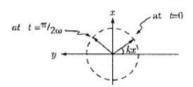
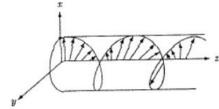
Problem 9.8

(a) $\mathbf{f}_v(z,t) = A\cos(kz - \omega t)\,\hat{\mathbf{x}}; \ \mathbf{f}_h(z,t) = A\cos(kz - \omega t + 90^\circ)\,\hat{\mathbf{y}} = -A\sin(kz - \omega t)\,\hat{\mathbf{y}}.$ Since $f_v^2 + f_h^2 = A^2$, the vector sum $\mathbf{f} = \mathbf{f}_v + \mathbf{f}_h$ lies on a circle of radius A. At time t = 0, $\mathbf{f} = A\cos(kz)\,\hat{\mathbf{x}} - A\sin(kz)\,\hat{\mathbf{y}}.$ At time $t = \pi/2\omega$, $\mathbf{f} = A\cos(kz-90^\circ)\,\hat{\mathbf{x}} - A\sin(kz-90^\circ)\,\hat{\mathbf{y}} = A\sin(kz)\,\hat{\mathbf{x}} + A\cos(kz)\,\hat{\mathbf{y}}.$ Evidently it circles counterclockwise. To make a wave circling the other way, use $\delta_h = -90^\circ.$





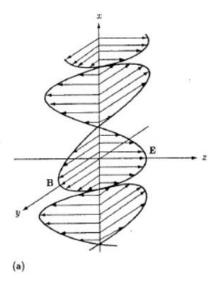


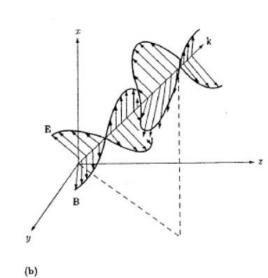
(c) Shake it around in a circle, instead of up and down.

Problem 9.9

$$\mathbf{(a)} \ \boxed{\mathbf{k} = -\frac{\omega}{c} \, \hat{\mathbf{x}}; \ \hat{\mathbf{n}} = \hat{\mathbf{z}}.} \ \mathbf{k} \cdot \mathbf{r} = \left(-\frac{\omega}{c} \, \hat{\mathbf{x}} \right) \cdot \left(x \, \hat{\mathbf{x}} + y \, \hat{\mathbf{y}} + z \, \hat{\mathbf{z}} \right) = -\frac{\omega}{c} x; \ \mathbf{k} \times \hat{\mathbf{n}} = -\hat{\mathbf{x}} \times \hat{\mathbf{z}} = \hat{\mathbf{y}}.$$

$$\mathbf{E}(x,t) = E_0 \cos\left(\frac{\omega}{c}x + \omega t\right)\hat{\mathbf{z}}; \quad \mathbf{B}(x,t) = \frac{E_0}{c} \cos\left(\frac{\omega}{c}x + \omega t\right)\hat{\mathbf{y}}.$$





(b)
$$k = \frac{\omega}{c} \left(\frac{\hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}}{\sqrt{3}} \right)$$
; $\hat{\mathbf{n}} = \frac{\hat{\mathbf{x}} - \hat{\mathbf{z}}}{\sqrt{2}}$. (Since $\hat{\mathbf{n}}$ is parallel to the xz plane, it must have the form $\alpha \hat{\mathbf{x}} + \beta \hat{\mathbf{z}}$; since $\hat{\mathbf{n}} \cdot \mathbf{k} = 0, \beta = -\alpha$; and since it is a unit vector, $\alpha = 1/\sqrt{2}$.)

$$\mathbf{k} \cdot \mathbf{r} = \frac{\omega}{\sqrt{3}c} (\hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}) \cdot (x \,\hat{\mathbf{x}} + y \,\hat{\mathbf{y}} + z \,\hat{\mathbf{z}}) = \frac{\omega}{\sqrt{3}c} (x + y + z); \ \hat{\mathbf{k}} \times \hat{\mathbf{n}} = \frac{1}{\sqrt{6}} \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ 1 & 1 & 1 \\ 1 & 0 & -1 \end{vmatrix} = \frac{1}{\sqrt{6}} (-\hat{\mathbf{x}} + 2 \,\hat{\mathbf{y}} - \hat{\mathbf{z}}).$$

$$\mathbf{E}(x, y, z, t) = E_0 \cos \left[\frac{\omega}{\sqrt{3}c} (x + y + z) - \omega t \right] \left(\frac{\hat{\mathbf{x}} - \hat{\mathbf{z}}}{\sqrt{2}} \right);$$

$$\mathbf{B}(x, y, z, t) = \frac{E_0}{c} \cos \left[\frac{\omega}{\sqrt{3}c} (x + y + z) - \omega t \right] \left(\frac{-\hat{\mathbf{x}} + 2\hat{\mathbf{y}} - \hat{\mathbf{z}}}{\sqrt{6}} \right).$$

I currently don't have access to the solutions manual for the 4th edition of the textbook. For this solutions set I used the 3rd edition manual. Problems 9.14 and 9.16 in the 3rd edition correspond to problems 9.15 and 9.17 in the 4th edition respectively.

Equation 9.78 is replaced by $\tilde{E}_{0_T}\hat{\mathbf{x}}+\tilde{E}_{0_R}\hat{\mathbf{n}}_R=\tilde{E}_{0_T}\hat{\mathbf{n}}_T$, and Eq. 9.80 becomes $\tilde{E}_{0_T}\hat{\mathbf{y}}-\tilde{E}_{0_R}(\hat{\mathbf{z}}\times\hat{\mathbf{n}}_R)=\beta \hat{E}_{0_T}(\hat{\mathbf{z}}\times\hat{\mathbf{n}}_T)$. The y component of the first equation is $\tilde{E}_{0_R}\sin\theta_R=\tilde{E}_{0_T}\sin\theta_T$; the x component of the second is $\tilde{E}_{0_R}\sin\theta_R=-\beta \tilde{E}_{0_T}\sin\theta_T$. Comparing these two, we conclude that $\sin\theta_R=\sin\theta_T=0$, and hence $\theta_R = \theta_T = 0$. qed

Problem 9.16
$$\begin{cases}
\tilde{\mathbf{E}}_{I} = \tilde{E}_{0_{I}} e^{i(\mathbf{k}_{I} \cdot \mathbf{r} - \omega t)} \hat{\mathbf{y}}, \\
\tilde{\mathbf{B}}_{I} = \frac{1}{v_{1}} \tilde{E}_{0_{I}} e^{i(\mathbf{k}_{I} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{1} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{E}}_{R} = \tilde{E}_{0_{R}} e^{i(\mathbf{k}_{R} \cdot \mathbf{r} - \omega t)} \hat{\mathbf{y}}, \\
\tilde{\mathbf{B}}_{R} = \frac{1}{v_{1}} \tilde{E}_{0_{R}} e^{i(\mathbf{k}_{R} \cdot \mathbf{r} - \omega t)} (\cos \theta_{1} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{E}}_{T} = \tilde{E}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} \hat{\mathbf{y}}, \\
\tilde{\mathbf{B}}_{T} = \frac{1}{v_{2}} \tilde{E}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{0_{T}} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{D} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{D} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{D} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{D} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{D} e^{i(\mathbf{k}_{T} \cdot \mathbf{r} - \omega t)} (-\cos \theta_{2} \,\hat{\mathbf{x}} + \sin \theta_{1} \,\hat{\mathbf{z}}); \\
\tilde{\mathbf{B}}_{D} = \frac{1}{v_{2}} \tilde{\mathbf{E}}_{D} e^{i(\mathbf{k}_{T$$

Law of refraction: $\frac{\sin \theta_2}{\sin \theta_1} = \frac{v_2}{v_1}$. [Note: $\mathbf{k}_I \cdot \mathbf{r} - \omega t = \mathbf{k}_R \cdot \mathbf{r} - \omega t = \mathbf{k}_T \cdot \mathbf{r} - \omega t$, at z = 0, so we can drop all exponential factors in applying the boundary conditions.]

Boundary condition (i): 0 = 0 (trivial). Boundary condition (iii): $\bar{E}_{0_I} + \bar{E}_{0_R} = \tilde{E}_{0_T}$

Boundary condition (ii): $\frac{1}{v_1}\tilde{E}_{0_I}\sin\theta_1 + \frac{1}{v_1}\tilde{E}_{0_R}\sin\theta_1 = \frac{1}{v_2}\tilde{E}_{0_T}\sin\theta_2 \Rightarrow \tilde{E}_{0_I} + \tilde{E}_{0_R} = \left(\frac{v_1\sin\theta_2}{v_2\sin\theta_1}\right)\tilde{E}_{0_T}.$

But the term in parentheses is 1, by the law of refraction, so this is the same as (ii).

Boundary condition (iv):
$$\frac{1}{\mu_1} \left[\frac{1}{v_1} \tilde{E}_{0_I} (-\cos\theta_1) + \frac{1}{v_1} \tilde{E}_{0_R} \cos\theta_1 \right] = \frac{1}{\mu_2 v_2} \tilde{E}_{0_T} (-\cos\theta_2) \Rightarrow$$

$$\tilde{E}_{0_I} - \tilde{E}_{0_R} = \left(\frac{\mu_1 v_1 \cos\theta_2}{\mu_2 v_2 \cos\theta_1} \right) \tilde{E}_{0_T}. \quad \text{Let} \left[\alpha \equiv \frac{\cos\theta_2}{\cos\theta_1}; \ \beta \equiv \frac{\mu_1 v_1}{\mu_2 v_2}. \right] \quad \text{Then} \left[\frac{\tilde{E}_{0_I} - \tilde{E}_{0_R} = \alpha \beta \tilde{E}_{0_T}}{\tilde{E}_{0_T}}. \right]$$

Solving for \tilde{E}_{0_R} and \tilde{E}_{0_T} : $2\tilde{E}_{0_I} = (1+\alpha\beta)\tilde{E}_{0_T} \Rightarrow \tilde{E}_{0_T} = \left(\frac{2}{1+\alpha\beta}\right)\tilde{E}_{0_I}$; $\tilde{E}_{0_R} = \tilde{E}_{0_T} - \tilde{E}_{0_I} = \left(\frac{2}{1+\alpha\beta} - \frac{1+\alpha\beta}{1+\alpha\beta}\right)\tilde{E}_{0_I} \Rightarrow \tilde{E}_{0_R} = \left(\frac{1-\alpha\beta}{1+\alpha\beta}\right)\tilde{E}_{0_I}$. Since α and β are positive, it follows that $2/(1+\alpha\beta)$ is positive, and hence the transmitted wave is in phase

Since α and β are positive, it follows that $2/(1+\alpha\beta)$ is positive, and hence the transmitted wave is in phase with the incident wave, and the (real) amplitudes are related by $E_{0_T} = \left(\frac{2^{\frac{\alpha}{2}}}{1+\alpha\beta}\right) E_{0_I}$. The reflected wave is

Is there a Brewster's angle? Well, $E_{0_R} = 0$ would mean that $\alpha\beta = 1$, and hence that

$$\alpha = \frac{\sqrt{1 - (v_2/v_1)^2 \sin^2 \theta}}{\cos \theta} = \frac{1}{\beta} = \frac{\mu_2 v_2}{\mu_1 v_1}, \text{ or } 1 - \left(\frac{v_2}{v_1}\right)^2 \sin^2 \theta = \left(\frac{\mu_2 v_2}{\mu_1 v_1}\right)^2 \cos^2 \theta, \text{ so}$$

 $1 = \left(\frac{v_2}{v_1}\right)^2 \left[\sin^2\theta + (\mu_2/\mu_1)^2\cos^2\theta\right]$. Since $\mu_1 \approx \mu_2$, this means $1 \approx (v_2/v_1)^2$, which is only true for optically indistinguishable media, in which case there is of *course* no reflection—but that would be true at *any* angle, not just at a special "Brewster's angle". [If μ_2 were substantially different from μ_1 , and the relative velocities were just right, it *would* be possible to get a Brewster's angle for this case, at

$$\left(\frac{v_1}{v_2}\right)^2 = 1 - \cos^2\theta + \left(\frac{\mu_2}{\mu_1}\right)^2\cos^2\theta \Rightarrow \cos^2\theta = \frac{(v_1/v_2)^2 - 1}{(\mu_2/\mu_1)^2 - 1} = \frac{(\mu_2\epsilon_2/\mu_1\epsilon_1) - 1}{(\mu_2/\mu_1)^2 - 1} = \frac{(\epsilon_2/\epsilon_1) - (\mu_1/\mu_2)}{(\mu_2/\mu_1) - (\mu_1/\mu_2)}.$$

But the media would be very peculiar.

By the same token, δ_R is either always 0, or always π , for a given interface—it does not switch over as you change θ , the way it does for polarization in the plane of incidence. In particular, if $\beta = 3/2$, then $\alpha\beta > 1$, for

$$\alpha \beta = \frac{\sqrt{2.25 - \sin^2 \theta}}{\cos \theta} > 1 \text{ if } 2.25 - \sin^2 \theta > \cos^2 \theta, \text{ or } 2.25 > \sin^2 \theta + \cos^2 \theta = 1. \checkmark$$

In general, for $\beta > 1$, $\alpha \beta > 1$, and hence $\delta_R = \pi$. For $\beta < 1$, $\alpha \beta < 1$, and $\delta_R = 0$.

At normal incidence, $\alpha = 1$, so Fresnel's equations reduce to $E_{0_T} = \left(\frac{2}{1+\beta}\right) E_{0_I}$; $E_{0_R} = \left|\frac{1-\beta}{1+\beta}\right| E_{0_I}$, consistent with Eq. 9.82.

Reflection and Transmission coefficients: $R = \left(\frac{E_{0_R}}{E_{0_I}}\right)^2 = \left(\frac{1 - \alpha\beta}{1 + \alpha\beta}\right)^2$. Referring to Eq. 9.116,

in phase if $\alpha\beta < 1$ and 180° out of phase if $\alpha\beta < 1$; the (real) amplitudes are related by $\left| E_{0_R} = \left| \frac{1 - \alpha\beta}{1 + \alpha\beta} \right| E_{0_{\tau}} \right|$. These are the Fresnel equations for polarization perpendicular to the plane of incidence.

To construct the graphs, note that $\alpha\beta = \beta \frac{\sqrt{1-\sin^2\theta/\beta^2}}{\cos\theta} = \frac{\sqrt{\beta^2-\sin^2\theta}}{\cos\theta}$, where θ is the angle of incidence, so, for $\beta=1.5$, $\alpha\beta = \frac{\sqrt{2.25-\sin^2\theta}}{\cos\theta}$.

