificial' starting values $D_{0}=1, D_{1}=2$ and obtain from (2.41) the same result for $D_{2}, D_{3}, \ldots$.
Our derivation has provided us with the value $\operatorname{det}\left(A_{j k}\right)=N$. Inserting this into (2.39) yields

$$
\begin{equation*}
\phi\left(0, t_{N} \mid 0, t_{0}\right)=\lim _{N \rightarrow \infty}\left[\frac{m}{2 \pi i \hbar \epsilon_{N} N}\right]^{\frac{1}{2}} \tag{2.44}
\end{equation*}
$$

and with $\epsilon_{N} N=t_{N}-t_{0}$, which follows from (2.18) we obtain

$$
\begin{equation*}
\phi\left(0, t_{N} \mid 0, t_{0}\right)=\left[\frac{m}{2 \pi i \hbar\left(t_{N}-t_{0}\right)}\right]^{\frac{1}{2}} \tag{2.45}
\end{equation*}
$$

## Expressions for Free Particle Propagator

We have now collected all pieces for the final expression of the propagator (2.31) and obtain, defining $t=t_{N}, x=x_{N}$

$$
\begin{equation*}
\phi\left(x, t \mid x_{0}, t_{0}\right)=\left[\frac{m}{2 \pi i \hbar\left(t-t_{0}\right)}\right]^{\frac{1}{2}} \exp \left[\frac{i m}{2 \hbar} \frac{\left(x-x_{0}\right)^{2}}{t-t_{0}}\right] \tag{2.46}
\end{equation*}
$$

This propagator, according to (2.5) allows us to predict the time evolution of any state function $\psi(x, t)$ of a free particle. Below we will apply this to a particle at rest and a particle forming a so-called wave packet.
The result (2.46) can be generalized to three dimensions in a rather obvious way. One obtains then for the propagator (2.10)

$$
\begin{equation*}
\phi\left(\vec{r}, t \mid \vec{r}_{0}, t_{0}\right)=\left[\frac{m}{2 \pi i \hbar\left(t-t_{0}\right)}\right]^{\frac{3}{2}} \exp \left[\frac{i m}{2 \hbar} \frac{\left(\vec{r}-\vec{r}_{0}\right)^{2}}{t-t_{0}}\right] \tag{2.47}
\end{equation*}
$$

## One-Dimensional Free Particle Described by Wave Packet

We assume a particle at time $t=t_{o}=0$ is described by the wave function

$$
\begin{equation*}
\psi\left(x_{0}, t_{0}\right)=\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{4}} \exp \left(-\frac{x_{0}^{2}}{2 \delta^{2}}+i \frac{p_{o}}{\hbar} x\right) \tag{2.48}
\end{equation*}
$$

Obviously, the associated probability distribution

$$
\begin{equation*}
\left|\psi\left(x_{0}, t_{0}\right)\right|^{2}=\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{2}} \exp \left(-\frac{x_{0}^{2}}{\delta^{2}}\right) \tag{2.49}
\end{equation*}
$$

is Gaussian of width $\delta$, centered around $x_{0}=0$, and describes a single particle since

$$
\begin{equation*}
\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{2}} \int_{-\infty}^{+\infty} d x_{0} \exp \left(-\frac{x_{0}^{2}}{\delta^{2}}\right)=1 . \tag{2.50}
\end{equation*}
$$

One refers to such states as wave packets. We want to apply axiom (2.5) to (2.48) as the initial state using the propagator (2.46).
We will obtain, thereby, the wave function of the particle at later times. We need to evaluate for this purpose the integral

$$
\begin{align*}
\psi(x, t)= & {\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{4}}\left[\frac{m}{2 \pi i \hbar t}\right]^{\frac{1}{2}} } \\
& \int_{-\infty}^{+\infty} d x_{0} \exp \underbrace{\left[\frac{i m}{2 \hbar} \frac{\left(x-x_{0}\right)^{2}}{t}-\frac{x_{0}^{2}}{2 \delta^{2}}+i \frac{p_{o}}{\hbar} x_{o}\right]}_{E_{o}\left(x_{o}, x\right)+E(x)} \tag{2.51}
\end{align*}
$$

For this evaluation we adopt the strategy of combining in the exponential the terms quadratic $\left(\sim x_{0}^{2}\right)$ and linear $\left(\sim x_{0}\right)$ in the integration variable to a complete square

$$
\begin{equation*}
a x_{0}^{2}+2 b x_{0}=a\left(x_{0}+\frac{b}{a}\right)^{2}-\frac{b^{2}}{a} \tag{2.52}
\end{equation*}
$$

and applying (2.247).
We devide the contributions to the exponent $E_{o}\left(x_{o}, x\right)+E(x)$ in (2.51) as follows

$$
\begin{equation*}
E_{o}\left(x_{o}, x\right)=\frac{i m}{2 \hbar t}\left[x_{o}^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)-2 x_{o}\left(x-\frac{p_{o}}{m} t\right)+f(x)\right] \tag{2.53}
\end{equation*}
$$

$$
\begin{equation*}
E(x)=\frac{i m}{2 \hbar t}\left[x^{2}-f(x)\right] \tag{2.54}
\end{equation*}
$$

One chooses then $f(x)$ to complete, according to (2.52), the square in (2.53)

$$
\begin{equation*}
f(x)=\left(\frac{x-\frac{p_{o}}{m} t}{\sqrt{1+i \frac{\hbar t}{m \delta^{2}}}}\right)^{2} \tag{2.55}
\end{equation*}
$$

This yields

$$
\begin{equation*}
E_{o}\left(x_{o}, x\right)=\frac{i m}{2 \hbar t}\left(x_{o} \sqrt{1+i \frac{\hbar t}{m \delta^{2}}}-\frac{x-\frac{p_{o}}{m} t}{\sqrt{1+i \frac{\hbar t}{m \delta^{2}}}}\right)^{2} \tag{2.56}
\end{equation*}
$$

One can write then (2.51)

$$
\begin{equation*}
\psi(x, t)=\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{4}}\left[\frac{m}{2 \pi i \hbar t}\right]^{\frac{1}{2}} e^{E(x)} \int_{-\infty}^{+\infty} d x_{0} e^{E_{o}\left(x_{o}, x\right)} \tag{2.57}
\end{equation*}
$$

and needs to determine the integral

$$
\begin{align*}
I & =\int_{-\infty}^{+\infty} d x_{0} e^{E_{o}\left(x_{o}, x\right)} \\
& =\int_{-\infty}^{+\infty} d x_{0} \exp \left[\frac{i m}{2 \hbar t}\left(x_{o} \sqrt{1+i \frac{\hbar t}{m \delta^{2}}}-\frac{x-\frac{p_{o}}{m} t}{\sqrt{1+i \frac{\hbar t}{m \delta^{2}}}}\right)^{2}\right] \\
& =\int_{-\infty}^{+\infty} d x_{0} \exp \left[\frac{i m}{2 \hbar t}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)\left(x_{o}-\frac{x-\frac{p_{o}}{m} t}{1+i \frac{\hbar t}{m \delta^{2}}}\right)^{2}\right] \tag{2.58}
\end{align*}
$$

The integrand is an analytical function everywhere in the complex plane and we can alter the integration path, making certain, however, that the new path does not lead to additional contributions to the integral.
We proceed as follows. We consider a transformation to a new integration variable $\rho$ defined through

$$
\begin{equation*}
\sqrt{i\left(1-i \frac{\hbar t}{m \delta^{2}}\right)} \rho=x_{0}-\frac{x-\frac{p_{o}}{m} t}{1+i \frac{\hbar t}{m \delta^{2}}} \tag{2.59}
\end{equation*}
$$

An integration path in the complex $x_{0}$-plane along the direction

$$
\begin{equation*}
\sqrt{i\left(1-i \frac{\hbar t}{m \delta^{2}}\right)} \tag{2.60}
\end{equation*}
$$

is then represented by real $\rho$ values. The beginning and the end of such path are the points

$$
\begin{equation*}
z_{1}^{\prime}=-\infty \times \sqrt{i\left(1-i \frac{\hbar t}{m \delta^{2}}\right)}, \quad z_{2}^{\prime}=+\infty \times \sqrt{i\left(1-i \frac{\hbar t}{m \delta^{2}}\right)} \tag{2.61}
\end{equation*}
$$

whereas the original path in (2.58) has the end points

$$
\begin{equation*}
z_{1}=-\infty, \quad z_{2}=+\infty \tag{2.62}
\end{equation*}
$$

If one can show that an integration of (2.58) along the path $z_{1} \rightarrow z_{1}^{\prime}$ and along the path $z_{2} \rightarrow z_{2}^{\prime}$ gives only vanishing contributions one can replace (2.58) by

$$
\begin{equation*}
I=\sqrt{i\left(1-i \frac{\hbar t}{m \delta^{2}}\right)} \int_{-\infty}^{+\infty} d \rho \exp \left[-\frac{m}{2 \hbar t}\left(1+\left(\frac{\hbar t}{m \delta^{2}}\right)^{2}\right) \rho^{2}\right] \tag{2.63}
\end{equation*}
$$

which can be readily evaluated. In fact, one can show that $z_{1}^{\prime}$ lies at $-\infty-i \times \infty$ and $z_{2}^{\prime}$ at $+\infty+i \times \infty$. Hence, the paths between $z_{1} \rightarrow z_{1}^{\prime}$ and $z_{2} \rightarrow z_{2}^{\prime}$ have a real part of $x_{0}$ of $\pm \infty$. Since the exponent in (2.58) has a leading contribution in $x_{0}$ of $-x_{0}^{2} / \delta^{2}$ the integrand of (2.58) vanishes for $R e x_{0} \rightarrow \pm \infty$. We can conclude then that (2.63) holds and, accordingly,

$$
\begin{equation*}
I=\sqrt{\frac{2 \pi i \hbar t}{m\left(1+i \frac{\hbar t}{m \delta^{2}}\right)}} . \tag{2.64}
\end{equation*}
$$

Equation (2.57) reads then

$$
\begin{equation*}
\psi(x, t)=\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{4}}\left[\frac{1}{1+i \frac{\hbar t}{m \delta^{2}}}\right]^{\frac{1}{2}} \exp [E(x)] \tag{2.65}
\end{equation*}
$$

Seperating the phase factor

$$
\begin{equation*}
\left[\frac{1-i \frac{\hbar t}{m \delta^{2}}}{1+i \frac{\hbar t}{m \delta^{2}}}\right]^{\frac{1}{4}} \tag{2.66}
\end{equation*}
$$

yields

$$
\begin{equation*}
\psi(x, t)=\left[\frac{1-i \frac{\hbar t}{m \delta^{2}}}{1+i \frac{\hbar t}{m \delta^{2}}}\right]^{\frac{1}{4}}\left[\frac{1}{\pi \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right]^{\frac{1}{4}} \exp [E(x)] \tag{2.67}
\end{equation*}
$$

We need to determine finally (2.54) using (2.55). One obtains

$$
\begin{equation*}
E(x)=-\frac{x^{2}}{2 \delta^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)}+\frac{i \frac{p_{o}}{\hbar} x}{1+i \frac{\hbar t}{m \delta^{2}}}-\frac{\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m} t}{1+i \frac{\hbar t}{m \delta^{2}}} \tag{2.68}
\end{equation*}
$$

and, using

$$
\begin{equation*}
\frac{a}{1+b}=a-\frac{a b}{1+b}, \tag{2.69}
\end{equation*}
$$

finally

$$
\begin{equation*}
E(x)=-\frac{\left(x-\frac{p_{o}}{m} t\right)^{2}}{2 \delta^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)}+i \frac{p_{o}}{\hbar} x-\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m} t \tag{2.70}
\end{equation*}
$$

which inserted in (2.67) provides the complete expression of the wave function at all times $t$

$$
\begin{align*}
\psi(x, t)= & {\left[\frac{1-i \frac{\hbar t}{m \delta^{2}}}{1+i \frac{\hbar t}{m \delta^{2}}}\right]^{\frac{1}{4}}\left[\frac{1}{\pi \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right]^{\frac{1}{4}} \times }  \tag{2.71}\\
& \times \exp \left[-\frac{\left(x-\frac{p_{o}}{m} t\right)^{2}}{2 \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\left(1-i \frac{\hbar t}{m \delta^{2}}\right)+i \frac{p_{o}}{\hbar} x-\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m} t\right]
\end{align*}
$$

The corresponding probability distribution is

$$
\begin{equation*}
|\psi(x, t)|^{2}=\left[\frac{1}{\pi \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right]^{\frac{1}{2}} \exp \left[-\frac{\left(x-\frac{p_{o}}{m} t\right)^{2}}{\delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right] \tag{2.72}
\end{equation*}
$$

## Comparision of Moving Wave Packet with Classical Motion

It is revealing to compare the probability distributions (2.49), (2.72) for the initial state (2.48) and for the final state (2.71), respectively. The center of the distribution (2.72) moves in the direction of the positive $x$-axis with velocity $v_{o}=p_{o} / m$ which identifies $p_{o}$ as the momentum of the particle. The width of the distribution (2.72)

$$
\begin{equation*}
\delta \sqrt{1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}} \tag{2.73}
\end{equation*}
$$

increases with time, coinciding at $t=0$ with the width of the initial distribution (2.49). This 'spreading' of the wave function is a genuine quantum phenomenon. Another interesting observation is that the wave function $(2.71)$ conserves the phase factor $\exp \left[i\left(p_{o} / \hbar\right) x\right]$ of the original wave function (2.48) and that the respective phase factor is related with the velocity of the classical particle and of the center of the distribution (2.72). The conservation of this factor is particularly striking for the (unnormalized) initial wave function

$$
\begin{equation*}
\psi\left(x_{0}, t_{0}\right)=\exp \left(i \frac{p_{o}}{m} x_{o}\right) \tag{2.74}
\end{equation*}
$$

which corresponds to (2.48) for $\delta \rightarrow \infty$. In this case holds

$$
\begin{equation*}
\psi(x, t)=\exp \left(i \frac{p_{o}}{m} x-\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m} t\right) \tag{2.75}
\end{equation*}
$$

i.e., the spatial dependence of the initial state (2.74) remains invariant in time. However, a timedependent phase factor $\exp \left[-\frac{i}{\hbar}\left(p_{o}^{2} / 2 m\right) t\right]$ arises which is related to the energy $\epsilon=p_{o}^{2} / 2 m$ of a particle with momentum $p_{o}$. We had assumed above [c.f. (2.48)] $t_{o}=0$. the case of arbitrary $t_{o}$ is recovered iby replacing $t \rightarrow t_{o}$ in (2.71, 2.72). This yields, instead of (2.75)

$$
\begin{equation*}
\psi(x, t)=\exp \left(i \frac{p_{o}}{m} x-\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m}\left(t-t_{o}\right)\right) \tag{2.76}
\end{equation*}
$$

From this we conclude that an initial wave function

$$
\begin{equation*}
\psi\left(x_{o}, t_{0}\right)=\exp \left(i \frac{p_{o}}{m} x_{o}-\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m} t_{o}\right) \tag{2.77}
\end{equation*}
$$

becomes at $t>t_{o}$

$$
\begin{equation*}
\psi(x, t)=\exp \left(i \frac{p_{o}}{m} x-\frac{i}{\hbar} \frac{p_{o}^{2}}{2 m} t\right) \tag{2.78}
\end{equation*}
$$

i.e., the spatial as well as the temporal dependence of the wave function remains invariant in this case. One refers to the respective states as stationary states. Such states play a cardinal role in quantum mechanics.

### 2.5 Propagator for a Quadratic Lagrangian

We will now determine the propagator $(2.10,2.12,2.13)$

$$
\begin{equation*}
\phi\left(x_{N}, t_{N} \mid x_{0}, t_{0}\right)=\iiint_{x\left(t_{0}\right)=x_{0}}^{x\left(t_{N}\right)=x_{N}} d[x(t)] \exp \left\{\frac{i}{\hbar} S[x(t)]\right\} \tag{2.79}
\end{equation*}
$$

for a quadratic Lagrangian

$$
\begin{equation*}
L(x, \dot{x}, t)=\frac{1}{2} m \dot{x}^{2}-\frac{1}{2} c(t) x^{2}-e(t) x . \tag{2.80}
\end{equation*}
$$

For this purpose we need to determine the action integral

$$
\begin{equation*}
S[x(t)]=\int_{t_{0}}^{t_{N}} d t^{\prime} L(x, \dot{x}, t) \tag{2.81}
\end{equation*}
$$

for an arbitrary path $x(t)$ with end points $x\left(t_{0}\right)=x_{0}$ and $x\left(t_{N}\right)=x_{N}$. In order to simplify this task we define again a new path $y(t)$

$$
\begin{equation*}
x(t)=x_{c l}(t)+y(t) \tag{2.82}
\end{equation*}
$$

which describes the deviation from the classical path $x_{c l}(t)$ with end points $x_{c l}\left(t_{0}\right)=x_{0}$ and $x_{c l}\left(t_{N}\right)=x_{N}$. Obviously, the end points of $y(t)$ are

$$
\begin{equation*}
y\left(t_{0}\right)=0 \quad ; \quad y\left(t_{N}\right)=0 . \tag{2.83}
\end{equation*}
$$

Inserting (2.80) into (2.82) one obtains

$$
\begin{equation*}
L\left(x_{c l}+y, \dot{x}_{c l}+\dot{y}(t), t\right)=L\left(x_{c l}, \dot{x}_{c l}, t\right)+L^{\prime}(y, \dot{y}(t), t)+\delta L \tag{2.84}
\end{equation*}
$$

where

$$
\begin{align*}
L\left(x_{c l}, \dot{x}_{c l}, t\right) & =\frac{1}{2} m \dot{x}_{c l}^{2}-\frac{1}{2} c(t) x_{c l}^{2}-e(t) x_{c l} \\
L^{\prime}(y, \dot{y}(t), t) & =\frac{1}{2} m \dot{y}^{2}-\frac{1}{2} c(t) y^{2} \\
\delta L & =m \dot{x}_{c l} \dot{y}(t)-c(t) x_{c l} y-e(t) y . \tag{2.85}
\end{align*}
$$

We want to show now that the contribution of $\delta L$ to the action integral (2.81) vanishes ${ }^{2}$. For this purpose we use

$$
\begin{equation*}
\dot{x}_{c l} \dot{y}=\frac{d}{d t}\left(\dot{x}_{c l} y\right)-\ddot{x}_{c l} y \tag{2.86}
\end{equation*}
$$

[^1]and obtain
\[

$$
\begin{equation*}
\int_{t_{0}}^{t_{N}} d t \delta L=\left.m\left[\dot{x}_{c l} y\right]\right|_{t_{0}} ^{N^{N}}-\int_{t_{0}}^{t_{N}} d t\left[m \ddot{x}_{c l}(t)+c(t) x_{c l}(t)+e(t)\right] y(t) . \tag{2.87}
\end{equation*}
$$

\]

According to (2.83) the first term on the r.h.s. vanishes. Applying the Euler-Lagrange conditions (1.24) to the Lagrangian (2.80) yields for the classical path

$$
\begin{equation*}
m \ddot{x}_{c l}+c(t) x_{c l}+e(t)=0 \tag{2.88}
\end{equation*}
$$

and, hence, also the second contribution on the r.h.s. of (2.88) vanishes. One can then express the propagator (2.79)

$$
\begin{equation*}
\phi\left(x_{N}, t_{N} \mid x_{0}, t_{0}\right)=\exp \left\{\frac{i}{\hbar} S\left[x_{c l}(t)\right]\right\} \tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right) \tag{2.89}
\end{equation*}
$$

where

$$
\begin{equation*}
\tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right)=\iint_{y\left(t_{0}\right)=0}^{y\left(t_{N}\right)=0} d[y(t)] \exp \left\{\frac{i}{\hbar} \int_{t_{0}}^{t_{N}} d t L^{\prime}(y, \dot{y}, t)\right\} . \tag{2.90}
\end{equation*}
$$

## Evaluation of the Necessary Path Integral

We have achieved for the quadratic Lagrangian a separation in terms of a classical action integral and a propagator connecting the end points $y\left(t_{0}\right)=0$ and $y\left(t_{N}\right)=0$ which is analogue to the result (2.31) for the free particle propagator. For the evaluation of $\tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right)$ we will adopt a strategy which is similar to that used for the evaluation of (2.32). The discretization scheme adopted above yields in the present case

$$
\begin{gather*}
\tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right)=\lim _{N \rightarrow \infty}\left[\frac{m}{2 \pi i \hbar \epsilon_{N}}\right]^{\frac{N}{2}} \times  \tag{2.91}\\
\times \int_{-\infty}^{+\infty} d y_{1} \cdots \int_{-\infty}^{+\infty} d y_{N-1} \exp \left[\frac{i}{\hbar} \epsilon_{N} \sum_{j=0}^{N-1}\left(\frac{1}{2} m \frac{\left(y_{j+1}-y_{j}\right)^{2}}{\epsilon_{N}^{2}}-\frac{1}{2} c_{j} y_{j}^{2}\right)\right]
\end{gather*}
$$

where $c_{j}=c\left(t_{j}\right), t_{j}=t_{0}+\epsilon_{N} j$. One can express the exponent $E$ in (2.91) through the quadratic form

$$
\begin{equation*}
E=i \sum_{j, k=1}^{N-1} y_{j} a_{j k} y_{k} \tag{2.92}
\end{equation*}
$$

where $a_{j k}$ are the elements of the following $(N-1) \times(N-1)$ matrix

$$
\begin{align*}
\left(a_{j k}\right) & =\frac{m}{2 \hbar \epsilon_{N}}\left(\begin{array}{rrrrrr}
2 & -1 & 0 & \ldots & 0 & 0 \\
-1 & 2 & -1 & \cdots & 0 & 0 \\
0 & -1 & 2 & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & 2 & -1 \\
0 & 0 & 0 & & -1 & 2
\end{array}\right) \\
& -\frac{\epsilon_{N}}{2 \hbar}\left(\begin{array}{rrrrrr}
c_{1} & 0 & 0 & \ldots & 0 & 0 \\
0 & c_{2} & 0 & \cdots & 0 & 0 \\
0 & 0 & c_{3} & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \ldots & c_{N-2} & 0 \\
0 & 0 & 0 & & 0 & c_{N-1}
\end{array}\right) \tag{2.93}
\end{align*}
$$

In case $\operatorname{det}\left(a_{j k}\right) \neq 0$ one can express the multiple integral in (2.91) according to (2.36) as follows

$$
\begin{align*}
\tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right) & =\lim _{N \rightarrow \infty}\left[\frac{m}{2 \pi i \hbar \epsilon_{N}}\right]^{\frac{N}{2}}\left[\frac{(i \pi)^{N-1}}{\operatorname{det}(\mathbf{a})}\right]^{\frac{1}{2}} \\
& =\lim _{N \rightarrow \infty}\left[\frac{m}{2 \pi i \hbar} \frac{1}{\epsilon_{N}\left(\frac{2 \hbar \epsilon_{N}}{m}\right)^{N-1} \operatorname{det}(\mathbf{a})}\right]^{\frac{1}{2}} . \tag{2.94}
\end{align*}
$$

In order to determine $\tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right)$ we need to evaluate the function

$$
\begin{equation*}
f\left(t_{0}, t_{N}\right)=\lim _{N \rightarrow \infty}\left[\epsilon_{N}\left(\frac{2 \hbar \epsilon_{N}}{m}\right)^{N-1} \operatorname{det}(\mathbf{a})\right] . \tag{2.95}
\end{equation*}
$$

According to (2.93) holds

$$
\begin{gather*}
D_{N-1} \stackrel{\text { def }}{=}\left[\frac{2 \hbar \epsilon_{N}}{m}\right]^{N-1} \operatorname{det}(\mathbf{a})  \tag{2.96}\\
=\left|\left(\begin{array}{rrrrrr}
2-\frac{\epsilon_{N}^{2}}{m} c_{1} & -1 & 0 & \ldots & 0 & 0 \\
-1 & 2-\frac{\epsilon_{N}^{2}}{m} c_{2} & -1 & \ldots & 0 & 0 \\
0 & -1 & 2-\frac{\epsilon_{N}^{2}}{m} c_{3} & \ldots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \ldots & 2-\frac{\epsilon_{N}^{2}}{m} c_{N-2} & -1 \\
0 & 0 & 0 & & -1 & 2-\frac{\epsilon_{N}^{2}}{m} c_{N-1}
\end{array}\right)\right|
\end{gather*}
$$

In the following we will asume that the dimension $n=N-1$ of the matrix in (2.97) is variable. One can derive then for $D_{n}$ the recursion relationship

$$
\begin{equation*}
D_{n}=\left(2-\frac{\epsilon_{N}^{2}}{m} c_{n}\right) D_{n-1}-D_{n-2} \tag{2.97}
\end{equation*}
$$

using the well-known method of expanding a determinant in terms of the determinants of lower dimensional submatrices. Using the starting values [c.f. the comment below Eq. (2.43)]

$$
\begin{equation*}
D_{0}=1 ; \quad D_{1}=2-\frac{\epsilon_{N}^{2}}{m} c_{1} \tag{2.98}
\end{equation*}
$$

this recursion relationship can be employed to determine $D_{N-1}$. One can express (2.97) through the 2 nd order difference equation

$$
\begin{equation*}
\frac{D_{n+1}-2 D_{n}+D_{n-1}}{\epsilon_{N}^{2}}=-\frac{c_{n+1} D_{n}}{m} . \tag{2.99}
\end{equation*}
$$

Since we are interested in the solution of this equation in the limit of vanishing $\epsilon_{N}$ we may interpret (2.99) as a 2 nd order differential equation in the continuous variable $t=n \epsilon_{N}+t_{0}$

$$
\begin{equation*}
\frac{d^{2} f\left(t_{0}, t\right)}{d t^{2}}=-\frac{c(t)}{m} f\left(t_{0}, t\right) \tag{2.100}
\end{equation*}
$$

The boundary conditions at $t=t_{0}$, according to (2.98), are

$$
\begin{align*}
f\left(t_{0}, t_{0}\right) & =\epsilon_{N} D_{0}=0 \\
\left.\frac{d f\left(t_{0}, t\right)}{d t}\right|_{t=t_{0}} & =\epsilon_{N} \frac{D_{1}-D_{0}}{\epsilon_{N}}=2-\frac{\epsilon_{N}^{2}}{m} c_{1}-1=1 \tag{2.101}
\end{align*}
$$

We have then finally for the propagator (2.79)

$$
\begin{equation*}
\phi\left(x, t \mid x_{0}, t_{0}\right)=\left[\frac{m}{2 \pi i \hbar f\left(t_{o}, t\right)}\right]^{\frac{1}{2}} \exp \left\{\frac{i}{\hbar} S\left[x_{c l}(t)\right]\right\} \tag{2.102}
\end{equation*}
$$

where $f\left(t_{0}, t\right)$ is the solution of $(2.100,2.101)$ and where $S\left[x_{c l}(t)\right]$ is determined by solving first the Euler-Lagrange equations for the Lagrangian (2.80) to obtain the classical path $x_{c l}(t)$ with end points $x_{c l}\left(t_{0}\right)=x_{0}$ and $x_{c l}\left(t_{N}\right)=x_{N}$ and then evaluating (2.81) for this path. Note that the required solution $x_{c l}(t)$ involves a solution of the Euler-Lagrange equations for boundary conditions which are different from those conventionally encountered in Classical Mechanics where usually a solution for initial conditions $x_{c l}\left(t_{0}\right)=x_{0}$ and $\dot{x}_{c l}\left(t_{0}\right)=v_{0}$ are determined.

### 2.6 Wave Packet Moving in Homogeneous Force Field

We want to consider now the motion of a quantum mechanical particle, decribed at time $t=t_{o}$ by a wave packet (2.48), in the presence of a homogeneous force due to a potential $V(x)=-f x$. As we have learnt from the study of the time-development of (2.48) in case of free particles the wave packet $(2.48)$ corresponds to a classical particle with momentum $p_{o}$ and position $x_{o}=0$. We expect then that the classical particle assumes the following position and momentum at times $t>t_{o}$

$$
\begin{align*}
y(t) & =\frac{p_{o}}{m}\left(t-t_{o}\right)+\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)^{2}  \tag{2.103}\\
p(t) & =p_{o}+f\left(t-t_{o}\right) \tag{2.104}
\end{align*}
$$

The Lagrangian for the present case is

$$
\begin{equation*}
L(x, \dot{x}, t)=\frac{1}{2} m \dot{x}^{2}+f x \tag{2.105}
\end{equation*}
$$

This corresponds to the Lagrangian in (2.80) for $c(t) \equiv 0, e(t) \equiv-f$. Accordingly, we can employ the expression $(2.89,2.90)$ for the propagator where, in the present case, holds $L^{\prime}(y, \dot{y}, t)=\frac{1}{2} m \dot{y}^{2}$ such that $\tilde{\phi}\left(0, t_{N} \mid 0, t_{0}\right)$ is the free particle propagator (2.45). One can write then the propagator for a particle moving subject to a homogeneous force

$$
\begin{equation*}
\phi\left(x, t \mid x_{0}, t_{0}\right)=\left[\frac{m}{2 \pi i \hbar\left(t-t_{0}\right)}\right]^{\frac{1}{2}} \exp \left[\frac{i}{\hbar} S\left[x_{c l}(\tau)\right]\right] . \tag{2.106}
\end{equation*}
$$

Here $S\left[x_{c l}(\tau)\right]$ is the action integral over the classical path with end points

$$
\begin{equation*}
x_{c l}\left(t_{o}\right)=x_{o} \quad, \quad x_{c l}(t)=x \tag{2.107}
\end{equation*}
$$

The classical path obeys

$$
\begin{equation*}
m \ddot{x}_{c l}=f . \tag{2.108}
\end{equation*}
$$

The solution of $(2.107,2.108)$ is

$$
\begin{equation*}
x_{c l}(\tau)=x_{o}+\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right) \tau+\frac{1}{2} \frac{f}{m} \tau^{2} \tag{2.109}
\end{equation*}
$$

as can be readily verified. The velocity along this path is

$$
\begin{equation*}
\dot{x}_{c l}(\tau)=\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)+\frac{f}{m} \tau \tag{2.110}
\end{equation*}
$$

and the Lagrangian along the path, considered as a function of $\tau$, is

$$
\begin{align*}
g(\tau)= & \frac{1}{2} m \dot{x}_{c l}^{2}(\tau)+f x_{c l}(\tau) \\
= & \frac{1}{2} m\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right)^{2}+f\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right) \tau \\
& +\frac{1}{2} \frac{f^{2}}{m} \tau^{2}+f x_{o}+f\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right) \tau+\frac{1}{2} \frac{f^{2}}{m} \tau^{2} \\
= & \frac{1}{2} m\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right)^{2}+2 f\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right) \tau \\
& +\frac{f^{2}}{m} \tau^{2}+f x_{o} \tag{2.111}
\end{align*}
$$

One obtains for the action integral along the classical path

$$
\begin{align*}
& S\left[x_{c l}(\tau)\right]=\int_{t_{o}}^{t} d \tau g(\tau) \\
& =\quad \frac{1}{2} m\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right)^{2}\left(t-t_{o}\right) \\
& \quad+f\left(\frac{x-x_{o}}{t-t_{o}}-\frac{1}{2} \frac{f}{m}\left(t-t_{o}\right)\right)\left(t-t_{o}\right)^{2} \\
& \quad \\
& \quad+\frac{1}{3} \frac{f^{2}}{m}\left(t-t_{o}\right)^{3}+x_{o} f\left(t-t_{o}\right)  \tag{2.112}\\
& =\quad \frac{1}{2} m \frac{\left(x-x_{o}\right)^{2}}{t-t_{o}}+\frac{1}{2}\left(x+x_{o}\right) f\left(t-t_{o}\right)-\frac{1}{24} \frac{f^{2}}{m}\left(t-t_{o}\right)^{3}
\end{align*}
$$

and, finally, for the propagator

$$
\begin{align*}
& \phi\left(x, t \mid x_{o}, t_{o}\right)=\left[\frac{m}{2 \pi i \hbar\left(t-t_{o}\right)}\right]^{\frac{1}{2}} \times  \tag{2.113}\\
& \quad \times \exp \left[\frac{i m}{2 \hbar} \frac{\left(x-x_{o}\right)^{2}}{t-t_{o}}+\frac{i}{2 \hbar}\left(x+x_{o}\right) f\left(t-t_{o}\right)-\frac{i}{24} \frac{f^{2}}{\hbar m}\left(t-t_{o}\right)^{3}\right]
\end{align*}
$$

The propagator (2.113) allows one to determine the time-evolution of the initial state (2.48) using (2.5). Since the propagator depends only on the time-difference $t-t_{o}$ we can assume, withoult loss of generality, $t_{o}=0$ and are lead to the integral

$$
\begin{align*}
& \psi(x, t)=\left[\frac{1}{\pi \delta^{2}}\right]^{\frac{1}{4}}\left[\frac{m}{2 \pi i \hbar t}\right]^{\frac{1}{2}} \int_{-\infty}^{+\infty} d x_{0}  \tag{2.114}\\
& \exp \underbrace{\left[\frac{i m}{2 \hbar} \frac{\left(x-x_{0}\right)^{2}}{t}-\frac{x_{0}^{2}}{2 \delta^{2}}+i \frac{p_{o}}{\hbar} x_{o}+\frac{i}{2 \hbar}\left(x+x_{o}\right) f t-\frac{i}{24} \frac{f^{2}}{m \hbar} t^{3}\right]}_{E_{o}\left(x_{o}, x\right)+E(x)}
\end{align*}
$$

To evaluate the integral we adopt the same computational strategy as used for (2.51) and divide the exponent in (2.114) as follows [c.f. (2.54)]

$$
\begin{gather*}
E_{o}\left(x_{o}, x\right)=\frac{i m}{2 \hbar t}\left[x_{o}^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)-2 x_{o}\left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)+f(x)\right]  \tag{2.115}\\
E(x)=\frac{i m}{2 \hbar t}\left[x^{2}+\frac{f t^{2}}{m} x-f(x)\right]-\frac{1}{24} \frac{f^{2} t^{3}}{\hbar m} \tag{2.116}
\end{gather*}
$$

One chooses then $f(x)$ to complete, according to (2.52), the square in (2.115)

$$
\begin{equation*}
f(x)=\left(\frac{x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}}{\sqrt{1+i \frac{\hbar t}{m \delta^{2}}}}\right)^{2} \tag{2.117}
\end{equation*}
$$

This yields

$$
\begin{equation*}
E_{o}\left(x_{o}, x\right)=\frac{i m}{2 \hbar t}\left(x_{o} \sqrt{1+i \frac{\hbar t}{m \delta^{2}}}-\frac{x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}}{\sqrt{1+i \frac{\hbar t}{m \delta^{2}}}}\right)^{2} \tag{2.118}
\end{equation*}
$$

Following in the footsteps of the calculation on page 18 ff . one can state again

$$
\begin{equation*}
\psi(x, t)=\left[\frac{1-i \frac{\hbar t}{m \delta^{2}}}{1+i \frac{\hbar t}{m \delta^{2}}}\right]^{\frac{1}{4}}\left[\frac{1}{\pi \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right]^{\frac{1}{4}} \exp [E(x)] \tag{2.119}
\end{equation*}
$$

and is lead to the exponential (2.116)

$$
\begin{equation*}
E(x)=-\frac{1}{24} \frac{f^{2} t^{3}}{\hbar m}+\frac{i m}{2 \hbar t\left(1+i \frac{\hbar t}{m \delta^{2}}\right)} S(x) \tag{2.120}
\end{equation*}
$$

where

$$
\begin{align*}
S(x)= & x^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)+x \frac{f t^{2}}{m}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)-\left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)^{2} \\
= & \left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)-\left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)^{2} \\
& +\left[x \frac{f t^{2}}{m}+2 x\left(\frac{p_{o}}{m} t+\frac{f t^{2}}{2 m}\right)-\left(\frac{p_{o}}{m} t+\frac{f t^{2}}{2 m}\right)^{2}\right]\left(1+i \frac{\hbar t}{m \delta^{2}}\right) \tag{2.121}
\end{align*}
$$

Inserting this into (2.120) yields

$$
\begin{align*}
E(x)=\quad & -\frac{\left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)^{2}}{2 \delta^{2}\left(1+i \frac{\hbar t}{m \delta^{2}}\right)}  \tag{2.122}\\
& +\frac{i}{\hbar}\left(p_{o}+f t\right) x-\frac{i}{2 m \hbar}\left(p_{o} t+p_{o} f t^{2}+\frac{f^{2} t^{3}}{4}+\frac{f^{2} t^{3}}{12}\right)
\end{align*}
$$

The last term can be written

$$
\begin{equation*}
-\frac{i}{2 m \hbar}\left(p_{o} t+p_{o} f t^{2}+\frac{f^{2} t^{3}}{3}\right)=-\frac{i}{2 m \hbar} \int_{0}^{t} d \tau\left(p_{o}+f \tau\right)^{2} \tag{2.123}
\end{equation*}
$$

Altogether, $(2.119,2.122,2.123)$ provide the state of the particle at time $t>0$

$$
\begin{align*}
\psi(x, t)= & {\left[\frac{1-i \frac{\hbar t}{m \delta^{2}}}{1+i \frac{\hbar t}{m \delta^{2}}}\right]^{\frac{1}{4}}\left[\frac{1}{\pi \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right]^{\frac{1}{4}} \times } \\
& \times \exp \left[-\frac{\left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)^{2}}{2 \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\left(1-i \frac{\hbar t}{m \delta^{2}}\right)\right] \times \\
& \times \exp \left[\frac{i}{\hbar}\left(p_{o}+f t\right) x-\frac{i}{\hbar} \int_{0}^{t} d \tau \frac{\left(p_{o}+f \tau\right)^{2}}{2 m}\right] \tag{2.124}
\end{align*}
$$

The corresponding probablity distribution is

$$
\begin{equation*}
|\psi(x, t)|^{2}=\left[\frac{1}{\pi \delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right]^{\frac{1}{2}} \exp \left[-\frac{\left(x-\frac{p_{o}}{m} t-\frac{f t^{2}}{2 m}\right)^{2}}{\delta^{2}\left(1+\frac{\hbar^{2} t^{2}}{m^{2} \delta^{4}}\right)}\right] \tag{2.125}
\end{equation*}
$$

## Comparision of Moving Wave Packet with Classical Motion

It is again [c.f. (2.4)] revealing to compare the probability distributions for the initial state (2.48) and for the states at time $t$, i.e., (2.125). Both distributions are Gaussians. Distribution (2.125) moves along the $x$-axis with distribution centers positioned at $y(t)$ given by (2.103), i.e., as expected for a classical particle. The states (2.124), in analogy to the states (2.71) for free particles, exhibit a phase factor $\exp [i p(t) x / \hbar]$, for which $p(t)$ agrees with the classical momentum (2.104). While these properties show a close correspondence between classical and quantum mechanical behaviour, the distribution shows also a pure quantum effect, in that it increases its width . This increase, for the homogeneous force case, is identical to the increase (2.73) determined for a free particle. Such increase of the width of a distribution is not a necessity in quantum mechanics. In fact, in case of socalled bound states, i.e., states in which the classical and quantum mechanical motion is confined to a finite spatial volume, states can exist which do not alter their spatial distribution in time. Such states are called stationary states. In case of a harmonic potential there exists furthermore the possibility that the center of a wave packet follows the classical behaviour and the width remains constant in time. Such states are referred to as coherent states, or Glauber states, and will be
studied below. It should be pointed out that in case of vanishing, linear and quadratic potentials quantum mechanical wave packets exhibit a particularly simple evolution; in case of other type of potential functions and, in particular, in case of higher-dimensional motion, the quantum behaviour can show features which are much more distinctive from classical behaviour, e.g., tunneling and interference effects.

## Propagator of a Harmonic Oscillator

In order to illustrate the evaluation of (2.102) we consider the case of a harmonic oscillator. In this case holds for the coefficents in the Lagrangian (2.80) $c(t)=m \omega^{2}$ and $e(t)=0$, i.e., the Lagrangian is

$$
\begin{equation*}
L(x, \dot{x})=\frac{1}{2} m \dot{x}^{2}-\frac{1}{2} m \omega^{2} x^{2} \tag{2.126}
\end{equation*}
$$

.We determine first $f\left(t_{0}, t\right)$. In the present case holds

$$
\begin{equation*}
\ddot{f}=-\omega^{2} f ; \quad f\left(t_{0}, t_{0}\right)=0 ; \quad \dot{f}\left(t_{o}, t_{o}\right)=1 \tag{2.127}
\end{equation*}
$$

The solution which obeys the stated boundary conditions is

$$
\begin{equation*}
f\left(t_{0}, t\right)=\frac{\sin \omega\left(t-t_{0}\right)}{\omega} \tag{2.128}
\end{equation*}
$$

We determine now $S\left[x_{c l}(\tau)\right]$. For this purpose we seek first the path $x_{c l}(\tau)$ which obeys $x_{c l}\left(t_{0}\right)=x_{0}$ and $x_{c l}(t)=x$ and satisfies the Euler-Lagrange equation for the harmonic oscillator

$$
\begin{equation*}
m \ddot{x}_{c l}+m \omega^{2} x_{c l}=0 \tag{2.129}
\end{equation*}
$$

This equation can be written

$$
\begin{equation*}
\ddot{x}_{c l}=-\omega^{2} x_{c l} \tag{2.130}
\end{equation*}
$$

the general solution of which is

$$
\begin{equation*}
x_{c l}\left(\tau^{\prime}\right)=A \sin \omega\left(\tau-t_{0}\right)+B \cos \omega\left(\tau-t_{0}\right) \tag{2.131}
\end{equation*}
$$

The boundary conditions $x_{c l}\left(t_{0}\right)=x_{0}$ and $x_{c l}(t)=x$ are satisfied for

$$
\begin{equation*}
B=x_{0} ; \quad A=\frac{x-x_{0} \cos \omega\left(t-t_{o}\right)}{\sin \omega\left(t-t_{0}\right)} \tag{2.132}
\end{equation*}
$$

and the desired path is

$$
\begin{equation*}
x_{c l}(\tau)=\frac{x-x_{0} c}{s} \sin \omega\left(\tau-t_{0}\right)+x_{0} \cos \omega\left(\tau-t_{0}\right) \tag{2.133}
\end{equation*}
$$

where we introduced

$$
\begin{equation*}
c=\cos \omega\left(t-t_{o}\right), \quad s=\sin \omega\left(t-t_{0}\right) \tag{2.134}
\end{equation*}
$$

We want to determine now the action integral associated with the path $(2.133,2.134)$

$$
\begin{equation*}
S\left[x_{c l}(\tau)\right]=\int_{t_{0}}^{t} d \tau\left(\frac{1}{2} m \dot{x}_{c l}^{2}(\tau)-\frac{1}{2} m \omega^{2} x_{c l}^{2}(\tau)\right) \tag{2.135}
\end{equation*}
$$

For this purpose we assume presently $t_{o}=0$. From (2.133) follows for the velocity along the classical path

$$
\begin{equation*}
\dot{x}_{c l}(\tau)=\omega \frac{x-x_{0} c}{s} \cos \omega \tau-\omega x_{0} \sin \omega \tau \tag{2.136}
\end{equation*}
$$

and for the kinetic energy

$$
\begin{align*}
\frac{1}{2} m \dot{x}_{c l}^{2}(\tau)= & \frac{1}{2} m \omega^{2} \frac{\left(x-x_{0} c\right)^{2}}{s^{2}} \cos ^{2} \omega \tau \\
& -m \omega^{2} x_{o} \frac{x-x_{0} c}{s} \cos \omega \tau \sin \omega \tau \\
& +\frac{1}{2} m \omega^{2} x_{o}^{2} \sin ^{2} \omega \tau \tag{2.137}
\end{align*}
$$

Similarly, one obtains from (2.133) for the potential energy

$$
\begin{align*}
\frac{1}{2} m \omega^{2} x_{c l}^{2}(\tau)= & \frac{1}{2} m \omega^{2} \frac{\left(x-x_{0} c\right)^{2}}{s^{2}} \sin ^{2} \omega \tau \\
& +m \omega^{2} x_{o} \frac{x-x_{0} c}{s} \cos \omega \tau \sin \omega \tau \\
& +\frac{1}{2} m \omega^{2} x_{o}^{2} \cos ^{2} \omega \tau \tag{2.138}
\end{align*}
$$

Using

$$
\begin{align*}
\cos ^{2} \omega \tau & =\frac{1}{2}+\frac{1}{2} \cos 2 \omega \tau  \tag{2.139}\\
\sin ^{2} \omega \tau & =\frac{1}{2}-\frac{1}{2} \cos 2 \omega \tau  \tag{2.140}\\
\cos \omega \tau \sin \omega \tau & =\frac{1}{2} \sin 2 \omega \tau \tag{2.141}
\end{align*}
$$

the Lagrangian, considered as a function of $\tau$, reads

$$
\begin{align*}
g(\tau)=\frac{1}{2} m \dot{x}_{c l}^{2}(\tau)-\frac{1}{2} m \omega^{2} x_{c l}^{2}(\tau)= & \frac{1}{2} m \omega^{2} \frac{\left(x-x_{0} c\right)^{2}}{s^{2}} \cos 2 \omega \tau \\
& -m \omega^{2} x_{o} \frac{x-x_{0} c}{s} \sin 2 \omega \tau \\
& -\frac{1}{2} m \omega^{2} x_{o}^{2} \cos 2 \omega \tau \tag{2.142}
\end{align*}
$$

Evaluation of the action integral (2.135), i.e., of $S\left[x_{c l}(\tau)\right]=\int_{0}^{t} d \tau g(\tau)$ requires the integrals

$$
\begin{align*}
\int_{0}^{t} d \tau \cos 2 \omega \tau & =\frac{1}{2 \omega} \sin 2 \omega t=\frac{1}{\omega} s c  \tag{2.143}\\
\int_{0}^{t} d \tau \sin 2 \omega \tau & =\frac{1}{2 \omega}[1-\cos 2 \omega t]=\frac{1}{\omega} s^{2} \tag{2.144}
\end{align*}
$$

where we employed the definition (2.134) Hence, (2.135) is, using $s^{2}+c^{2}=1$,

$$
\begin{align*}
S\left[x_{c l}(\tau)\right] & =\frac{1}{2} m \omega \frac{\left(x-x_{0} c\right)^{2}}{s^{2}} s c-m \omega x_{o} \frac{x-x_{0} c}{s} s^{2}-\frac{1}{2} m \omega^{2} x_{o}^{2} s c \\
& =\frac{m \omega}{2 s}\left[\left(x^{2}-2 x_{0} c+x_{o}^{2} c^{2}\right) c-2 x_{o} x s^{2}+2 x_{o}^{2} c s^{2}-x_{o}^{2} s^{2} c\right] \\
& =\frac{m \omega}{2 s}\left[\left(x^{2}+x_{o}^{2}\right) c-2 x_{o} x\right] \tag{2.145}
\end{align*}
$$

and, with the definitions (2.134),

$$
\begin{equation*}
S\left[x_{c l}(\tau)\right]=\frac{m \omega}{2 \sin \omega\left(t-t_{0}\right)}\left[\left(x_{0}^{2}+x^{2}\right) \cos \omega\left(t-t_{0}\right)-2 x_{0} x\right] \tag{2.146}
\end{equation*}
$$

For the propagator of the harmonic oscillator holds then

$$
\begin{gather*}
\phi\left(x, t \mid x_{0}, t_{0}\right)=\left[\frac{m \omega}{2 \pi i \hbar \sin \omega\left(t-t_{0}\right)}\right]^{\frac{1}{2}} \times \\
\times \exp \left\{\frac{i m \omega}{2 \hbar \sin \omega\left(t-t_{0}\right)}\left[\left(x_{0}^{2}+x^{2}\right) \cos \omega\left(t-t_{0}\right)-2 x_{0} x\right]\right\} \tag{2.147}
\end{gather*}
$$

## Quantum Pendulum or Coherent States

As a demonstration of the application of the propagator (2.147) we use it to describe the time development of the wave function for a particle in an initial state

$$
\begin{equation*}
\psi\left(x_{0}, t_{0}\right)=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}} \exp \left(-\frac{m \omega\left(x_{0}-b_{o}\right)^{2}}{2 \hbar}+\frac{i}{\hbar} p_{o} x_{o}\right) \tag{2.148}
\end{equation*}
$$

The initial state is decribed by a Gaussian wave packet centered around the position $x=b_{o}$ and corresponds to a particle with initial momentum $p_{o}$. The latter property follows from the role of such factor for the initial state (2.48) when applied to the case of a free particle [c.f. (2.71)] or to the case of a particle moving in a homogeneous force [c.f. $(2.124,2.125)$ ] and will be borne out of the following analysis; at present one may regard it as an assumption.
If one identifies the center of the wave packet with a classical particle, the following holds for the time development of the position (displacement), momentum, and energy of the particle

$$
\begin{align*}
b(t) & =b_{o} \cos \omega\left(t-t_{o}\right)+\frac{p_{o}}{m \omega} \sin \omega\left(t-t_{o}\right) & & \text { displacement } \\
p(t) & =-m \omega b_{o} \sin \omega\left(t-t_{o}\right)+p_{o} \cos \omega\left(t-t_{o}\right) & & \text { momentum }  \tag{2.149}\\
\epsilon_{o} & =\frac{p_{o}^{2}}{2 m}+\frac{1}{2} m \omega^{2} b_{o}^{2} & & \text { energy }
\end{align*}
$$

We want to explore, using (2.5), how the probability distribution $|\psi(x, t)|^{2}$ of the quantum particle propagates in time.
The wave function at times $t>t_{0}$ is

$$
\begin{equation*}
\psi(x, t)=\int_{-\infty}^{\infty} d x_{0} \phi\left(x, t \mid x_{0}, t_{0}\right) \psi\left(x_{0}, t_{0}\right) \tag{2.150}
\end{equation*}
$$

Expressing the exponent in (2.148)

$$
\begin{equation*}
\frac{i m \omega}{2 \hbar \sin \omega\left(t-t_{o}\right)}\left[i\left(x_{o}-b_{o}\right)^{2} \sin \omega\left(t-t_{o}\right)+\frac{2 p_{o}}{m \omega} x_{o} \sin \omega\left(t-t_{o}\right)\right] \tag{2.151}
\end{equation*}
$$

(2.147, 2.150, 2.151) can be written

$$
\begin{equation*}
\psi(x, t)=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}}\left[\frac{m}{2 \pi i \omega \hbar \sin \omega\left(t-t_{0}\right)}\right]^{\frac{1}{2}} \int_{-\infty}^{\infty} d x_{0} \exp \left[E_{0}+E\right] \tag{2.152}
\end{equation*}
$$

where

$$
\begin{align*}
E_{0}\left(x_{o}, x\right)= & \frac{i m \omega}{2 \hbar s}\left[x_{o}^{2} c-2 x_{o} x+i s x_{o}^{2}-2 i s x_{o} b_{o}+\frac{2 p_{o}}{m \omega} x_{o} s+f(x)\right] \\
E(x)= & \frac{i m \omega}{2 \hbar s}\left[x^{2} c+i s b_{o}^{2}-f(x)\right]  \tag{2.153}\\
& c=\cos \omega\left(t-t_{o}\right), \quad s=\sin \omega\left(t-t_{o}\right) \tag{2.155}
\end{align*}
$$

Here $f(x)$ is a function which is introduced to complete the square in (2.153) for simplification of the Gaussian integral in $x_{0}$. Since $E(x)$ is independent of $x_{o}$ (2.152) becomes

$$
\begin{equation*}
\psi(x, t)=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}}\left[\frac{m}{2 \pi i \omega \hbar \sin \omega\left(t-t_{0}\right)}\right]^{\frac{1}{2}} e^{E(x)} \int_{-\infty}^{\infty} d x_{0} \exp \left[E_{0}\left(x_{o}, x\right)\right] \tag{2.156}
\end{equation*}
$$

We want to determine now $E_{o}\left(x_{o}, x\right)$ as given in (2.153). It holds

$$
\begin{equation*}
E_{o}=\frac{i m \omega}{2 \hbar s}\left[x_{o}^{2} e^{i \omega\left(t-t_{o}\right)}-2 x_{o}\left(x+i s b_{o}-\frac{p_{o}}{m \omega} s\right)+f(x)\right] \tag{2.157}
\end{equation*}
$$

For $f(x)$ to complete the square we choose

$$
\begin{equation*}
f(x)=\left(x+i s b_{o}-\frac{p_{o}}{m \omega} s\right)^{2} e^{-i \omega\left(t-t_{o}\right)} . \tag{2.158}
\end{equation*}
$$

One obtains for (2.157)

$$
\begin{equation*}
E_{0}\left(x_{o}, x\right)=\frac{i m \omega}{2 \hbar s} \exp \left[i \omega\left(t-t_{0}\right)\right]\left[x_{0}-\left(x+i s b_{o}-\frac{p_{o}}{m \omega} s\right) \exp \left(-i \omega\left(t-t_{0}\right)\right]^{2}\right. \tag{2.159}
\end{equation*}
$$

To determine the integral in (2.156) we employ the integration formula (2.247) and obtain

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d x_{0} e^{E_{0}\left(x_{0}\right)}=\left[\frac{2 \pi i \hbar \sin \omega\left(t-t_{0}\right)}{m \omega \exp \left[i \omega\left(t-t_{0}\right)\right]}\right]^{\frac{1}{2}} \tag{2.160}
\end{equation*}
$$

Inserting this into (2.156) yields

$$
\begin{equation*}
\psi(x, t)=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}} e^{E(x)} \tag{2.161}
\end{equation*}
$$

For $E(x)$ as defined in (2.154) one obtains, using $\exp \left[ \pm i \omega\left(t-t_{o}\right)\right]=c \pm i s$,

$$
\begin{align*}
& E(x)=\frac{i m \omega}{2 \hbar s}\left[x^{2} c+i s b_{o}^{2}-x^{2} c+i s x^{2}-2 i s x b_{o} c-2 s^{2} x b_{o}\right. \\
& +s^{2} b_{o}^{2} c-i s^{3} b_{o}^{2}+2 \frac{p_{o}}{m \omega} x s c+2 i \frac{p_{o}}{m \omega} b_{o} s^{2} c \\
& \left.-2 i \frac{p_{o}}{m \omega} x s^{2}+2 \frac{p_{o}}{m \omega} b_{o} s^{3}-\frac{p_{o}^{2}}{m^{2} \omega^{2}} s^{2} c+i \frac{p_{o}^{2}}{m^{2} \omega^{2}} s^{3}\right] \\
& =-\frac{m \omega}{2 \hbar}\left[x^{2}+c^{2} b_{o}^{2}-2 x b_{o} c+2 i x s b_{o}-i b_{o}^{2} s c\right. \\
& -2 \frac{p_{o}}{m \omega} x s+2 \frac{p_{o}}{m \omega} b_{o} s c+\frac{p_{o}^{2}}{m^{2} \omega^{2}} s^{2}-2 i \frac{p_{o}}{m \omega} x c \\
& \left.-2 i \frac{p_{o}}{m \omega} b_{o} s^{2}+i \frac{p_{o}^{2}}{m^{2} \omega^{2}} s c\right] \\
& =-\frac{m \omega}{2 \hbar}\left(x-c b_{o}-\frac{p_{o}}{m \omega} s\right)^{2}+\frac{i}{\hbar}\left(-m \omega b_{o} s+p_{o} c\right) x \\
& -\frac{i}{\hbar}\left(\frac{p_{o}^{2}}{2 m \omega}-\frac{1}{2} m \omega b_{o}^{2}\right) s c+\frac{i}{\hbar} p_{o} b_{o} s^{2} \tag{2.162}
\end{align*}
$$

We note the following identities

$$
\begin{align*}
\int_{t_{o}}^{t} d \tau & \frac{p^{2}(\tau)}{2 m} \\
& =\frac{1}{2} \epsilon_{o}\left(t-t_{o}\right)+\frac{1}{2}\left(\frac{p_{o}^{2}}{2 m \omega}-\frac{m \omega b_{o}^{2}}{2}\right) s c-\frac{1}{2} b_{o} p_{o} s^{2}  \tag{2.163}\\
\int_{t_{o}}^{t} d \tau & \frac{m \omega^{2} b^{2}(\tau)}{2} \\
& =\frac{1}{2} \epsilon_{o}\left(t-t_{o}\right)-\frac{1}{2}\left(\frac{p_{o}^{2}}{2 m \omega}-\frac{m \omega b_{o}^{2}}{2}\right) s c+\frac{1}{2} b_{o} p_{o} s^{2} \tag{2.164}
\end{align*}
$$

where we employed $b(\tau)$ and $p(\tau)$ as defined in (2.149). From this follows, using $p(\tau)=m \dot{b}(\tau)$ and the Lagrangian (2.126),

$$
\begin{equation*}
\int_{t_{o}}^{t} d \tau L[b(\tau), \dot{b}(\tau)]=\left(\frac{p_{o}^{2}}{2 m \omega}-\frac{m \omega b_{o}^{2}}{2}\right) s c-b_{o} p_{o} s \tag{2.165}
\end{equation*}
$$

such that $E(x)$ in (2.162) can be written, using again (2.149)),

$$
\begin{equation*}
E(x)=-\frac{m \omega}{2 \hbar}[x-b(t)]^{2}+\frac{i}{\hbar} p(t) x-i \frac{1}{2} \omega\left(t-t_{o}\right)-\frac{i}{\hbar} \int_{t_{o}}^{t} d \tau L[b(\tau), \dot{b}(\tau)] \tag{2.166}
\end{equation*}
$$

Inserting this into (2.161) yields,

$$
\begin{align*}
& \psi(x, t)=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}} \times \exp \left\{-\frac{m \omega}{2 \hbar}[x-b(t)]^{2}\right\} \times  \tag{2.167}\\
& \quad \times \exp \left\{\frac{i}{\hbar} p(t) x-i \frac{1}{2} \omega\left(t-t_{o}\right)-\frac{i}{\hbar} \int_{t_{o}}^{t} d \tau L[b(\tau), \dot{b}(\tau)]\right\}
\end{align*}
$$

where $b(t), p(t)$, and $\epsilon_{o}$ are the classical displacement, momentum and energy, respectively, defined in (2.149).

## Comparision of Moving Wave Packet with Classical Motion

The probability distribution associated with (2.167)

$$
\begin{equation*}
|\psi(x, t)|^{2}=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{2}} \exp \left\{-\frac{m \omega}{\hbar}[x-b(t)]^{2}\right\} \tag{2.168}
\end{equation*}
$$

is a Gaussian of time-independent width, the center of which moves as described by $b(t)$ given in (2.148) , i.e., the center follows the motion of a classical oscillator (pendulum) with initial position $b_{o}$ and initial momentum $p_{o}$. It is of interest to recall that propagating wave packets in the case of vanishing [c.f. (2.72)] or linear [c.f. (2.125)] potentials exhibit an increase of their width in time; in case of the quantum oscillator for the particular width chosen for the initial state (2.148) the width, actually, is conserved. One can explain this behaviour as arising from constructive interference due to the restoring forces of the harmonic oscillator. We will show in Chapter 4 [c.f. $(4.166,4.178)$ and Fig. 4.1] that an initial state of arbitrary width propagates as a Gaussian with oscillating width.

In case of the free particle wave packet $(2.48,2.71)$ the factor $\exp \left(i p_{o} x\right)$ gives rise to the translational motion of the wave packet described by $p_{o} t / m$, i.e., $p_{o}$ also corresponds to initial classical momentum. In case of a homogeneous force field the phase factor $\exp \left(i p_{o} x\right)$ for the initial state (2.48) gives rise to a motion of the center of the propagating wave packet [c.f. (2.125)] described by $\left(p_{o} / m\right) t+\frac{1}{2} f t^{2}$ such that again $p_{o}$ corresponds to the classical momentum. Similarly, one observes for all three cases (free particle, linear and quadratic potential) a phase factor $\exp [i p(t) x / \hbar]$ for the propagating wave packet where $\mathrm{f} p(t)$ corresponds to the initial classical momentum at time $t$. One can, hence, summarize that for the three cases studied (free particle, linear and quadratic potential) propagating wave packets show remarkably close analogies to classical motion.
We like to consider finally the propagation of an initial state as in (2.148), but with $b_{o}=0$ and $p_{o}=0$. Such state is given by the wave function

$$
\begin{equation*}
\psi\left(x_{0}, t_{0}\right)=\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}} \exp \left(-\frac{m \omega x_{0}^{2}}{2 \hbar}-\frac{i \omega}{2} t_{o}\right) . \tag{2.169}
\end{equation*}
$$

where we added a phase factor $\exp \left(-i \omega t_{o} / 2\right)$. According to (2.167) the state (2.169) reproduces itself at later times $t$ and the probablity distribution remains at all times equal to

$$
\begin{equation*}
\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{2}} \exp \left(-\frac{m \omega x_{0}^{2}}{\hbar}\right) \tag{2.170}
\end{equation*}
$$

i.e., the state (2.169) is a stationary state of the system. The question arises if the quantum oscillator posesses further stationary states. In fact, there exist an infinite number of such states which will be determined now.

### 2.7 Stationary States of the Harmonic Oscillator

In order to find the stationary states of the quantum oscillator we consider the function

$$
\begin{equation*}
W(x, t)=\exp \left(2 \sqrt{\frac{m \omega}{\hbar}} x e^{-i \omega t}-e^{-2 i \omega t}-\frac{m \omega}{2 \hbar} x^{2}-\frac{i \omega t}{2}\right) . \tag{2.171}
\end{equation*}
$$

We want to demonstrate that $w(x, t)$ is invariant in time, i.e., for the propagator (2.147) of the harmonic oscillator holds

$$
\begin{equation*}
W(x, t)=\int_{-\infty}^{+\infty} d x_{o} \phi\left(x, t \mid x_{o}, t_{o}\right) W\left(x_{o}, t_{o}\right) . \tag{2.172}
\end{equation*}
$$

We will demonstrate further below that (2.172) provides us in a nutshell with all the stationary states of the harmonic oscillator, i.e., with all the states with time-independent probability distribution.
In order to prove (2.172) we express the propagator, using (2.147) and the notation $T=t-t_{o}$

$$
\begin{align*}
& \phi\left(x, t \mid x_{o}, t_{o}\right)=e^{-\frac{1}{2} i \omega T}\left[\frac{m \omega}{\pi \hbar\left(1-e^{-2 i \omega T}\right)}\right]^{\frac{1}{2}} \times \\
& \times \exp \left[-\frac{m \omega}{2 \hbar}\left(x_{o}^{2}+x^{2}\right) \frac{1+e^{-2 i \omega T}}{1-e^{-2 i \omega T}}-\frac{m \omega}{\hbar \omega} \frac{2 x x_{o} e^{-i \omega T}}{1-e^{-2 i \omega T}}\right] \tag{2.173}
\end{align*}
$$

One can write then the r.h.s. of (2.172)

$$
\begin{equation*}
I=e^{-\frac{1}{2} i \omega t}\left[\frac{m \omega}{\pi \hbar\left(1-e^{-2 i \omega T}\right)}\right]^{\frac{1}{2}} \int_{-\infty}^{+\infty} d x_{o} \exp \left[E_{o}\left(x_{o}, x\right)+E(x)\right] \tag{2.174}
\end{equation*}
$$

where

$$
\begin{align*}
E_{o}\left(x_{o}, x\right)= & -\frac{m \omega}{2 \hbar}\left[x_{o}^{2}\left(\frac{1+e^{-2 i \omega T}}{1-e^{-2 i \omega T}}+1\right)\right.  \tag{2.175}\\
& \left.+2 x_{o}\left(\frac{2 x e^{-i \omega T}}{1-e^{-2 i \omega T}}+2 \sqrt{\frac{\hbar}{m \omega}} e^{-i \omega t_{o}}\right)+f(x)\right] \\
E(x)= & -\frac{m \omega}{2 \hbar}\left[x^{2} \frac{1+e^{-2 i \omega T}}{1-e^{-2 i \omega T}}+\frac{2 \hbar}{m \omega} e^{-2 i \omega t_{o}}-f(x)\right] \tag{2.176}
\end{align*}
$$

Following the by now familiar strategy one choses $f(x)$ to complete the square in (2.175), namely,

$$
\begin{equation*}
f(x)=\frac{1}{2}\left(1-e^{-2 i \omega T}\right)\left(\frac{2 x e^{-i \omega T}}{1-e^{-2 i \omega T}}+2 \sqrt{\frac{\hbar}{m \omega}} e^{-i \omega t_{o}}\right)^{2} . \tag{2.177}
\end{equation*}
$$

This choice of $f(x)$ results in

$$
\begin{align*}
E_{o}\left(x_{o}, x\right)= & -\frac{m \omega}{2 \hbar}\left[x_{o} \sqrt{\frac{2}{1-e^{-2 i \omega T}}}\right. \\
& \left.+\sqrt{\frac{1-e^{-2 i \omega T}}{2}}\left(\frac{2 x e^{-i \omega T}}{1-e^{-2 i \omega T}}+2 \sqrt{\frac{\hbar}{m \omega}} e^{-i \omega t_{o}}\right)\right]^{2} \\
= & i \frac{m \omega}{i \hbar\left(e^{-2 i \omega T}-1\right)}\left(x_{o}+z_{o}\right)^{2} \tag{2.178}
\end{align*}
$$

for some constant $z_{o} \in \mathbb{C}$. Using (2.247) one obtains

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d x_{o} e^{E_{o}\left(x_{o}, x\right)}=\left[\frac{\pi \hbar\left(1-e^{-2 i \omega T}\right.}{m \omega}\right]^{\frac{1}{2}} \tag{2.179}
\end{equation*}
$$

and, therefore, one obtains for (2.174)

$$
\begin{equation*}
I=e^{-\frac{1}{2} i \omega t} e^{E(x)} \tag{2.180}
\end{equation*}
$$

For $E(x)$, as given in $(2.176,2.177)$, holds

$$
\begin{align*}
E(x)= & -\frac{m \omega}{2 \hbar}\left[x^{2} \frac{1+e^{-2 i \omega T}}{1-e^{-2 i \omega T}}+\frac{2 \hbar}{m \omega} e^{-2 i \omega t_{o}}-\frac{2 x^{2} e^{-2 i \omega T}}{1-e^{-2 i \omega T}}\right. \\
& \left.-4 \sqrt{\frac{\hbar}{m \omega}} x e^{-i \omega T}-2\left(1-e^{-2 i \omega T}\right) \frac{\hbar}{m \omega} e^{-2 i \omega t_{o}}\right] \\
= & -\frac{m \omega}{2 \hbar}\left[x^{2}-4 \sqrt{\frac{\hbar}{m \omega}} x e^{-i \omega t}+\frac{2 \hbar}{m \omega} e^{-2 i \omega t}\right] \\
= & -\frac{m \omega}{2 \hbar} x^{2}+2 \sqrt{\frac{m \omega}{\hbar}} x e^{-i \omega t}-e^{-2 i \omega t} \tag{2.181}
\end{align*}
$$

Altogether, one obtains for the r.h.s. of (2.172)

$$
\begin{equation*}
I=\exp \left(2 \sqrt{\frac{m \omega}{\hbar}} x e^{-i \omega t}-e^{-2 i \omega t}-\frac{m \omega}{2 \hbar} x^{2}-\frac{1}{2} i \omega t\right) \tag{2.182}
\end{equation*}
$$

Comparision with (2.171) concludes the proof of (2.172).
We want to inspect the consequences of the invariance property (2.171, 2.172). We note that the factor $\exp \left(2 \sqrt{m \omega / \hbar} x e^{-i \omega t}-e^{-2 i \omega t}\right)$ in $(2.171)$ can be expanded in terms of $e^{-i n \omega t}, n=1,2, \ldots$.. Accoordingly, one can expand (2.171)

$$
\begin{equation*}
W(x, t)=\sum_{n=0}^{\infty} \frac{1}{n!} \exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] \tilde{\phi}_{n}(x) \tag{2.183}
\end{equation*}
$$

where the expansion coefficients are functions of $x$, but not of $t$. Noting that the propagator (2.147) in (2.172) is a function of $t-t_{o}$ and defining accordingly

$$
\begin{equation*}
\Phi\left(x, x_{o} ; t-t_{o}\right)=\phi\left(x, t \mid x_{o}, t_{o}\right) \tag{2.184}
\end{equation*}
$$

we express (2.172) in the form

$$
\begin{align*}
& \sum_{n=0}^{\infty} \frac{1}{n!} \exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] \tilde{\phi}_{n}(x) \\
& \quad=\sum_{m=0}^{\infty} \int_{-\infty}^{+\infty} d x_{o} \Phi\left(x, x_{o} ; t-t_{o}\right) \frac{1}{m!} \exp \left[-i \omega\left(m+\frac{1}{2}\right) t_{o}\right] \tilde{\phi}_{m}\left(x_{o}\right) \tag{2.185}
\end{align*}
$$

Replacing $t \rightarrow t+t_{o}$ yields

$$
\begin{align*}
& \sum_{n=0}^{\infty} \frac{1}{n!} \exp \left[-i \omega\left(n+\frac{1}{2}\right)\left(t+t_{o}\right)\right] \tilde{\phi}_{n}(x) \\
& \quad=\sum_{m=0}^{\infty} \int_{-\infty}^{+\infty} d x_{o} \Phi\left(x, x_{o} ; t\right) \frac{1}{m!} \exp \left[-i \omega\left(m+\frac{1}{2}\right) t_{o}\right] \tilde{\phi}_{m}\left(x_{o}\right) \tag{2.186}
\end{align*}
$$

Fourier transform, i.e., $\int_{-\infty}^{+\infty} d t_{o} \exp \left[i \omega\left(n+\frac{1}{2}\right) t_{o}\right] \cdots$, results in

$$
\begin{align*}
& \frac{1}{n!} \exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] \tilde{\phi}_{n}(x) \\
& \quad=\int_{-\infty}^{+\infty} d x_{o} \Phi\left(x, x_{o} ; t-t_{o}\right) \frac{1}{n!} \tilde{\phi}_{n}\left(x_{o}\right) \tag{2.187}
\end{align*}
$$

or

$$
\begin{align*}
& \exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] \tilde{\phi}_{n}(x) \\
&=\int_{-\infty}^{+\infty} d x_{o} \phi\left(x, t \mid x_{o}, t_{o}\right) \exp \left[-i \omega\left(n+\frac{1}{2}\right) t_{o}\right] \tilde{\phi}_{n}\left(x_{o}\right) . \tag{2.188}
\end{align*}
$$

Equation (2.188) identifies the functions $\tilde{\psi}_{n}(x, t)=\exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] \tilde{\phi}_{n}(x)$ as invariants under the action of the propagator $\phi\left(x, t \mid x_{o}, t_{o}\right)$. In contrast to $W(x, t)$, which also exhibits such invariance,
the functions $\tilde{\psi}_{n}(x, t)$ are associated with a time-independent probablity density $\left|\tilde{\psi}_{n}(x, t)\right|^{2}=$ $\left|\tilde{\phi}_{n}(x)\right|^{2}$. Actually, we have identified then, through the expansion coefficients $\tilde{\phi}_{n}(x)$ in (2.183), stationary wave functions $\psi_{n}(x, t)$ of the quantum mechanical harmonic oscillator

$$
\begin{equation*}
\psi_{n}(x, t)=\exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] N_{n} \tilde{\phi}_{n}(x), \quad n=0,1,2, \ldots \tag{2.189}
\end{equation*}
$$

Here $N_{n}$ are constants which normalize $\psi_{n}(x, t)$ such that

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d x|\psi(x, t)|^{2}=N_{n}^{2} \int_{-\infty}^{+\infty} d x \tilde{\phi}_{n}^{2}(x)=1 \tag{2.190}
\end{equation*}
$$

is obeyed. In the following we will characterize the functions $\tilde{\phi}_{n}(x)$ and determine the normalization constants $N_{n}$. We will also argue that the functions $\psi_{n}(x, t)$ provide all stationary states of the quantum mechanical harmonic oscillator.

## The Hermite Polynomials

The function (2.171), through expansion (2.183), characterizes the wave functions $\tilde{\phi}_{n}(x)$. To obtain closed expressions for $\tilde{\phi}_{n}(x)$ we simplify the expansion $(2.183)$. For this purpose we introduce first the new variables

$$
\begin{align*}
y & =\sqrt{\frac{m \omega}{\hbar}} x  \tag{2.191}\\
z & =e^{-i \omega t} \tag{2.192}
\end{align*}
$$

and write (2.171)

$$
\begin{equation*}
W(x, t)=z^{\frac{1}{2}} e^{-y^{2} / 2} w(y, z) \tag{2.193}
\end{equation*}
$$

where

$$
\begin{equation*}
w(y, z)=\exp \left(2 y z-z^{2}\right) \tag{2.194}
\end{equation*}
$$

Expansion (2.183) reads then

$$
\begin{equation*}
w(y, z) z^{\frac{1}{2}} e^{-y^{2} / 2}=z^{\frac{1}{2}} \sum_{n=0}^{\infty} \frac{z^{n}}{n!} \tilde{\phi}_{n}(y) \tag{2.195}
\end{equation*}
$$

or

$$
\begin{equation*}
w(y, z)=\sum_{n=0}^{\infty} \frac{z^{n}}{n!} H_{n}(y) \tag{2.196}
\end{equation*}
$$

where

$$
\begin{equation*}
H_{n}(y)=e^{y^{2} / 2} \tilde{\phi}_{n}(y) \tag{2.197}
\end{equation*}
$$

The expansion coefficients $H_{n}(y)$ in (2.197) are called Hermite polynomials which are polynomials of degree $n$ which will be evaluated below. Expression (2.194) plays a central role for the Hermite polynomials since it contains, according to (2.194), in a 'nutshell' all information on the Hermite polynomials. This follows from

$$
\begin{equation*}
\left.\frac{\partial^{n}}{\partial z^{n}} w(y, z)\right|_{z=0}=H_{n}(y) \tag{2.198}
\end{equation*}
$$

which is a direct consequence of (2.196). One calls $w(y, z)$ the generating function for the Hermite polynomials. As will become evident in the present case generating functions provide an extremely elegant access to the special functions of Mathematical Physics ${ }^{3}$. We will employ (2.194, 2.196) to derive, among other properties, closed expressions for $H_{n}(y)$, normalization factors for $\tilde{\phi}(y)$, and recursion equations for the efficient evaluation of $H_{n}(y)$.
The identity (2.198) for the Hermite polynomials can be expressed in a more convenient form employing definition (2.196)

$$
\begin{align*}
& \left.\frac{\partial^{n}}{\partial z^{n}} w(y, z)\right|_{z=0}=\left.\left.\frac{\partial^{n}}{\partial z^{n}} e^{2 y z-z^{2}}\right|_{z=0} e^{y^{2}} \frac{\partial^{n}}{\partial z^{n}} e^{-(y-z)^{2}}\right|_{z=0} \\
& \quad=\left.(-1)^{n} e^{y^{2}} \frac{\partial^{n}}{\partial y^{n}} e^{-(y-z)^{2}}\right|_{z=0}=(-1)^{n} e^{y^{2}} \frac{\partial^{n}}{\partial y^{n}} e^{-y^{2}} \tag{2.199}
\end{align*}
$$

Comparision with (2.196) results in the so-called Rodrigues formula for the Hermite polynomials

$$
\begin{equation*}
H_{n}(y)=(-1)^{n} e^{y^{2}} \frac{\partial^{n}}{\partial y^{n}} e^{-y^{2}} \tag{2.200}
\end{equation*}
$$

One can deduce from this expression the polynomial character of $H_{n}(y)$, i.e., that $H_{n}(y)$ is a polynomial of degree $n$. (2.200) yields for the first Hermite polynomials

$$
\begin{equation*}
H_{0}(y)=1, \quad H_{1}(y)=2 y, \quad H_{2}(y)=4 y^{2}-2, \quad H_{3}(y)=8 y^{3}-12 y, \ldots \tag{2.201}
\end{equation*}
$$




Figure 2.1: Schematic representation of change of summation variables $\nu$ and $\mu$ to $n=\nu+\mu$ and $m=\nu-\mu$. The diagrams illustrate that a summation over all points in a $\nu, \mu$ lattice (left diagram) corresponds to a summation over only every other point in an $n, m$ lattice (right diagram). The diagrams also identify the areas over which the summation is to be carried out.

We want to derive now explicit expressions for the Hermite polynomials. For this purpose we expand the generating function (2.194) in a Taylor series in terms of $y^{p} z^{q}$ and identify the corresponding coefficient $c_{p q}$ with the coefficient of the $p$-th power of $y$ in $H_{q}(y)$. We start from

$$
\begin{align*}
e^{2 y z-z^{2}} & =\sum_{\nu=0}^{\infty} \sum_{\mu=0}^{\nu} \frac{1}{\nu!}\binom{\nu}{\mu} z^{2 \mu}(-1)^{\mu}(2 y)^{\nu-\mu} z^{\nu-\mu} \\
& =\sum_{\nu=0}^{\infty} \sum_{\mu=0}^{\nu} \frac{1}{\nu}\binom{\nu}{\mu}(-1)^{\mu}(2 y)^{\nu-\mu} z^{\nu+\mu} \tag{2.202}
\end{align*}
$$

[^2]and introduce now new summation variables
\[

$$
\begin{equation*}
n=\nu+\mu, \quad m=\nu-\mu \quad 0 \leq n<\infty, 0 \leq m \leq n \tag{2.203}
\end{equation*}
$$

\]

The old summation variables $\nu, \mu$ expressend in terms of $n, m$ are

$$
\begin{equation*}
\nu=\frac{n+m}{2}, \quad \mu=\frac{n-m}{2} \tag{2.204}
\end{equation*}
$$

Since $\nu, \mu$ are integers the summation over $n, m$ must be restricted such that either both $n$ and $m$ are even or both $n$ and $m$ are odd. The lattices representing the summation terms are shown in Fig. 2.1. With this restriction in mind one can express (2.202)

$$
\begin{equation*}
e^{2 y z-z^{2}}=\sum_{n=0}^{\infty} \frac{z^{n}}{n!} \sum_{m \geq 0}^{\leq n} \frac{n!(-1)^{\frac{n-m}{2}}}{\left(\frac{n-m}{2}\right)!m!}(2 y)^{m} \tag{2.205}
\end{equation*}
$$

Since $(n-m) / 2$ is an integer we can introduce now the summation variable $k=(n-m) / 2,0 \leq$ $k \leq[n / 2]$ where $[x]$ denotes the largest integer $p, p \leq x$. One can write then using $m=n-2 k$

$$
\begin{equation*}
e^{2 y z-z^{2}}=\sum_{n=0}^{\infty} \frac{z^{n}}{n!} \underbrace{\sum_{k=0}^{[n / 2]} \frac{n!(-1)^{k}}{k!(n-2 k)!}(2 y)^{n-2 k}}_{=H_{n}(y)} \tag{2.206}
\end{equation*}
$$

From this expansion we can identify $H_{n}(y)$

$$
\begin{equation*}
H_{n}(y)=\sum_{k=0}^{[n / 2]} \frac{(-1)^{k} n!}{k!(n-2 k)!}(2 y)^{n-2 k} \tag{2.207}
\end{equation*}
$$

This expression yields for the first four Hermite polynomials

$$
\begin{equation*}
H_{0}(y)=1, \quad H_{1}(y)=2 y, \quad H_{2}(y)=4 y^{2}-2, \quad H_{3}(y)=8 y^{3}-12 y, \ldots \tag{2.208}
\end{equation*}
$$

which agrees with the expressions in (2.201).
From (2.207) one can deduce that $H_{n}(y)$, in fact, is a polynomial of degree $n$. In case of even $n$, the sum in (2.207) contains only even powers, otherwise, i.e., for odd $n$, it contains only odd powers. Hence, it holds

$$
\begin{equation*}
H_{n}(-y)=(-1)^{n} H_{n}(y) \tag{2.209}
\end{equation*}
$$

This property follows also from the generating function. According to $(2.194)$ holds $w(-y, z)=$ $w(y,-z)$ and, hence, according to 2.197)

$$
\begin{equation*}
\sum_{n=0}^{\infty} \frac{z^{n}}{n!} H_{n}(-y)=\sum_{n=0}^{\infty} \frac{(-z)^{n}}{n!} H_{n}(y)=\sum_{n=0}^{\infty} \frac{z^{n}}{n!}(-1)^{n} H_{n}(y) \tag{2.210}
\end{equation*}
$$

from which one can conclude the property (2.209).

The generating function allows one to determine the values of $H_{n}(y)$ at $y=0$. For this purpose one considers $w(0, z)=\exp \left(-z^{2}\right)$ and carries out the Taylor expansion on both sides of this expression resulting in

$$
\begin{equation*}
\sum_{m=0}^{\infty} \frac{(-1)^{m} z^{2 m}}{m!}=\sum_{n=0}^{\infty} H_{n}(0) \frac{z^{n}}{n!} \tag{2.211}
\end{equation*}
$$

Comparing terms on both sides of the equation yields

$$
\begin{equation*}
H_{2 n}(0)=(-1)^{n} \frac{(2 n)!}{n!}, \quad H_{2 n+1}(0)=0, \quad n=0,1,2, \ldots \tag{2.212}
\end{equation*}
$$

This implies that stationary states of the harmonic oscillator $\phi_{2 n+1}(x)$, as defined through (2.188, 2.197) above and given by (2.233) below, have a node at $y=0$, a property which is consistent with (2.209) since odd functions have a node at the origin.

## Recursion Relationships

A useful set of properties for special functions are the so-called recursion relationships. For Hermite polynomials holds, for example,

$$
\begin{equation*}
H_{n+1}(y)-2 y H_{n}(y)+2 n H_{n-1}(y)=0, \quad n=1,2, \ldots \tag{2.213}
\end{equation*}
$$

which allow one to evaluate $H_{n}(y)$ from $H_{0}(y)$ and $H_{1}(y)$ given by (2.208). Another relationship is

$$
\begin{equation*}
\frac{d}{d y} H_{n}(y)=2 n H_{n-1}(y), \quad n=1,2, \ldots \tag{2.214}
\end{equation*}
$$

We want to derive (??) using the generating function. Starting point of the derivation is the property of $w(y, z)$

$$
\begin{equation*}
\frac{\partial}{\partial z} w(y, z)-(2 y-2 z) w(y, z)=0 \tag{2.215}
\end{equation*}
$$

which can be readily verified using (2.194). Substituting expansion (2.196) into the differential equation (2.215) yields

$$
\begin{equation*}
\sum_{n=1}^{\infty} \frac{z^{n-1}}{(n-1)!} H_{n}(y)-2 y \sum_{n=0}^{\infty} \frac{z^{n}}{n!} H_{n}(y)+2 \sum_{n=0}^{\infty} \frac{z^{n+1}}{n!} H_{n}(y)=0 \tag{2.216}
\end{equation*}
$$

Combining the sums and collecting terms with identical powers of $z$

$$
\begin{equation*}
\sum_{n=1}^{\infty} \frac{z^{n}}{n!}\left[H_{n+1}(y)-2 y H_{n}(y)+2 n H_{n-1}(y)\right]+H_{1}(y)-2 y H_{0}(y)=0 \tag{2.217}
\end{equation*}
$$

gives

$$
\begin{equation*}
H_{1}(y)-2 y H_{0}(y)=0, H_{n+1}(y)-2 y H_{n}(y)+2 n H_{n-1}(y)=0, n=1,2, \ldots \tag{2.218}
\end{equation*}
$$

The reader should recognize the connection between the pattern of the differential equation (??) and the pattern of the recursion equation (??): a differential operator $d / d z$ increases the order $n$ of $H_{n}$ by one, a factor $z$ reduces the order of $H_{n}$ by one and introduces also a factor $n$. One can then readily state which differential equation of $w(y, z)$ should be equivalent to the relationship (??), namely, $d w / d y-2 z w=0$. The reader may verify that $w(y, z)$, as given in (2.194), indeed satisfies the latter relationship.

## Integral Representation of Hermite Polynomials

An integral representation of the Hermite polynomials can be derived starting from the integral

$$
\begin{equation*}
I(y)=\int_{-\infty}^{+\infty} d t e^{2 i y t-t^{2}} \tag{2.219}
\end{equation*}
$$

which can be written

$$
\begin{equation*}
I(y)=e^{-y^{2}} \int_{-\infty}^{+\infty} d t e^{-(t-i y)^{2}}=e^{-y^{2}} \int_{-\infty}^{+\infty} d z e^{-z^{2}} \tag{2.220}
\end{equation*}
$$

Using (2.247) for $a=i$ one obtains

$$
\begin{equation*}
I(y)=\sqrt{\pi} e^{-y^{2}} \tag{2.221}
\end{equation*}
$$

and, acording to the definition (2.226a),

$$
\begin{equation*}
e^{-y^{2}}=\frac{1}{\sqrt{\pi}} \int_{-\infty}^{+\infty} d t e^{2 i y t-t^{2}} \tag{2.222}
\end{equation*}
$$

Employing this expression now on the r.h.s. of the Rodrigues formula (2.200) yields

$$
\begin{equation*}
H_{n}(y)=\frac{(-1)^{n}}{\sqrt{\pi}} e^{y^{2}} \int_{-\infty}^{+\infty} d t \frac{d^{n}}{d y^{n}} e^{2 i y t-t^{2}} \tag{2.223}
\end{equation*}
$$

The identity

$$
\begin{equation*}
\frac{d^{n}}{d y^{n}} e^{2 i y t-t^{2}}=(2 i t)^{n} e^{2 i y t-t^{2}} \tag{2.224}
\end{equation*}
$$

results, finally, in the integral representation of the Hermite polynomials

$$
\begin{equation*}
H_{n}(y)=\frac{2^{n}(-i)^{n} e^{y^{2}}}{\sqrt{\pi}} \int_{-\infty}^{+\infty} d t t^{n} e^{2 i y t-t^{2}}, \quad n=0,1,2, \ldots \tag{2.225}
\end{equation*}
$$

## Orthonormality Properties

We want to derive from the generating function $(2.194,2.196)$ the orthogonality properties of the Hermite polynomials. For this purpose we consider the integral

$$
\begin{align*}
\int_{-\infty}^{+\infty} d y w(y, z) w\left(y, z^{\prime}\right) e^{-y^{2}} & =e^{2 z z^{\prime}} \int_{-\infty}^{+\infty} d y e^{-\left(y-z-z^{\prime}\right)^{2}}=\sqrt{\pi} e^{2 z z^{\prime}} \\
& =\sqrt{\pi} \sum_{n=0}^{\infty} \frac{2^{n} z^{n} z^{\prime n}}{n!} \tag{2.226}
\end{align*}
$$

Expressing the l.h.s. through a double series over Hermite polynomials using (2.194, 2.196) yields

$$
\begin{equation*}
\sum_{n, n^{\prime}=0}^{\infty} \int_{-\infty}^{+\infty} d y H_{n}(y) H_{n^{\prime}}(y) e^{-y^{2}} \frac{z^{n} z^{\prime n^{\prime}}}{n!n^{\prime}!}=\sum_{n=0}^{\infty} 2^{n} n!\sqrt{\pi} \frac{z^{n} z^{\prime n}}{n!n!} \tag{2.227}
\end{equation*}
$$

Comparing the terms of the expansions allows one to conclude the orthonormality conditions

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d y H_{n}(y) H_{n^{\prime}}(y) e^{-y^{2}}=2^{n} n!\sqrt{\pi} \delta_{n n^{\prime}} \tag{2.228}
\end{equation*}
$$



Figure 2.2: Stationary states $\phi_{n}(y)$ of the harmonic oscillator for $n=0,1,2,3,4$.

## Normalized Stationary States

The orthonormality conditions (2.228) allow us to construct normalized stationary states of the harmonic oscillator. According to (2.197) holds

$$
\begin{equation*}
\tilde{\phi}_{n}(y)=e^{-y^{2} / 2} H_{n}(y) . \tag{2.229}
\end{equation*}
$$

The normalized states are [c.f. (2.189, 2.190)]

$$
\begin{equation*}
\phi_{n}(y)=N_{n} e^{-y^{2} / 2} H_{n}(y) . \tag{2.230}
\end{equation*}
$$

and for the normalization constants $N_{n}$ follows from (2.228)

$$
\begin{equation*}
N_{n}^{2} \int_{-\infty}^{+\infty} d y e^{-y^{2}} H_{n}^{2}(y)=N_{n}^{2} 2^{n} n!\sqrt{\pi}=1 \tag{2.231}
\end{equation*}
$$

We conclude

$$
\begin{equation*}
N_{n}=\frac{1}{\sqrt{2^{n} n!\sqrt{\pi}}} \tag{2.232}
\end{equation*}
$$

and can finally state the explicit form of the normalized stationary states

$$
\begin{equation*}
\phi_{n}(y)=\frac{1}{\sqrt{2^{n} n!\sqrt{\pi}}} e^{-y^{2} / 2} H_{n}(y) . \tag{2.233}
\end{equation*}
$$

The stationary states (2.233) are presented for $n=0,1,2,3,4$ in Fig. 2.2. One can recognize, in agreement with our above discussions, that the wave functions are even for $n=0,2,4$ and odd for $n=1,3$. One can also recognize that $n$ is equal to the number of nodes of the wave function. Furthermore, the value of the wave function at $y=0$ is positive for $n=0,4$, negative for $n=2$ and vanishes for $n=1,3$, in harmony with (??).

The normalization condition (2.231) of the wave functions differs from that postulated in (2.189) by the Jacobian $d x / d y$, i.e., by

$$
\begin{equation*}
\sqrt{\left|\frac{d x}{d y}\right|}=\left[\frac{m \omega}{\hbar}\right]^{\frac{1}{4}} \tag{2.234}
\end{equation*}
$$

The explicit form of the stationary states of the harmonic oscillator in terms of the position variable $x$ is then, using (2.233) and (2.189)

$$
\begin{equation*}
\phi_{n}(x)=\frac{1}{\sqrt{2^{n} n!}}\left[\frac{m \omega}{\pi \hbar}\right]^{\frac{1}{4}} e^{-\frac{m \omega x^{2}}{2 \hbar}} H_{n}\left(\sqrt{\frac{m \omega}{\hbar}} x\right) \tag{2.235}
\end{equation*}
$$

## Completeness of the Hermite Polynomials

The Hermite polynomials are the first members of a large class of special functions which one encounters in the course of describing stationary quantum states for various potentials and in spaces of different dimensions. The Hermite polynomials are so-called orthonogal polynomials since they obey the conditions (2.228). The various orthonogal polynomials differ in the spaces $\Omega \subset \mathbb{R}$ over which they are defined and differ in a weight function $w(y)$ which enter in their orthonogality conditions. The latter are written for polynomials $p_{n}(x)$ in the general form

$$
\begin{equation*}
\int_{\Omega} d x p_{n}(x) p_{m}(x) w(x)=I_{n} \delta_{n m} \tag{2.236}
\end{equation*}
$$

where $w(x)$ is a so-called weight function with the property

$$
\begin{equation*}
w(x) \geq 0, w(x)=0 \quad \text { only at a discrete set of points } x_{k} \in \Omega \tag{2.237}
\end{equation*}
$$

and where $I_{n}$ denotes some constants. Comparision with (2.228) shows that the orthonogality condition of the Hermite polynomials is in complience with $(2.236,2.237)$ for $\Omega=\mathbb{R}, w(x)=$ $\exp \left(-x^{2}\right)$, and $I_{n}=2^{n} n!\sqrt{\pi}$.
Other examples of orthogonal polynomials are the Legendre and Jacobi polynomials which arise in solving three-dimensional stationary Schrödinger equations, the ultra-spherical harmonics which arise in $n$-dimensional Schrödinger equations and the associated Laguerre polynomials which arise for the stationary quantum states of particles moving in a Coulomb potential. In case of the Legendre polynomials, denoted by $P_{\ell}(x)$ and introduced in Sect. 5 below [c.f. $(5.150,5.151,5.156$, 5.179] holds $\Omega=[-1,1], w(x) \equiv 1$, and $I_{\ell}=2 /(2 \ell+1)$. In case of the associated Laguerre polynomials, denoted by $L_{n}^{(\alpha)}(x)$ and encountered in case of the stationary states of the nonrelativistic [see Sect. ??? and eq. ???] and relativistic [see Sect. 10.10 and eq. (10.459] hydrogen atom, holds $\Omega=\left[0,+\infty\left[, w(x)=x^{\alpha} e^{-x}, I_{n}=\Gamma(n+\alpha+1) / n!\right.\right.$ where $\Gamma(z)$ is the so-called Gamma function.
The orthogonal polynomials $p_{n}$ mentioned above have the important property that they form a complete basis in the space $\mathcal{F}$ of normalizable functions, i.e., of functions which obey

$$
\begin{equation*}
\int_{\Omega} d x f^{2}(x) w(x)=<\infty \tag{2.238}
\end{equation*}
$$

where the space is endowed with the scalar product

$$
\begin{equation*}
(f \mid g)=\int_{\Omega} d x f(x) g(x) w(x)=<\infty, \quad f, g \in \mathcal{F} \tag{2.239}
\end{equation*}
$$

As a result holds for any $f \in \mathcal{F}$

$$
\begin{equation*}
f(x)=\sum_{n} c_{n} p_{n}(x) \tag{2.240}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{n}=\frac{1}{I_{n}} \int_{\Omega} d x w(x) f(x) p_{n}(x) . \tag{2.241}
\end{equation*}
$$

The latter identity follows from (2.236). If one replaces for all $f \in \mathcal{F}: f(x) \rightarrow \sqrt{w(x)} f(x)$ and, in particular, $p_{n}(x) \rightarrow \sqrt{w(x)} p_{n}(x)$ the scalar product (2.239) becomes the conventional scalar product of quantum mechanics

$$
\begin{equation*}
\langle f \mid g\rangle=\int_{\Omega} d x f(x) g(x) \tag{2.242}
\end{equation*}
$$

Let us assume now the case of a function space governed by the norm (2.242) and the existence of a normalizable state $\psi(y, t)$ which is stationary under the action of the harmonic oscillator propagator (2.147), i.e., a state for which (2.172) holds. Since the Hermite polynomials form a complete basis for such states we can expand

$$
\begin{equation*}
\psi(y, t)=\sum_{n=0}^{\infty} c_{n}(t) e^{-y^{2} / 2} H_{n}(y) \tag{2.243}
\end{equation*}
$$

To be consistent with $(2.188,2.197)$ it must hold $c_{n}(t)=d_{n} \exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right]$ and, hence, the stationary state $\psi(y, t)$ is

$$
\begin{equation*}
\psi(y, t)=\sum_{n=0}^{\infty} d_{n} \exp \left[-i \omega\left(n+\frac{1}{2}\right) t\right] e^{-y^{2} / 2} H_{n}(y) \tag{2.244}
\end{equation*}
$$

For the state to be stationary $|\psi(x, t)|^{2}$, i.e.,

$$
\begin{equation*}
\sum_{n, m=0}^{\infty} d_{n}^{*} d_{m} \exp [i \omega(m-n) t] e^{-y^{2}} H_{n}(y) H_{m}(y) \tag{2.245}
\end{equation*}
$$

must be time-independent. The only possibility for this to be true is $d_{n}=0$, except for a single $n=n_{o}$, i.e., $\psi(y, t)$ must be identical to one of the stationary states (2.233). Therefore, the states (2.233) exhaust all stationary states of the harmonic oscillator.

## Appendix: Exponential Integral

We want to prove

$$
\begin{equation*}
I=\int_{-\infty}^{+\infty} d y_{1} \ldots \int_{-\infty}^{+\infty} d y_{n} e^{i \sum_{j, k}^{n} y_{j} a_{j k} y_{k}}=\sqrt{\frac{(i \pi)^{n}}{\operatorname{det}(\mathbf{a})}} \tag{2.246}
\end{equation*}
$$

for $\operatorname{det}(\mathbf{a}) \neq 0$ and real, symmetric a, i.e. $\mathbf{a}^{T}=\mathbf{a}$. In case of $n=1$ this reads

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d x e^{i a x^{2}}=\sqrt{\frac{i \pi}{a}} \tag{2.247}
\end{equation*}
$$

which holds for $a \in \mathbb{C}$ as long as $a \neq 0$.
The proof of (2.246) exploits that for any real, symmetric matrix exists a similarity transformation such that

$$
\mathbf{S}^{-1} \mathbf{a} \mathbf{S}=\tilde{\mathbf{a}}=\left(\begin{array}{cccc}
\tilde{a}_{11} & 0 & \ldots & 0  \tag{2.248}\\
0 & \tilde{a}_{22} & \ldots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \ldots & \tilde{a}_{n n}
\end{array}\right)
$$

where $\mathbf{S}$ can be chosen as an orthonormal transformation, i.e.,

$$
\begin{equation*}
\mathbf{S}^{T} \mathbf{S}=\mathbb{1} \quad \text { or } \quad \mathbf{S}=\mathbf{S}^{-1} . \tag{2.249}
\end{equation*}
$$

The $\tilde{a}_{k k}$ are the eigenvalues of a and are real. This property allows one to simplify the bilinear form $\sum_{j, k}^{n} y_{j} a_{j k} y_{k}$ by introducing new integration variables

$$
\begin{equation*}
\tilde{y}_{j}=\sum_{k}^{n}\left(S^{-1}\right)_{j k} y_{k} ; \quad y_{k}=\sum_{k}^{n} S_{k j} \tilde{y}_{j} . \tag{2.250}
\end{equation*}
$$

The bilinear form in (2.246) reads then in terms of $\tilde{y}_{j}$

$$
\begin{align*}
\sum_{j, k}^{n} y_{j} a_{j k} y_{k} & =\sum_{j, k}^{n} \sum_{\ell m}^{n} \tilde{y}_{\ell} S_{j \ell} a_{j k} S_{k m} \tilde{y}_{m} \\
& =\sum_{j, k}^{n} \sum_{\ell m}^{n} \tilde{y}_{\ell}\left(S^{T}\right)_{\ell j} a_{j k} S_{k m} \tilde{y}_{m} \\
& =\sum_{j, k}^{n} \tilde{y}_{j} \tilde{a}_{j k} \tilde{y}_{k} \tag{2.251}
\end{align*}
$$

where, according to ( $2.248,2.249$ )

$$
\begin{equation*}
\tilde{a}_{j k}=\sum_{l, m}^{n}\left(S^{T}\right)_{j l} a_{l m} S_{m k} . \tag{2.252}
\end{equation*}
$$

For the determinant of ã holds

$$
\begin{equation*}
\operatorname{det}(\tilde{\mathbf{a}})=\prod_{j=1}^{n} \tilde{a}_{j j} \tag{2.253}
\end{equation*}
$$

as well as

$$
\begin{align*}
\operatorname{det}(\tilde{\mathbf{a}}) & =\operatorname{det}\left(\mathbf{S}^{-1} \mathbf{a S}\right)=\operatorname{det}\left(\mathbf{S}^{-1}\right) \operatorname{det}(\mathbf{a}), \operatorname{det}(\mathbf{S}) \\
& =(\operatorname{det}(\mathbf{S}))^{-1} \operatorname{det}(\mathbf{a}) \operatorname{det}(\mathbf{S})=\operatorname{det}(\mathbf{a}) \tag{2.254}
\end{align*}
$$

One can conclude

$$
\begin{equation*}
\operatorname{det}(\mathbf{a})=\prod_{j=1}^{n} \tilde{a}_{j j} \tag{2.255}
\end{equation*}
$$

We have assumed $\operatorname{det}(\mathbf{a}) \neq 0$. Accordingly, holds

$$
\begin{equation*}
\prod_{j=1}^{n} \tilde{a}_{j j} \neq 0 \tag{2.256}
\end{equation*}
$$

such that none of the eigenvalues of $\mathbf{a}$ vanishes, i.e.,

$$
\begin{equation*}
\tilde{a}_{j j} \neq 0, \quad \text { for } j=1,2, \ldots, n \tag{2.257}
\end{equation*}
$$

Substitution of the integration variables (2.250) allows one to express (2.250)

$$
\begin{equation*}
I=\int_{-\infty}^{+\infty} d \tilde{y}_{1} \ldots \int_{-\infty}^{+\infty} d \tilde{y}_{n}\left|\operatorname{det}\left(\frac{\partial\left(y_{1}, \ldots, y_{n}\right)}{\partial\left(\tilde{y}_{1}, \ldots, \tilde{y}_{n}\right)}\right)\right| e^{i \sum_{k}^{n} \tilde{a}_{k k} \tilde{y}_{k}^{2}} \tag{2.258}
\end{equation*}
$$

where we introduced the Jacobian matrix

$$
\begin{equation*}
\mathbf{J}=\frac{\partial\left(y_{1}, \ldots, y_{n}\right)}{\partial\left(\tilde{y}_{1}, \ldots, \tilde{y}_{n}\right)} \tag{2.259}
\end{equation*}
$$

with elements

$$
\begin{equation*}
J_{j s}=\frac{\partial y_{j}}{\partial \tilde{y}_{s}} . \tag{2.260}
\end{equation*}
$$

According to (2.250) holds

$$
\begin{equation*}
\mathbf{J}=\mathbf{S} \tag{2.261}
\end{equation*}
$$

and, hence,

$$
\begin{equation*}
\operatorname{det}\left(\frac{\partial\left(y_{1}, \ldots, y_{n}\right)}{\partial\left(\tilde{y}_{1}, \ldots, \tilde{y}_{n}\right)}\right)=\operatorname{det}(\mathbf{S}) \tag{2.262}
\end{equation*}
$$

From (2.249) follows

$$
\begin{equation*}
1=\operatorname{det}\left(\mathbf{S}^{T} \mathbf{S}\right)=(\operatorname{det} \mathbf{S})^{2} \tag{2.263}
\end{equation*}
$$

such that one can conclude

$$
\begin{equation*}
\operatorname{det} \mathbf{S}= \pm 1 \tag{2.264}
\end{equation*}
$$

One can right then (2.258)

$$
\begin{align*}
I & =\int_{-\infty}^{+\infty} d \tilde{y}_{1} \ldots \int_{-\infty}^{+\infty} d \tilde{y}_{n} e^{i \sum_{k}^{n} \tilde{a}_{k k} \tilde{y}_{k}^{2}} \\
& =\int_{-\infty}^{+\infty} d \tilde{y}_{1} e^{i \tilde{a}_{11} \tilde{y}_{1}^{2}} \ldots \int_{-\infty}^{+\infty} d \tilde{y}_{n} e^{i \tilde{a}_{n n} \tilde{y}_{n}^{2}}=\prod_{k=1}^{n} \int_{-\infty}^{+\infty} d \tilde{y}_{k} e^{i \tilde{a}_{k k} \tilde{y}_{k}^{2}} \tag{2.265}
\end{align*}
$$

which leaves us to determine integrals of the type

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d x e^{i c x^{2}} \tag{2.266}
\end{equation*}
$$

where, according to (2.257) holds $c \neq 0$.
We consider first the case $c>0$ and discuss the case $c<0$ further below. One can relate integral (2.266) to the well-known Gaussian integral

$$
\begin{equation*}
\int_{-\infty}^{+\infty} d x e^{-c x^{2}}=\sqrt{\frac{\pi}{c}}, c>0 \tag{2.267}
\end{equation*}
$$

by considering the contour integral

$$
\begin{equation*}
J=\oint_{\gamma} d z e^{i c z^{2}}=0 \tag{2.268}
\end{equation*}
$$

along the path $\gamma=\gamma_{1}+\gamma_{2}+\gamma_{3}+\gamma_{4}$ displayed in Figure 2.3. The contour integral (2.268) vanishes, since $e^{i c z^{2}}$ is a holomorphic function, i.e., the integrand does not exhibit any singularities anywhere in $\mathbb{C}$. The contour intergral $(2.268)$ can be written as the sum of the following path integrals

$$
\begin{equation*}
J=J_{1}+J_{2}+J_{3}+J_{4} ; \quad J_{k}=\oint_{\gamma_{k}} d z e^{i c z^{2}} \tag{2.269}
\end{equation*}
$$

The contributions $J_{k}$ can be expressed through integrals along a real coordinate axis by realizing that the paths $\gamma_{k}$ can be parametrized by real coordinates $x$

$$
\begin{array}{rlrl}
\gamma_{1}: z=x & J_{1} & =\int_{-p}^{p} d x e^{i c x^{2}} \\
\gamma_{2}: z=i x+p & J_{2} & =\int_{0}^{p} i d x e^{i c(i x+p)^{2}} \\
\gamma_{3}: z=\sqrt{i} x & J_{3} & =\int_{\sqrt{2} p}^{-\sqrt{2} p} \sqrt{i} d x e^{i c(\sqrt{i} x)^{2}} \\
& =-\sqrt{i} \int_{-\sqrt{2} p}^{\sqrt{2} p} d x e^{-c x^{2}} \\
\gamma_{4}: z=i x-p & J_{4} & =\int_{-p}^{0} i d x e^{i c(i x-p)^{2}},
\end{array}
$$

Substituting $-x$ for $x$ into integral $J_{4}$ one obtains

$$
\begin{align*}
J_{4} & =\int_{p}^{0}(-i) d x e^{i c(-i x+p)^{2}} \\
& =\int_{0}^{p} i d x e^{i c(i x-p)^{2}}=J_{2} . \tag{2.271}
\end{align*}
$$



Figure 2.3: Contour path $\gamma$ in the complex plain.

We will now show that the two integrals $J_{2}$ and $J_{4}$ vanish for $p \rightarrow+\infty$. This follows from the following calculation

$$
\begin{align*}
\lim _{p \rightarrow+\infty}\left|J_{2 \text { or } 4}\right| & =\lim _{p \rightarrow+\infty}\left|\int_{0}^{p} i d x e^{i c(i x+p)^{2}}\right| \\
& \leq \lim _{p \rightarrow+\infty} \int_{0}^{p}|i| d x\left|e^{i c\left(p^{2}-x^{2}\right)}\right|\left|e^{-2 c x p}\right| \tag{2.272}
\end{align*}
$$

It holds $\left|e^{i c\left(p^{2}-x^{2}\right)}\right|=1$ since the exponent of $e$ is purely imaginary. Hence,

$$
\begin{align*}
\lim _{p \rightarrow+\infty} \mid J_{2} \text { or } 4 \mid & \leq \lim _{p \rightarrow+\infty} \int_{0}^{p} d x\left|e^{-2 c x p}\right| \\
& =\lim _{p \rightarrow+\infty} \frac{1-e^{-2 c p}}{2 c p}=0 \tag{2.273}
\end{align*}
$$

$J_{2}$ and $J_{4}$ do not contribute then to integral (2.268) for $p=+\infty$. One can state accordingly

$$
\begin{equation*}
J=\int_{-\infty}^{\infty} d x e^{i c x^{2}}-\sqrt{i} \int_{-\infty}^{\infty} d x e^{-c x^{2}}=0 \tag{2.274}
\end{equation*}
$$

Using 2.267) one has shown then

$$
\begin{equation*}
\int_{-\infty}^{\infty} d x e^{i c x^{2}}=\sqrt{\frac{i \pi}{c}} \tag{2.275}
\end{equation*}
$$

One can derive the same result for $c<0$, if one chooses the same contour integral as (2.268), but with a path $\gamma$ that is reflected at the real axis. This leads to

$$
\begin{equation*}
J=\int_{-\infty}^{\infty} d x e^{i c x^{2}}+\sqrt{-i} \int_{\infty}^{-\infty} d x e^{c x^{2}}=0 \tag{2.276}
\end{equation*}
$$

and $(c<0)$

$$
\begin{equation*}
\int_{-\infty}^{\infty} d x e^{i c x^{2}}=\sqrt{\frac{-i \pi}{-|c|}}=\sqrt{\frac{i \pi}{c}} \tag{2.277}
\end{equation*}
$$

We apply the above results $(2.275,2.277)$ to (2.265). It holds

$$
\begin{equation*}
I=\prod_{k=1}^{n} \sqrt{\frac{i \pi}{\tilde{a}_{k k}}}=\sqrt{\frac{(i \pi)^{n}}{\prod_{j=1}^{n} \tilde{a}_{j j}}} . \tag{2.278}
\end{equation*}
$$

Noting (2.255) this result can be expressed in terms of the matrix a

$$
\begin{equation*}
I=\sqrt{\frac{(i \pi)^{n}}{\operatorname{det}(\mathbf{a})}} \tag{2.279}
\end{equation*}
$$

which concludes our proof.


[^0]:    ${ }^{1}$ We have denoted explicitly that the action integral for a path connecting the space-time points $\left(x_{0}, t_{0}\right)$ and $\left(x_{N}, t_{N}\right)$ is to be evaluated.

[^1]:    ${ }^{2}$ The reader may want to verify that the contribution of $\delta L$ to the action integral is actually equal to the differential $\delta S\left[x_{c l}, y(t)\right]$ which vanishes according to the Hamiltonian principle as discussed in Sect. 1.

[^2]:    ${ }^{3}$ generatingfunctionology by H.S.Wilf (Academic Press, Inc., Boston, 1990) is a useful introduction to this tool as is a chapter in the eminently useful Concrete Mathematics by R.L.Graham, D.E.Knuth, and O.Patashnik (AddisonWesley, Reading, Massachusetts, 1989).

