

# Quantum Mechanics B (Physics 130B) Fall 2014

## Worksheet 3 – Solutions

### Announcements

- The 130B web site is:

<http://physics.ucsd.edu/students/courses/fall2014/physics130b/> .

Please check it regularly! It contains relevant course information!

- Greetings everyone! This week we're going to learn about spin, rotations, representations, and all that jazz.

### Problems

Suppose we are studying a system with a rotational symmetry. So we need understand how to *represent* this symmetry on our Hilbert space of states. This involves creating matrices which do all the things we expect.

#### 1. Do a Barrel Roll

Recall that in 3-dimensional space<sup>1</sup> we can derive the following rotation matrices from geometry:

$$R_x = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{pmatrix} \quad R_y = \begin{pmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{pmatrix} \quad R_z = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (1)$$

where  $R_i$  is a rotation about the  $i$ -th axis by an angle  $\theta$ . Consider a rotation with an infinitesimal  $\theta = \delta\theta$ .

- (a) Express each rotation in **1** as  $R_i(\theta = \delta\theta) = \mathbb{1} - \mathbf{i}(\delta\theta)X_i$  for some matrices  $X_i$ . These are the *generators* of rotations as we'll see in a moment.<sup>2</sup>

Use small angle approximation  $\cos \theta \approx 1$  and  $\sin \theta \approx \theta$

---

<sup>1</sup>Euclidean. Over  $\mathbb{R}$ . Don't get cheeky.

<sup>2</sup>Note that the factor of  $\mathbf{i}$  is conventional.

Spoilers. The form of  $X_i$  is simply:

$$X_1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -\mathbf{i} \\ 0 & \mathbf{i} & 0 \end{pmatrix} \quad X_2 = \begin{pmatrix} 0 & 0 & \mathbf{i} \\ 0 & 0 & 0 \\ -\mathbf{i} & 0 & 0 \end{pmatrix} \quad X_3 = \begin{pmatrix} 0 & -\mathbf{i} & 0 \\ \mathbf{i} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (2)$$

(b) Show explicitly that each  $X_i$  is Hermitian:  $X^\dagger = X$

Obvious

(c) I claim that the  $X_i$  of 2 satisfy the following algebra<sup>3</sup>

$$[X_i, X_j] = \mathbf{i}\epsilon^{ijk} X_k \quad (3)$$

Convince yourself of this by checking a few examples.

$$X_1 X_2 = \begin{pmatrix} 0 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{and} \quad X_2 X_1 = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{This implies } [X_1, X_2] = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \mathbf{i}X_3 \text{ and so on.}$$

Given a hermitian matrix  $X$  one can construct a unitary matrix  $U = e^{-\mathbf{i}Xa}$  which 'evolves' a state by an amount  $a$ . For example the Hamiltonian  $\hat{H}$  is hermitian and leads to the 'time-evolution' operator  $U = e^{-\mathbf{i}\hat{H}t}$ .

In this way  $\hat{H}$  generates time evolution. Can you guess where this is going?

(d) Consider the unitary matrices given by  $U_i = e^{-\mathbf{i}X_i\theta}$  for each  $X_i$  in 2. Show, using Taylor's theorem, that  $U_i = R_i$ ; they are the rotation matrices of 1.

Let's do this for  $X_1$ , the rest follow very similarly.

$$U_1 = e^{-\mathbf{i}X_1\theta} = e^{\theta A} \text{ for } A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}. \text{ Now let's Taylor expand:}$$

$$e^{\theta A} = \sum_{n=0}^{\infty} \frac{\theta^n A^n}{n!} = \mathbb{1} + \sum_{n=1}^{\infty} \frac{\theta^n A^n}{n!} \text{ where now we need to note the following facts:}$$

$$A^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \equiv -B \quad A^3 = -A \quad A^4 = B \quad A^5 = A \text{ and so on.}$$

This allows us to split the infinite sum into evens and odds and then pull out our  $A$  and  $B$  matrices.

$$\begin{aligned} e^{\theta A} &= \mathbb{1} + \sum_{n,\text{even}} \frac{\theta^n A^n}{n!} + \sum_{n,\text{odd}} \frac{\theta^n A^n}{n!} = \mathbb{1} + \sum_{n,\text{even}} \frac{(-1)^{\frac{n}{2}} \theta^n}{n!} B + \sum_{n,\text{odd}} \frac{(-1)^{\frac{n-1}{2}} \theta^n}{n!} A \\ &= \mathbb{1} + (\cos \theta - 1)B + \sin \theta A = R_x \end{aligned}$$

## 2. What is Spin?

The fact there are spin- $\frac{1}{2}$  particles is one of the most deeply quantum features of nature.

---

<sup>3</sup>This is known as a Lie algebra

We can think of the spin of an electron as an additional degree of freedom. This is represented quantum mechanically is a two dimensional Hilbert space  $\mathcal{H}_2$  spanned by two vectors  $\{|\uparrow\rangle, |\downarrow\rangle\}$

Now, how can we represent rotations on this space?

Consider the following matrices:

$$S_1 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad S_2 = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_3 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (4)$$

These, up to that factor of  $\frac{1}{2}$ , are known as the Pauli matrices.

(a) Show that  $S_i$  are hermitian. Show explicitly that the following algebra is satisfied:

$$[S_i, S_j] = \mathbf{i}\epsilon^{ijk} S_k \quad (5)$$

This is the same algebra as **3**, between the generators of rotations!<sup>4</sup> Together these imply we are constructing something like angular momentum.

Just do it.

Now let's construct the analog of rotation matrices for these objects.

(b) Define  $U_i = e^{-\mathbf{i}\theta S_i}$  and write a simple matrix expression for it.

Hint: Use the fact  $\sigma_i^2 = \mathbb{1}$  where  $\sigma_i$  is a Pauli matrix.

$$e^{-\mathbf{i}\theta S_i} = e^{-\mathbf{i}\frac{\theta}{2}\sigma_i} = \mathbb{1} \cos \frac{\theta}{2} - \mathbf{i}\sigma_i \sin \frac{\theta}{2}$$

(c) Now consider  $U_i(\theta = 2\pi)$ , what has happened?

$$U_i(\theta = 2\pi) = \mathbb{1} \cos \pi - \mathbf{i}\sigma_i \sin \pi = -\mathbb{1}$$

We have gone around a complete rotation and picked up a minus sign!

---

<sup>4</sup>Fancy math point, this is the statement  $SO(3)$  and  $SU(2)$  have the same Lie algebra.