

REVIEW

Maps of Manifolds

$\phi: M \rightarrow M'$ is a map between manifolds

(is a C^r map if the corresponding map of coordinates is C^r)

$$\begin{array}{ccc} M & \xrightarrow{\phi} & M' \\ x \downarrow & & y \downarrow \\ \mathbb{R}^n & & \mathbb{R}^m \end{array} \quad \text{so } y \circ \phi \circ x^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}^m \text{ is } C^r$$

Notes:

- In genl not one-to-one
- Even if one-to-one may not have an inverse

So it goes one way.

Let $f: M' \rightarrow \mathbb{R}$ a function on M'
(a "scalar" field)

then ϕ defines a function on M , $\phi^* f$

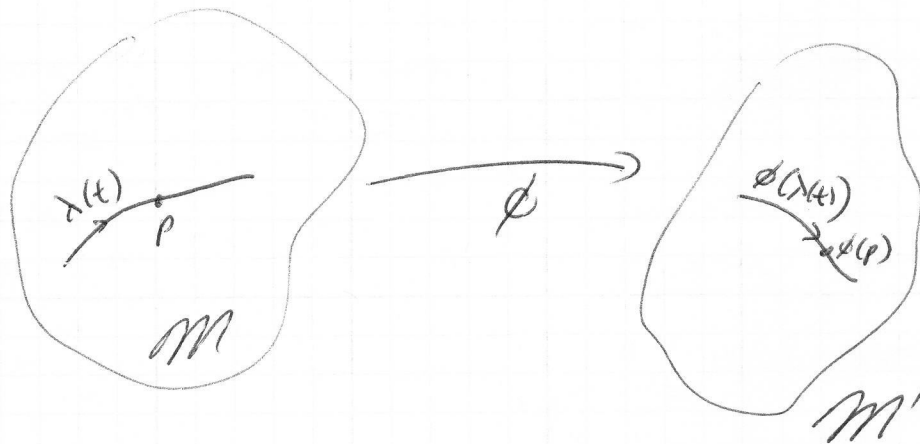
$$\phi^* f: M \rightarrow \mathbb{R}$$

defined by $M \xrightarrow{\phi} M' \rightarrow \mathbb{R}$

ie if $p \in M$ then $\phi(p) \in M'$ and $f(\phi(p))$ is defined.

(This is a "pull-back" of a zero form)

Go the other direction



By mapping curves $\lambda(t)$ in M into M' we can get maps of tangent vectors.

If $T_p(M)$ is the tangent space to M at p then
 push-forward
 $\phi_* : T_p(M) \rightarrow T_{\phi(p)}(M')$

defined by mapping $\left(\frac{\partial}{\partial t}\right)_\lambda \rightarrow \left(\frac{\partial}{\partial t}\right)_{\phi(\lambda)}$ (denote this by $\phi_* \left(\frac{\partial}{\partial t}\right)_\lambda$)

This is a linear transformation between the vector spaces: if x^m and y^a are local coordinates on patches of M & M' , then the curve is $x^m(t)$, mapped into $y^a(x^m(t))$ and

$$\frac{dy^a}{dt} \Big|_0 = \frac{\partial y^a}{\partial x^m} \Big|_p \frac{dx^m}{dt} \Big|_0$$

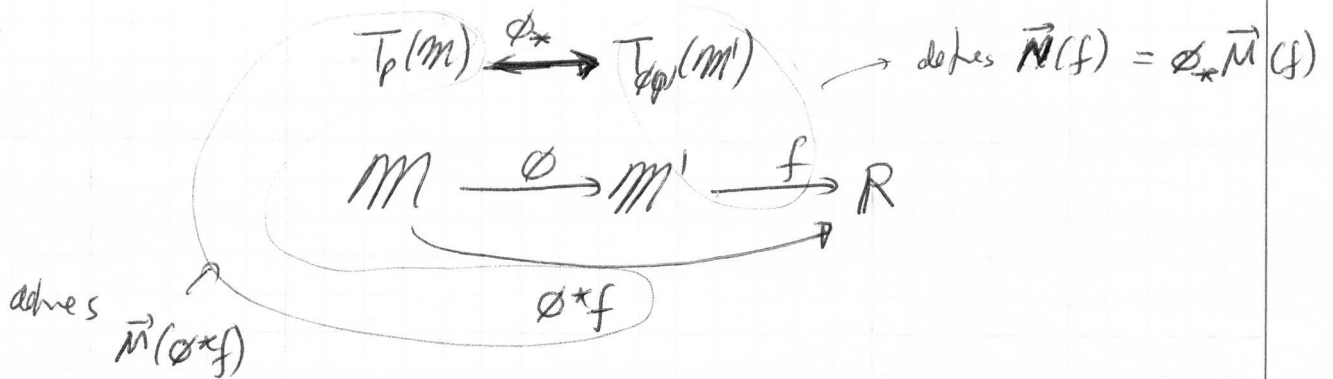
or $N^a = \frac{\partial y^a}{\partial x^m} \Big|_p M^m$ where $\vec{N} \in T_{\phi(p)}(M')$
 $\vec{M} \in T_p(M)$

so ϕ_* is just the matrix $\frac{\partial y^a}{\partial x^m} \Big|_p$. and we write $\vec{N} = \phi_* \vec{M}$

Since a vector \vec{M} is a directional derivative, we use $\vec{M}(f)$ defined.

A vector gives a map of any function f at p into a number. If $\vec{M} = \frac{\partial}{\partial t}$ then $\vec{M}(f) = \frac{df}{dt} \Big|_{p=\lambda(t_0)}$ i.e. the derivative of f along $\lambda(t)$.

Explicitly $\frac{df}{dt}(x(t)) = \frac{df}{dx^a} \dot{x}^a$ so the action of the vector \vec{A} with coordinates a^m on f is $\vec{A}(f) = a^m \frac{\partial f}{\partial x^m}$.



$$\vec{M}(\phi^*f) \Big|_p = \phi_* \vec{M}(f) \Big|_{\phi(p)}$$

check:

$$m^a \frac{\partial}{\partial x^a} (f(\phi(x))) \Big|_p = m^a \frac{\partial f}{\partial y^a} \Big|_{\phi(p)} \frac{\partial y^a}{\partial x^m} \Big|_p = (m^a \frac{\partial y^a}{\partial x^m}) \frac{\partial f}{\partial y^a} \Big|_{\phi(p)}$$

= m^a components of $\phi_* \vec{M}$

Students: should always flesh out relations in terms of coordinate patches, to make sure they understand.

Go on to 1-forms: define pull-back

$$\phi^*: T_p^*(M') \rightarrow T_p^*(M)$$

by requiring the contraction is mapped properly: $\phi^*: \tilde{\omega} \rightarrow \phi^* \tilde{\omega}$

$$\left(\phi^*: \tilde{\omega} \in T_{\phi(p)}^*(M') \rightarrow \phi^* \tilde{\omega} \in T_p^*(M) \right)$$

with $\boxed{\tilde{\omega}(\phi_* \vec{M}) = \phi^* \tilde{\omega}(\vec{M})}$

~~defines $\phi^* \tilde{\omega}$~~

~~Recall~~

$$T_p \xrightarrow{\phi_*} T_{\phi(p)}$$

$$M \xrightarrow{\phi} M'$$

$$T_p^* \xleftarrow{\phi^*} T_{\phi(p)}^*$$

Recall $\tilde{\omega}(\vec{N})$ is a number, ie $\tilde{\omega}$ is a map from $T_p \rightarrow \mathbb{R}$.
 (In components $\tilde{\omega}(\vec{N})|_p = \omega_a N^a|_p$, the index contraction.
 Some texts write $\langle \tilde{\omega}, \vec{N} \rangle$).

So the def above gives the action of $\phi^* \tilde{\omega}$ on vectors $\vec{M} \in T_p(M)$
 in terms of the action of $\tilde{\omega}$ on vectors $\vec{N} \in T_{\phi(p)}(M')$, which is
 (In components $(\phi^* \tilde{\omega})_\mu M^\mu = \omega_a N^a = \omega_a \frac{\partial y^a}{\partial x^\mu} M^\mu$

that is $(\phi^* \tilde{\omega})_\mu = \omega_a \frac{\partial y^a}{\partial x^\mu}$).

In particular $\phi^*(df) = d(\phi^* f)$

(In components $df = f_{,a} dy^a$ $\phi^*(df) = f_{,a} \frac{\partial y^a}{\partial x^\mu} dx^\mu$

while $d(\phi^* f) = df(y(x)) = \left(\frac{\partial f}{\partial y^a} \frac{\partial y^a}{\partial x^\mu} \right) dx^\mu$ ✓).

Clearly this can be extended to tensors of type T_0^r and T_r^0

$$\phi_* : T_0^r(p) \rightarrow T_0^r(\phi(p))$$

recall $T \in T_0^r(p)$ ~~acts~~ acts on r 1-forms $T(\tilde{\omega}^1, \dots, \tilde{\omega}^r) \in \mathbb{R}$

so $T \rightarrow \phi_* T$ by $T(\phi^* \tilde{\omega}^1, \dots, \phi^* \tilde{\omega}^r) = \phi_* T(\tilde{\omega}^1, \dots, \tilde{\omega}^r)$

And $T \in T_r^0$ acts on r vectors so $\phi^* : T_r^0(\phi(p)) \rightarrow T_r^0(p)$

$$\phi^* T(\vec{M}_1, \dots, \vec{M}_r) = T(\phi_* \vec{M}_1, \dots, \phi_* \vec{M}_r)$$

In components: $T_{a_1 \dots a_r} = \frac{\partial y^{a_1}}{\partial x^{m_1}} \dots \frac{\partial y^{a_r}}{\partial x^{m_r}} T_{m_1 \dots m_r}$

$$\phi^* : T_{m_1 \dots m_r} = \frac{\partial y^{a_1}}{\partial x^{m_1}} \dots \frac{\partial y^{a_r}}{\partial x^{m_r}} T_{a_1 \dots a_r}$$

Def Rank : $\phi : M \rightarrow M'$ is rank k at p if the dimension of the tangent space at $\phi(p)$ ($\phi_*(T_p(M))$) is k .

Injective ϕ above is injective^(at p) if rank = dimension of M
 $k = n$.

(In this case $n \leq n'$).

Exercise: If ϕ is injective then no non-zero vectors in $T_p(M)$ are mapped to zero by ϕ_*

Surjective: ϕ is surjective if $\text{rank of } \phi =$
dimension of M'
 $k = n'$

(So that $n \geq n'$).

~~(Immersion: ϕ is an immersion if it has an inverse ϕ^{-1}
(with same differentiability as ϕ) such that~~

~~for each $p \in M$ there is $U \subset M$ with $p \in U$~~

~~$\phi^{-1}: \phi(U) \rightarrow U$~~

(Skip immersion: it ~~is~~ is subtle only when C^r properties matter)

If ϕ is injective $\forall p \in M$ we say ϕ is an
immersion (actually, def'n of immersion is ~~of~~ given in terms of
existence of differentiable inverse of ϕ , and then equivalence of stat's
is proved) $\Rightarrow \phi_x: T_p \rightarrow \phi_x(T_p) \subset T_{\phi(p)}$ is an
isomorphism.

Then $\phi(M) \subset M'$ is an n -dimensional immersed
submanifold in M' .

This is one-one locally, but may not be so globally.

An embedding is, basically, an immersion that is one-one (actually
a homeomorphism onto its image).

Diffeomorphism: one-to-one map $\phi: M \rightarrow M'$ with
inverse $\phi^{-1}: M' \rightarrow M$.

Then $n=n'=k$, ϕ is injective and surjective.

Thm: If ϕ_x is injective and surjective at p then there is
an open $U \subset M$, $p \in U$ + $\phi: U \rightarrow \phi(U)$ is a diffeomorphism.

That is if $\phi_x: T_p \rightarrow T_{\phi(p)}$ is an isomorphism

then ϕ is a local diffeomorphism.

With a diffeomorphism we can go with $\phi_x: T_p(M) \rightarrow T_{\phi(p)}(M')$

and with $(\phi^{-1})^*: T_p^*(M) \rightarrow T_{\phi(p)}^*(M')$

So for any tensor T

$$T(\tilde{\omega}^1, \dots, \tilde{\omega}^s, \vec{M}_1, \dots, \vec{M}_r) \Big|_p = \phi_* T(\phi^{-1})^* \tilde{\omega}^1, \dots, (\phi^{-1})^* \tilde{\omega}^s, \phi_* M_1, \dots, \phi_* M_r \Big|_{\phi(p)}$$

Differentiation without a connection

Two types arise naturally:

- Exterior derivative
- Lie derivative

Exterior derivative $d: \Omega_s \rightarrow \Omega_{s+1}$

Ω_s : linear space of s -forms $\tilde{a} = a_{\mu_1 \dots \mu_s} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_s}$

($\Omega_s \subset T_s^0$, is the totally antisymmetric T_s^0 tensors).

Recall if $\tilde{a} \wedge \tilde{b}$ are p & q forms, $\tilde{a} \wedge \tilde{b} = (-1)^{pq} \tilde{b} \wedge \tilde{a}$.

d acts by

$$d\tilde{a} = da_{\mu_1 \dots \mu_s} \wedge dx^{\mu_1} \wedge \dots \wedge dx^{\mu_s}$$
$$= \frac{\partial a_{\mu_1 \dots \mu_s}}{\partial x^\sigma} dx^\sigma \wedge dx^{\mu_1} \wedge \dots \wedge dx^{\mu_s}$$

Exercise: show

- this is indeed a T_{s+1}^0 (tensor) (obvious from first line)
- $d(a \wedge b) = da \wedge b + (-1)^s a \wedge db$ if a is an s -form
- $d(d\tilde{a}) = 0$
- $d(\phi^* \tilde{a}) = \phi^*(d\tilde{a})$

Useful integration results (reminder)

if ϕ is a diffeomorphism
and \tilde{a} is an n -form
($n = \dim M$)

$$\int_M \tilde{a} = \int_{M' = \phi(M)} \phi_* \tilde{a}$$

If \tilde{b} is an $n-1$ form

$$\int_{\partial M} \tilde{b} = \int_M d\tilde{b}$$

Stoke's theorem.

Lie derivative

Let \vec{M} vector field on M
 Thm. \Leftrightarrow unique ~~point~~ ^{curve $\lambda(t)$} through p with $\lambda(0) = p$ and $\vec{M} = \frac{d}{dt}$
 (Fundamental of diff. eqs)

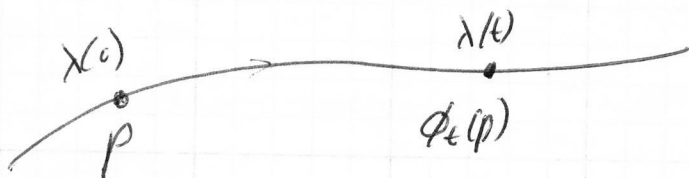
With locally, with coordinates x^M , $\lambda(t)$ is $x^M(t)$ with tangent $\frac{dx^M}{dt}$; so the theorem above is the statement of uniqueness of solution of

$$\frac{dx^M}{dt} = M^M(x(t))$$

$\lambda(t)$ is the "integral curve of \vec{M} "



Given \vec{M} we can construct a diffeomorphism ϕ_t of M into itself (actually from small open neighborhoods $U \ni p$ into M), that maps p into the point along the curve a distance ~~distance~~ ^{parameter} t away

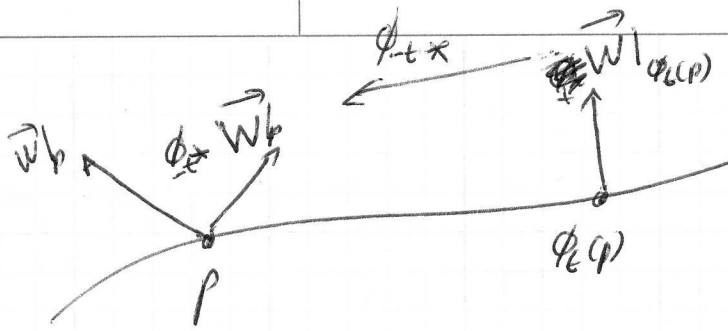


(Note ϕ_t forms a one parameter local group of diffeomorphisms.

$$\phi_{t+s} = \phi_t \circ \phi_s = \phi_s \circ \phi_t \quad \phi_{-t} = (\phi_t)^{-1} \quad \phi_0 = \text{identity})$$

From ϕ_t construct $\phi_{t*} : T_p^s(M) \rightarrow T_{\phi_t(p)}^s(M)$

$$T|_p \rightarrow \phi_{t*} T|_{\phi_t(p)}$$



Since $\phi_{t,x}$ is a diffeomorphism, $\phi_{t,x}$ is an isomorphism, we can directly compare $\phi_{t,x}^* T$ with T . Let the Lie derivative at p be

$$L_{\vec{M}} T = \lim_{t \rightarrow 0} \frac{1}{t} [\phi_{t,x}^* T - T]$$

Note: both etc.

Properties:

(i) If $T \in T_s^r(p) \Rightarrow L_{\vec{M}} T \in T_s^r(p)$

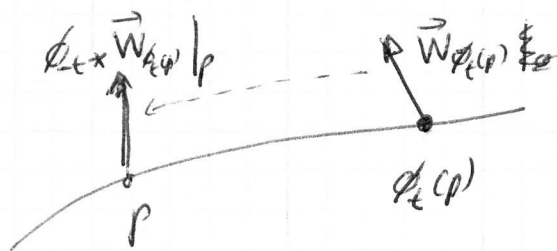
(ii) $L_{\vec{M}}$ is linear

(iii) $L_{\vec{M}}$ preserves contraction

(iv) $L_{\vec{M}} (T \otimes S) = L_{\vec{M}} T \otimes S + T \otimes L_{\vec{M}} S$

(v) $L_{\vec{M}} f = \vec{M}(f)$ (if a form $f: M \rightarrow \mathbb{R}$)

Get $L_{\vec{M}} \vec{W}$ explicitly:



Recall $M \xrightarrow{\phi} M'$

then $\vec{W}_p \rightarrow \phi_* \vec{W}|_{\phi(p)}$

$$\text{means } W^m \rightarrow (\phi_* W)^a = \frac{\partial x^a}{\partial x^m} \Big|_{\phi(p)} W^m \Big|_p$$

Moreover, for our case ϕ_{t*} at p is what? Take

$M \xrightarrow{\phi_t} M'$

$\vec{W}_{\phi_t(p)} \rightarrow \phi_{t*} \vec{W}|_p$

$$(\phi_{t*} W)^a \Big|_p = \frac{\partial x^a}{\partial x^m} \Big|_{\phi_t(p)} W^m \Big|_{\phi_t(p)}$$

But $y^a(x^m)$ is just the shift in coordinates along the curve:
 x^a are the coordinates of p , i.e. \rightarrow of x^m , the coordinates of $\phi_t(p)$.

If the curve is the integral of $\frac{dx^m}{dt} = M^m$ (\vec{M} a vector field).

Then, $x^m(t) = x^m(0) + t M^m$ to order t , and $y^a(x^m)$ is just

$$x^m(0) = x^m(t) - t M^m \quad \text{so} \quad \frac{\partial x^a}{\partial x^m} \Big|_{\phi_t(p)} = \delta^a_m - M^v_{,m} t$$

$W^m \Big|_{\phi_t(p)}$ is just $W^m(x^m(t)) = W^m(x^m(0) + t M^m) = W^m \Big|_p + t M^v W^m_{,v} \Big|_p$

$$\text{so } \phi_{t*} W \Big|_p - W \Big|_p = (\delta^v_m - M^v_{,m} t) (W^m + t M^v W^m_{,v}) - W^v$$

$$\text{and } (L_{\vec{M}} \vec{W})^a = M^v W^a_{,v} - W^v M^a_{,v} = [M, W]^a$$

"Lie bracket"
"commutator"

In particular, this shows $L_{\vec{M}} \vec{W} = -L_{\vec{W}} \vec{M}$

From this, ~~then~~ one can obtain ~~the~~ the action of $L_{\vec{M}}$ on other tensors:

$$L_{\vec{M}} (\tilde{\omega} \otimes \vec{W}) = L_{\vec{M}} \tilde{\omega} \otimes \vec{W} + \tilde{\omega} \otimes L_{\vec{M}} \vec{W}$$

now, contracting \Rightarrow

$$L_{\vec{M}} (\tilde{\omega}(\vec{W})) = L_{\vec{M}} \tilde{\omega}(\vec{W}) + \tilde{\omega}(L_{\vec{M}} \vec{W})$$

Now if we use $\vec{W} = \vec{E}_\mu$, a basis vector we can get $L_{\vec{M}} \tilde{\omega}$.

In particular, if $\vec{E}_\mu = \frac{\partial}{\partial x^\mu}$, the coordinate basis, then

$$L_{\vec{M}}(\tilde{\omega})(\vec{E}_\mu) = (L_{\vec{M}}(\tilde{\omega}))^\nu_{\mu} \quad \text{the components we are looking for.}$$

$$\begin{aligned} L_{\vec{M}}(\tilde{\omega})(\vec{E}_\mu) &= L_{\vec{M}}(\omega_\mu) = \vec{M}(\omega_\mu) \quad (\text{property (4)}) \\ &= \frac{\partial \omega_\mu}{\partial x^\nu} M^\nu = \omega_{\mu,\nu} M^\nu \end{aligned}$$

$$\text{and } \tilde{\omega}(L_{\vec{M}}(\vec{E}_\mu))^\nu = \frac{\partial (\vec{E}_\mu)^\nu}{\partial x^\rho} M^\rho - \frac{\partial M^\nu}{\partial x^\rho} (\vec{E}_\mu)^\rho = -\frac{\partial M^\nu}{\partial x^\mu}$$

$$\text{so } \tilde{\omega}(L_{\vec{M}}(\vec{E}_\mu))^\nu = -\omega_{\nu,\mu} M^\nu$$

$$\Rightarrow (L_{\vec{M}}(\tilde{\omega}))^\nu_{\mu} = \omega_{\mu,\nu} M^\nu + M^\nu_{,\mu} \omega_\nu$$

Exercise: Show

$$\begin{aligned}
 \mathcal{L}_M T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l} &= M^\sigma \partial_\sigma T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l} \\
 &- (\partial_\lambda M^{\mu_1}) T^{\lambda \mu_2 \dots \mu_k}_{\nu_1 \dots \nu_l} \\
 &- (\partial_\lambda M^{\mu_2}) T^{\mu_1 \lambda \dots \mu_k}_{\nu_1 \dots \nu_l} \\
 &\vdots \\
 &+ (\partial_{\nu_1} M^\lambda) T^{\mu_1 \dots \mu_k}_{\lambda \nu_2 \dots \nu_l} \\
 &+ (\partial_{\nu_2} M^\lambda) T^{\mu_1 \dots \mu_k}_{\nu_1 \lambda \dots \nu_l}
 \end{aligned}$$

In particular

$$\mathcal{L}_M g_{\mu\nu} = M^\sigma \partial_\sigma g_{\mu\nu} + \partial_\mu M^\lambda g_{\lambda\nu} + \partial_\nu M^\lambda g_{\mu\lambda}$$

Since these are tensors equations, we can replace ∂ by ∇ .

$$\Rightarrow \mathcal{L}_M g_{\mu\nu} = M^\lambda \nabla_{\mu} g_{\lambda\nu} + M^\lambda \nabla_{\nu} g_{\mu\lambda} = M_{\nu\mu;\lambda} + M_{\mu\nu;\lambda}$$

or

$$\boxed{\mathcal{L}_M g_{\mu\nu} = 2 M_{(\mu;\nu)}}$$

~~Easy~~ This is useful stuff. We will use it for symmetries later, but ~~the~~ here is a simple application. Assume the action for GR breaks down into

$$S = S_G(g_{\mu\nu}) + S_M(g_{\mu\nu}, \psi) \quad (\star)$$

ψ = matter fields

S_G = "Hilbert" action (Gives Einstein's eqs -- we'll use this later, it came).

Consider This theory is "diffeomorphism invariant": ~~the~~ $g_{\mu\nu}$ $\phi: M \rightarrow M$
 $(M, g_{\mu\nu}, \psi)$ and $(M, \phi^* g_{\mu\nu}, \phi^* \psi)$

represent the same physics. The change is S_M under a diffeomorphism

$$\delta S_M = \int d^4x \frac{\delta S_M}{\delta g_{\mu\nu}} \delta g_{\mu\nu} + \int d^4x \frac{\delta S_M}{\delta \psi} \delta \psi$$

Since we could have set $\psi=0$, δS_G can be considered separately (it is invariant by itself; here is where the separation assumption in (\star) come in).

But $\frac{\delta S_M}{\delta \psi} = 0$ for any variation. So while here we look only at variations from diffeomorphisms, that term vanishes separately for any variation. Left with first term, we consider diffeomorphisms generated by a vector field U^μ :

$$\delta g_{\mu\nu} = \mathcal{L}_U g_{\mu\nu} = 2 U_{(\mu;\nu)}$$

$$\Rightarrow \delta S_M = 0 = \int d^4x \frac{\delta S_M}{\delta g_{\mu\nu}} 2 U_{(\mu;\nu)} = 4 \int d^4x \frac{\delta S_M}{\delta g_{\mu\nu}} U_{\mu;\nu}$$

or

$$= 4 \int d^4x \left(\left[\frac{\delta S_M}{\delta g_{\mu\nu}} U_\mu \right]_{;\nu} - U_\mu \left(\frac{\delta S_M}{\delta g_{\mu\nu}} \right)_{;\nu} \right)$$

Dropping the surface term and multiplying by $\frac{\sqrt{g}}{\sqrt{g}}$ we have

$$\int dV U_\mu \nabla_\nu \left[\frac{1}{\sqrt{g}} \frac{\delta S_M}{\delta g_{\mu\nu}} \right] = 0$$

Since this holds for arbitrary U_μ (diffeomorphisms generated by arbitrary vector fields) it must be that

$$\nabla_\nu \left(\frac{1}{\sqrt{g}} \frac{\delta S_M}{\delta g_{\mu\nu}} \right) = 0$$

But

$$T^{\mu\nu} \equiv \frac{1}{\sqrt{g}} \frac{\delta S_M}{\delta g_{\mu\nu}}$$

is the energy-momentum tensor.

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