

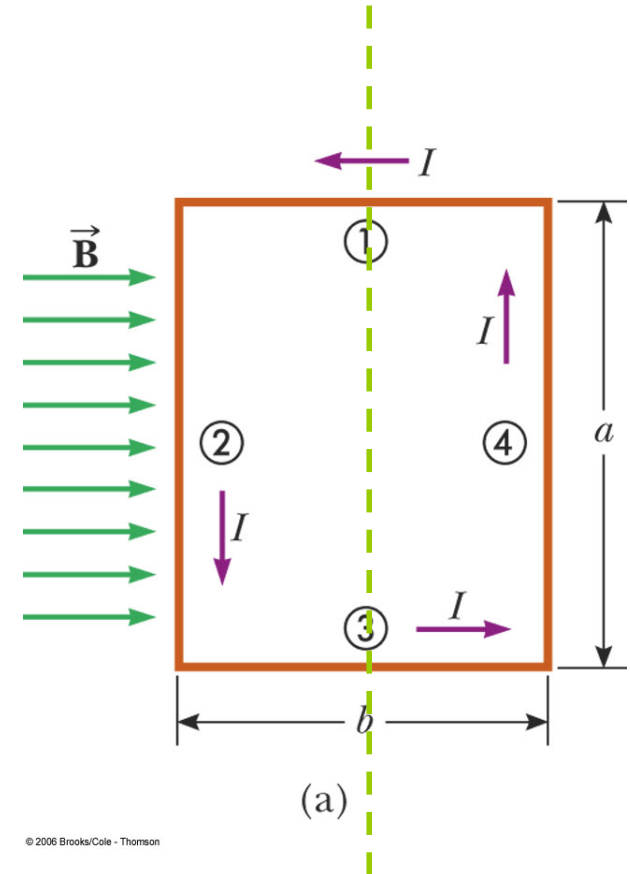
Force on a square loop of current in a uniform B-field.

$$F_{\text{top}} = 0 \quad \theta = 0; \sin\theta = 0; \text{ so } F_B = 0$$

$$F_{\text{bottom}} = 0$$

$$F_{\text{left}} = I a B \text{ (out of page)}$$

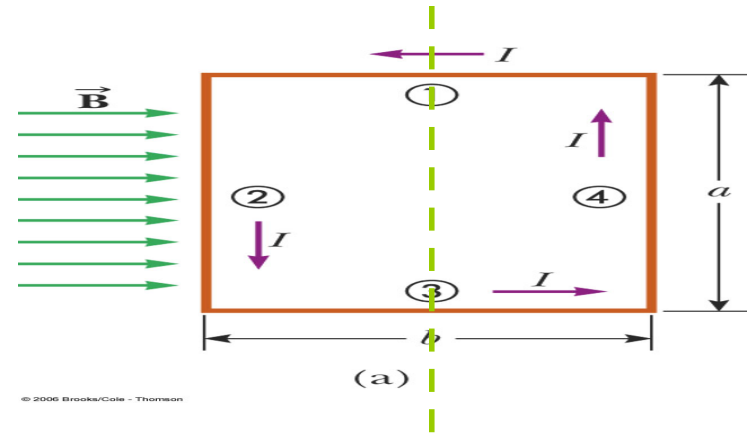
$$F_{\text{right}} = I a B \text{ (into page)}$$



Assume loop is on a frictionless axis

What's the TORQUE
on the current loop?

*Fig. 22.19b in text is the view
along the axis, from the
bottom towards the top.*



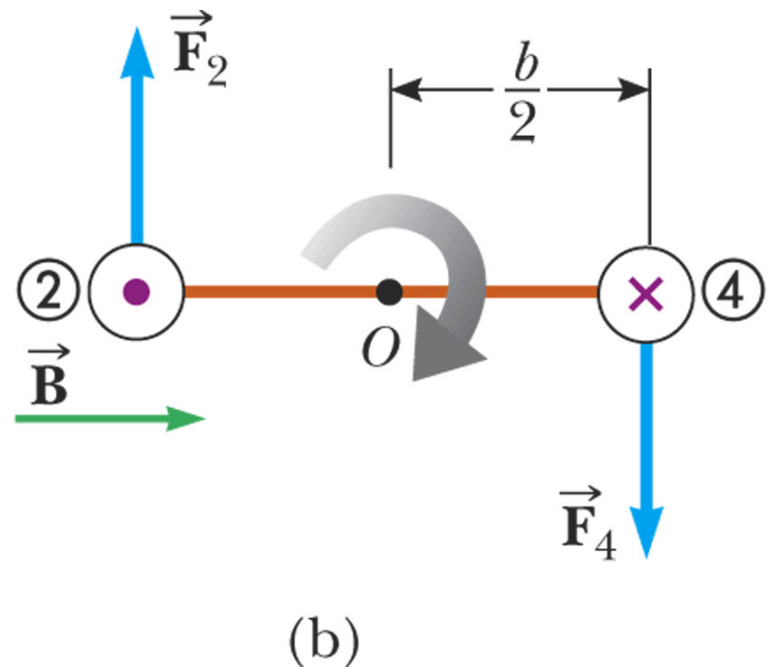
Reminder: torque = $\vec{F} \times \vec{r} =$
 $F r \sin\theta$

$$\tau = F_{\text{left}} b/2 + F_{\text{right}} b/2 =$$

$$(B a I + B a I) b/2 = B I A$$

A = area; $\theta=90^\circ$ here

Note direction of torque:
clockwise



For 1 loop:

$$\tau = BIA \sin\theta$$

$$\tau_{\max} = BIA$$

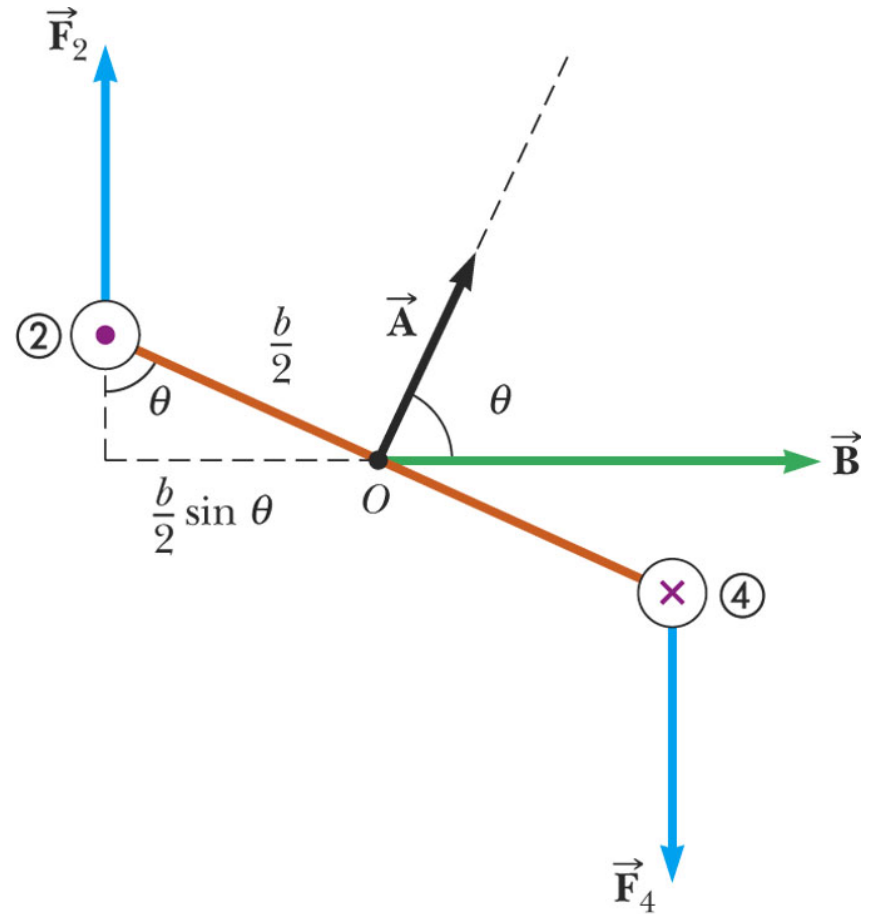
For N turns: Total current = NI

$$\tau = BIAN \sin\theta$$

Magnetic Moment $\vec{\mu} = I\vec{A}\vec{N}$

$\vec{\mu}$ always points perp. to the plane of the loops (points along the normal)

$$\tau = \mu B \sin\theta$$



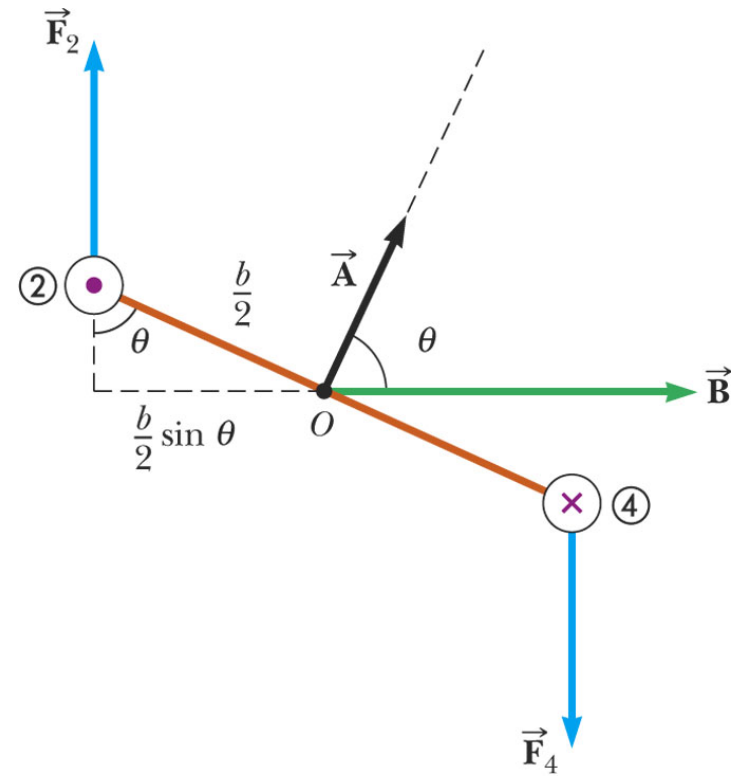
$$\vec{\tau} = I \vec{A} \times \vec{B}$$

- The product $I \vec{A}$ is defined as the **magnetic dipole moment**, $\vec{\mu}$ of the loop (for ANY loop shape)
- SI units: A m²
- Torque in terms of magnetic moment:

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

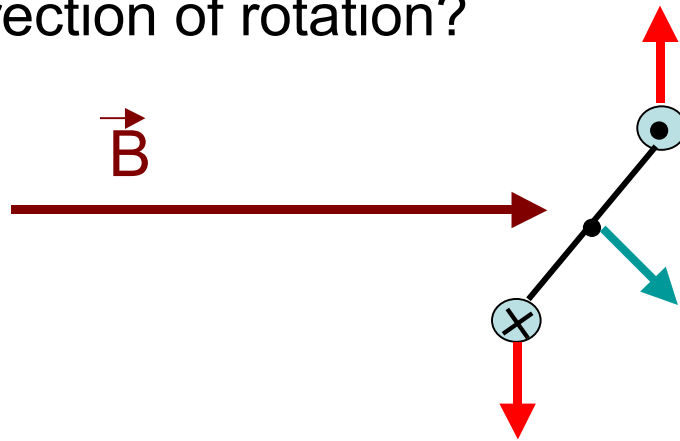
For a coil with N turns of wire:

$$\vec{\mu} = NI \vec{A}$$



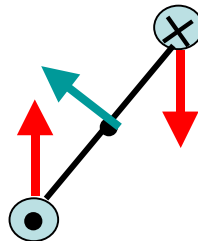
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A coil consisting of 100 turns, each carrying 3A of current and having an area 0.2 m², is oriented such that its normal makes a angle of 45° with a B-field of 0.5T. Find the total torque on the coil. What's the direction of rotation?

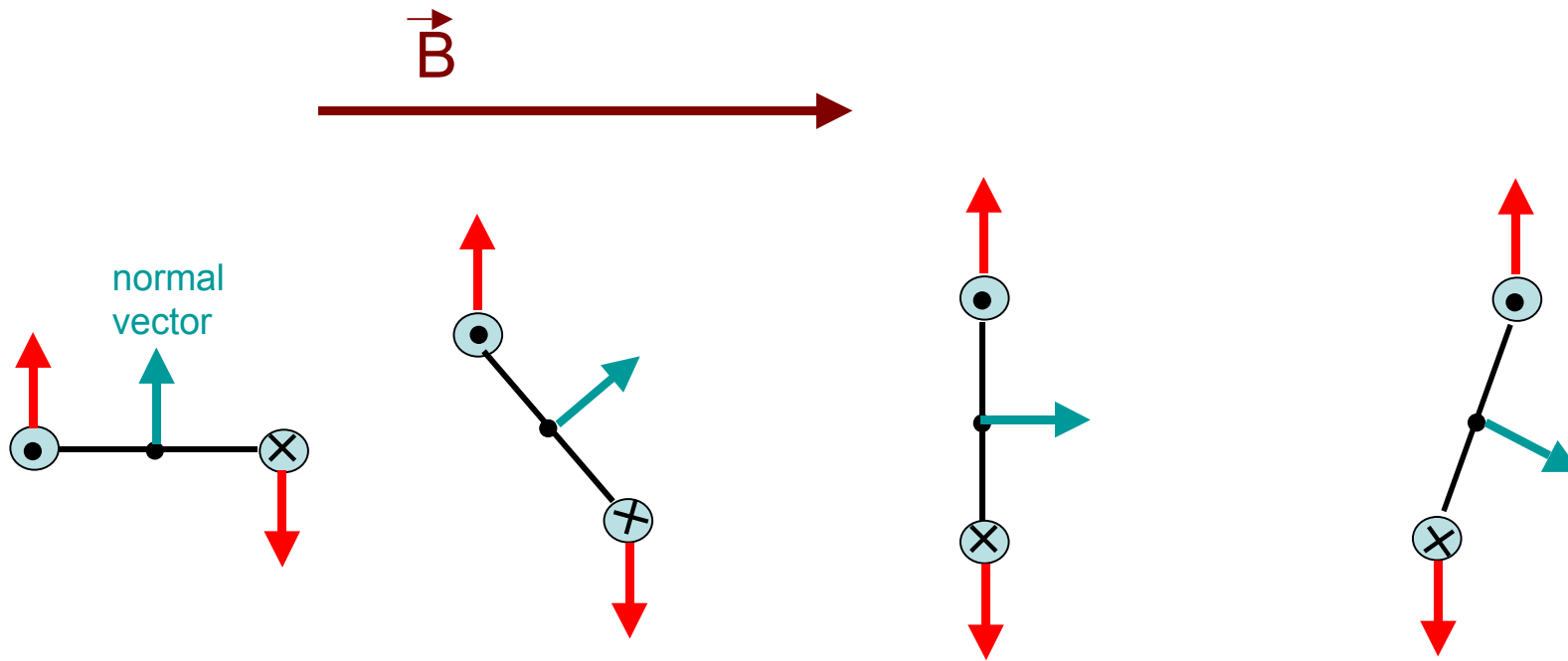


$$\tau = BIAN\sin\theta = (0.5\text{T})(3\text{A})(100)(0.2\text{m}^2)\sin 45^\circ = 21.2 \text{ Nm}$$

What would happen if the current were flowing in the opposite direction?



Same magnitude of τ , but rotation is now CW



#1: $\theta = 90^\circ$

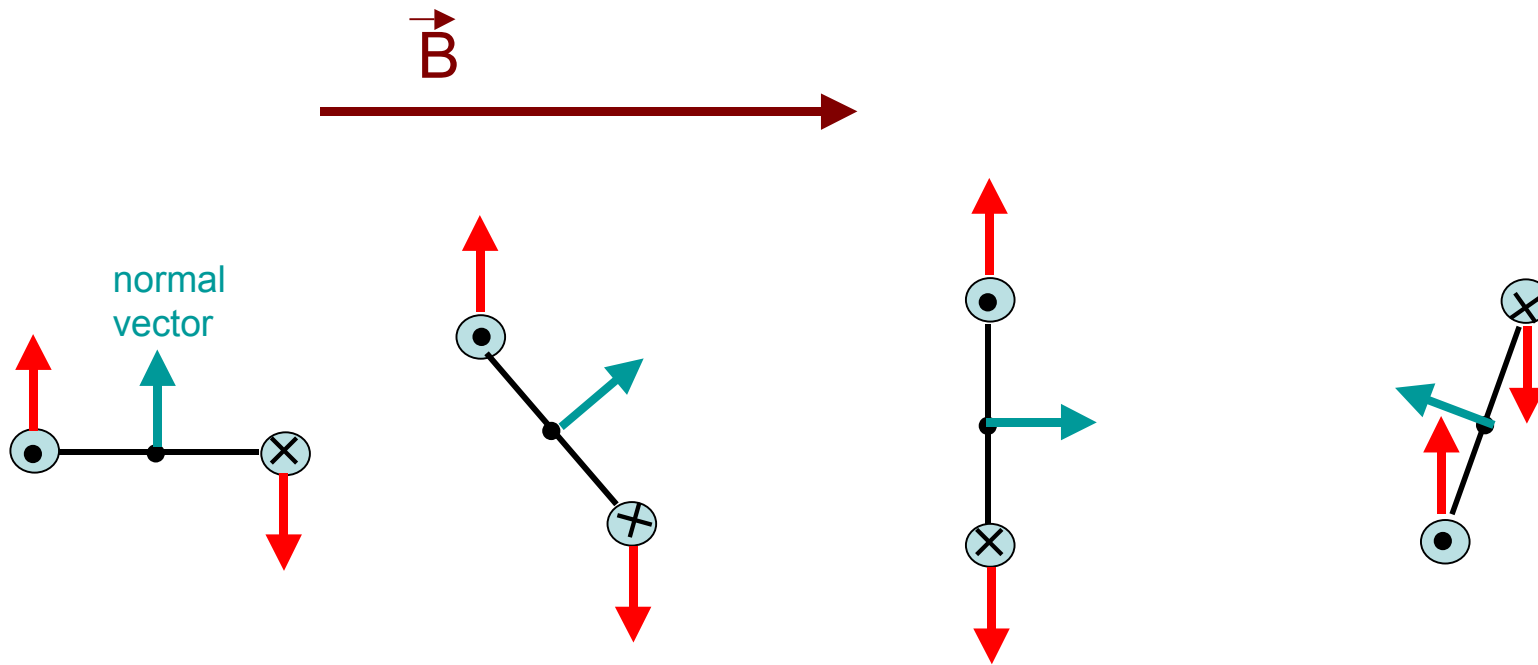
#2: $0^\circ < \theta < 90^\circ$

#3: $\theta = 0^\circ$

#4: $90^\circ < \theta < 180^\circ$

torque acts to align plane of loop perpendicular to B-field (align normal vector with B-field), as in #3

(if released from rest in this position, it won't rotate)



#1: $\theta = 90^\circ$

#2: $0^\circ < \theta < 90^\circ$

#3: $\theta = 0^\circ$

#4: $90^\circ < \theta < 180^\circ$

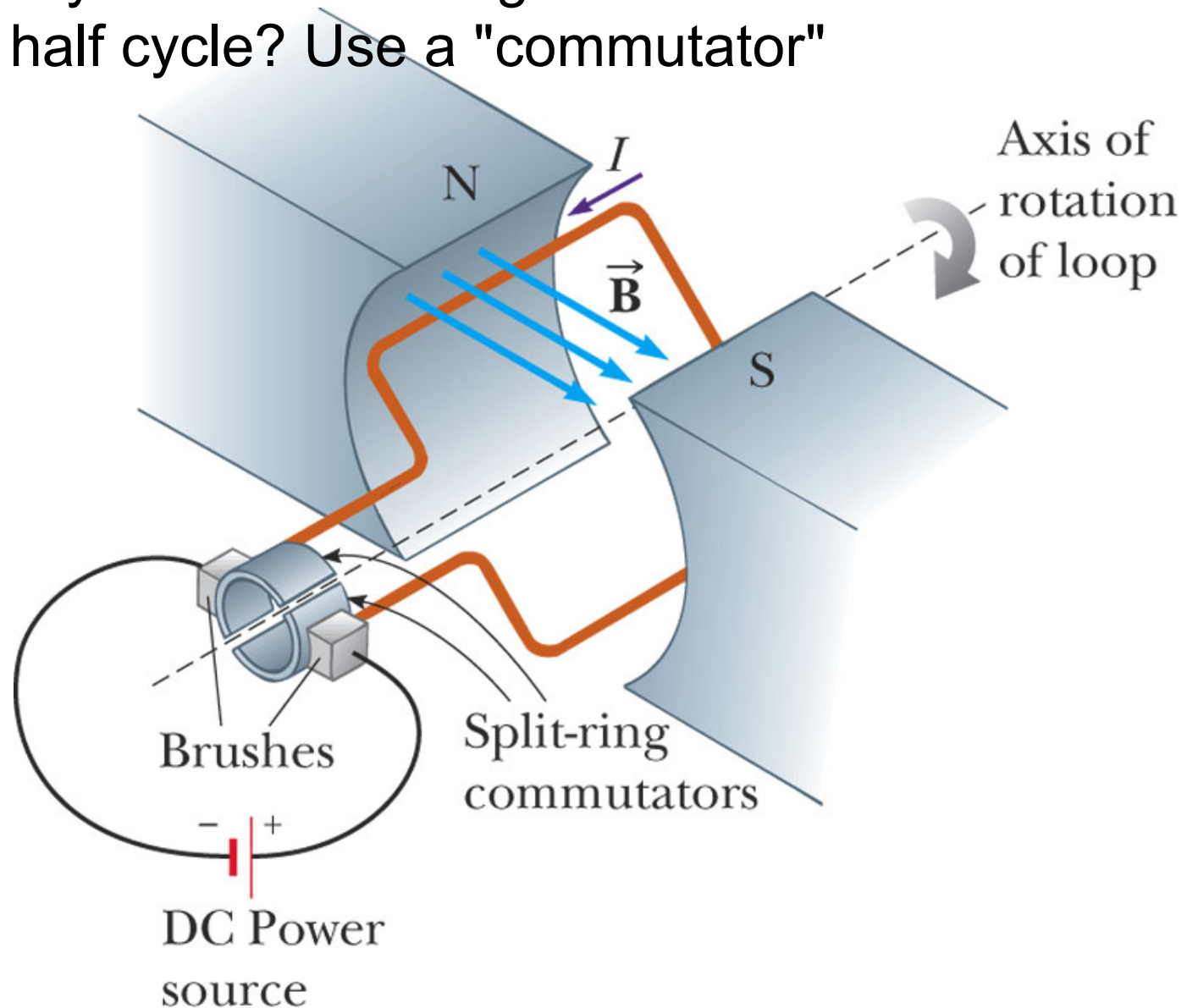
As loop is rotating, what would happen if we switched the direction of current immediately after #3?

The loop would continue to rotate clockwise!

Electric motors

- If direction of current is switched every time τ is about to change sign, then τ will never change sign!
- Loop will rotate nonstop: we have an electric motor (electrical energy converted to mechanical (rotational) energy)!
- Fans, blenders, power drills, etc.
- Use AC current (sign changes naturally), or if you only have DC current available.....

How do you switch the sign of current every half cycle? Use a "commutator"



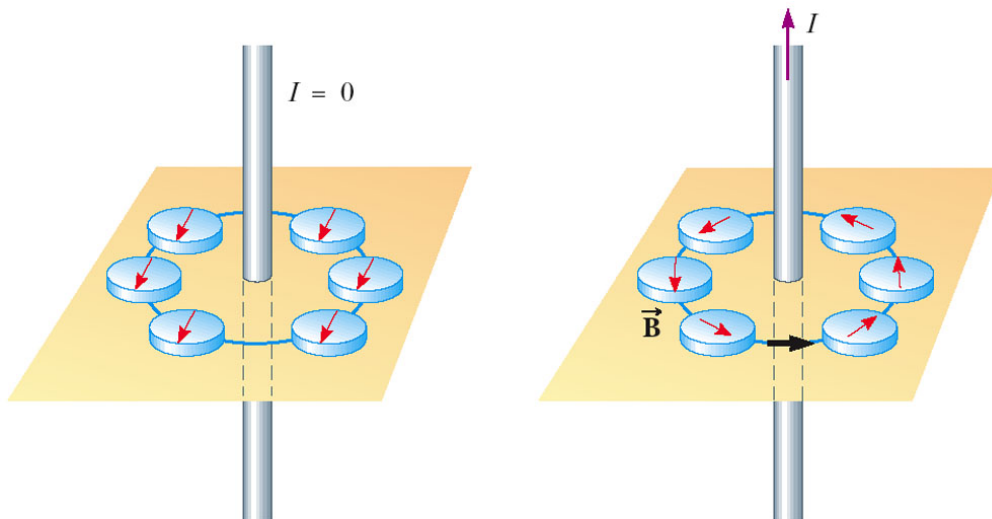
22.7 & 22.9 Biot-Savart Law / Ampere's Law

Context: Previous sections discussed what happens when moving charges are placed in a previously-existing B-fields: charged particles/current-carrying wires experience magnetic force; a loop of wire experiences a torque.

But what can GENERATE a magnetic field?

Magnetic Field of a long straight wire

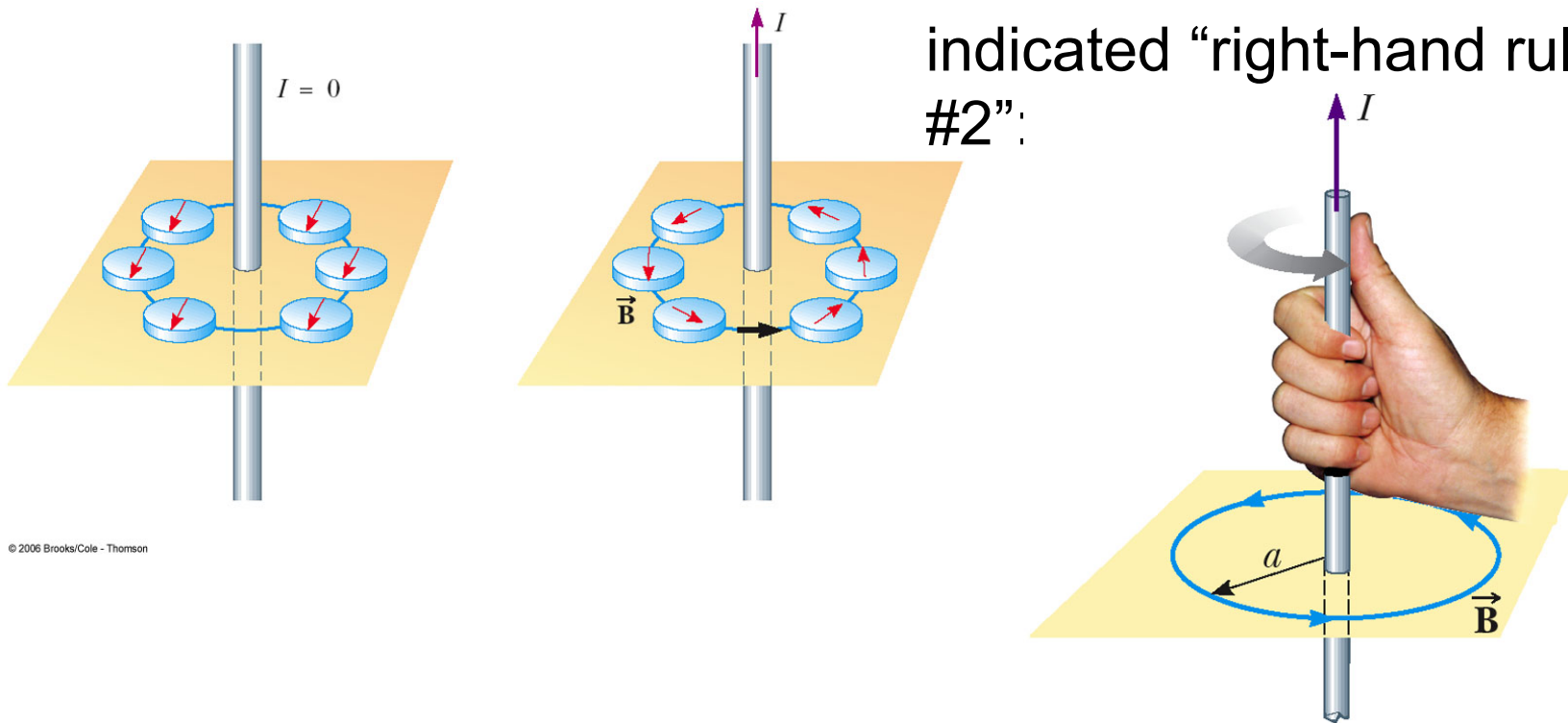
In 1819, Oersted (Denmark) noticed that a magnet (compass needle) was deflected when current was drawn through a nearby wire. 1820: compasses in a horizontal plane:



Magnetic Field of a long straight wire

In 1819, Oersted (Denmark) noticed that a magnet (compass needle) was deflected when current was drawn through a nearby wire. 1820: compasses in a horizontal plane:

Direction of deflection indicated “right-hand rule #2”:

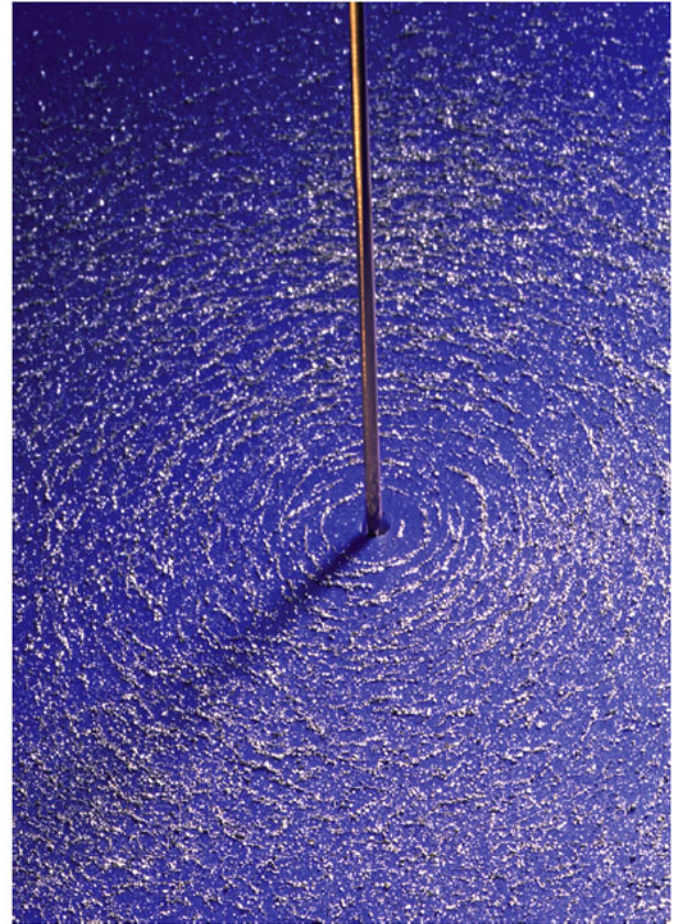


Magnetic Field of a long straight wire

B-field lines form concentric circles:

Notice that the iron filings are more strongly aligned closer to the wire

Magnitude of \vec{B} is the same everywhere along a given radius: $|\vec{B}|$ depends only on r (& physical constants)



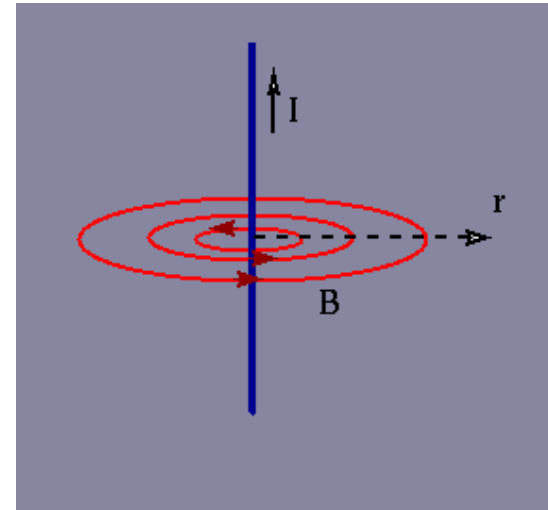
Magnetic Field of a long straight wire

The magnitude of the field at a distance r from a wire carrying a current of I is

$$B = \frac{\mu_0 I}{2\pi r}$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ T}\cdot\text{m} / \text{A}$$

μ_0 is called the *permeability of free space*



Ampere's Law: A general method for deriving magnitude of B-field due to sources of current

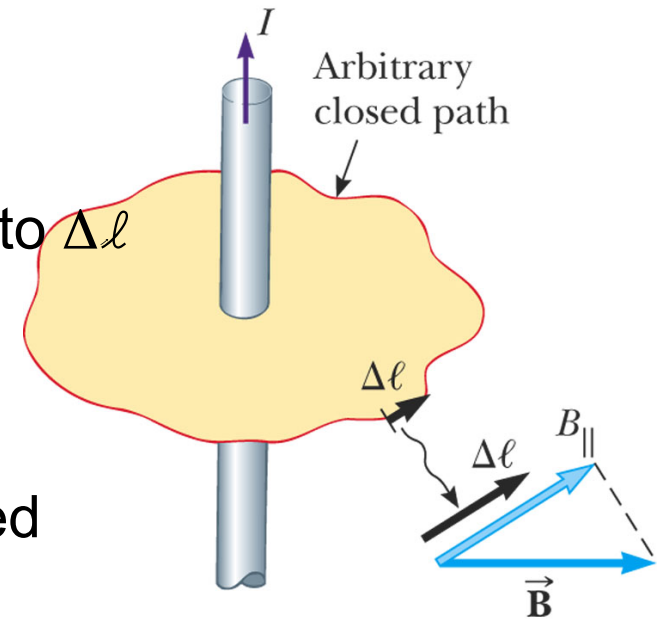
1. Construct a closed path consisting of short segments, each of length $\Delta\ell$

2. B = magnetic field

B_{\parallel} = Component of B-field PARALLEL to $\Delta\ell$

Consider the product $B_{\parallel} * \Delta\ell$

3. Sum of these products over the closed path = $\mu_0 I$



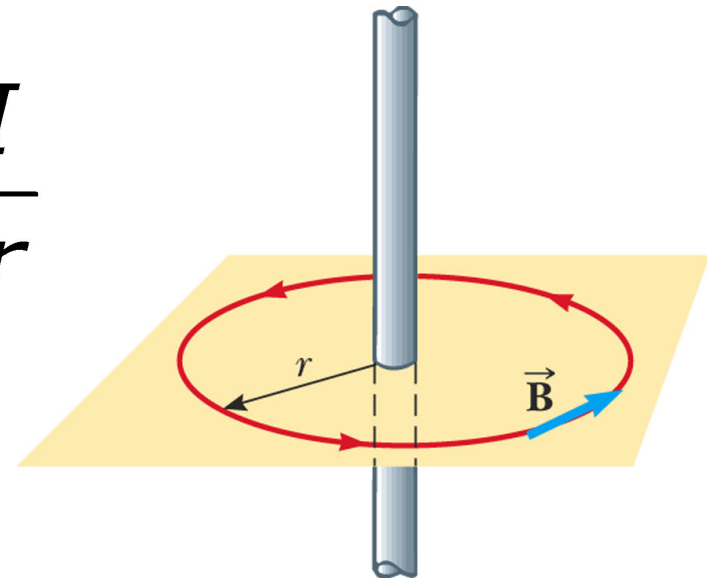
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$$\sum B_{\parallel} \Delta\ell = \mu_0 I$$

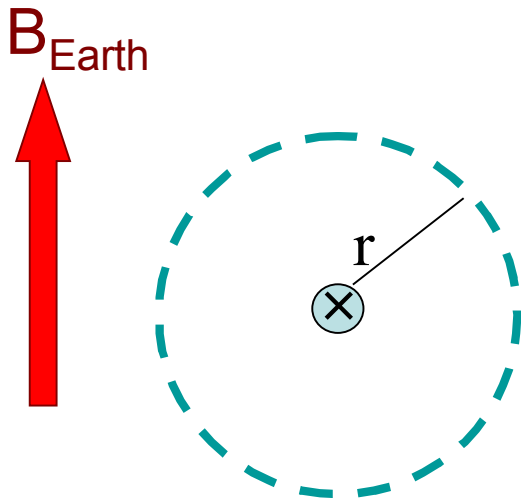
Take advantage of symmetry. When B-field lines are circles, we choose a circular Amperian loop. B is already || to the circle at all points on the circle

$$\begin{aligned}\sum B_{\parallel} \Delta \ell &= B_{\parallel} * \text{circumference} \\ &= B_{\parallel} * 2 \pi r = \mu_0 I\end{aligned}$$

Rearrange to get $B = \frac{\mu_0 I}{2 \pi r}$



Example: A wire carrying 5A of current travels vertically into the page. At what distance r will the B-field equal the Earth's B-field (which points northward) at the surface, 0.5 Gauss?



$$B = \frac{\mu_0 I}{2\pi r}$$

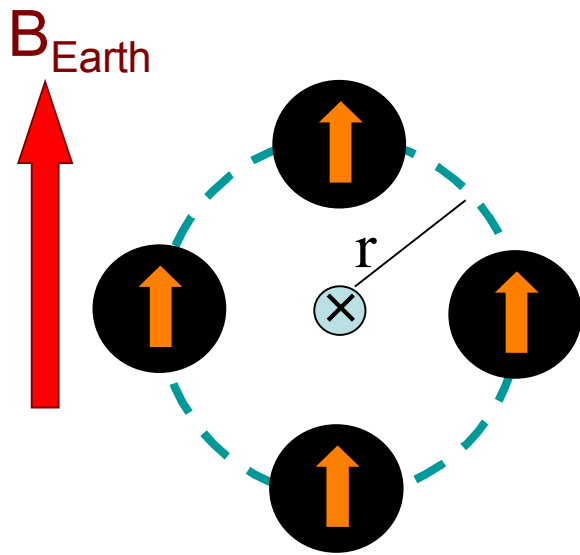
$$r = \mu_0 I / 2\pi B$$

$$r = (4\pi \times 10^{-7} \text{ T m / A})(5\text{A}) / (2 \pi 0.5 \times 10^{-4} \text{ T})$$

$$= (2 \times 10^{-7} \text{ T m / A})(5\text{A}) / 0.5 \times 10^{-4} \text{ T}$$

$$= 2 \times 10^{-2} \text{ m} = 2 \text{ cm.}$$

Example: A wire carrying 5A of current travels vertically into the page. At what distance r will the B-field equal the Earth's B-field (which points northward) at the surface, 0.5 Gauss? If 4 compasses are placed N,S,E,W of the wire at this radius, how will each compasses' needle be deflected?

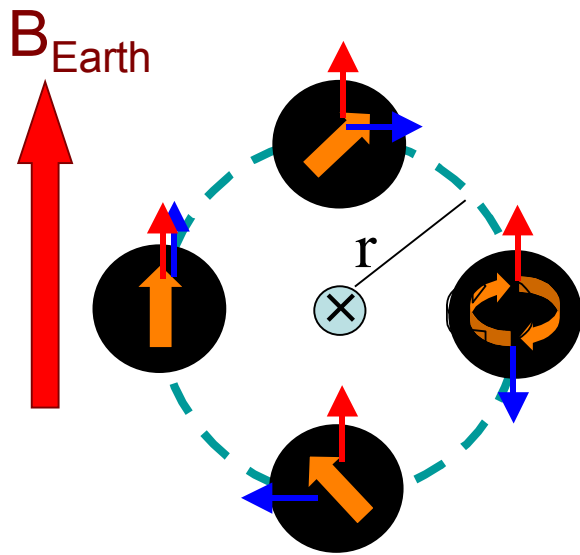


$$B = \frac{\mu_0 I}{2\pi r}$$

$$r = \mu_0 I / 2\pi B$$

$$\begin{aligned} r &= (4\pi \times 10^{-7} \text{ T m / A})(5\text{A}) / (2 \pi 0.5 \times 10^{-4} \text{ T}) \\ &= (2 \times 10^{-7} \text{ T m / A})(5\text{A}) / 0.5 \times 10^{-4} \text{ T} \\ &= 2 \times 10^{-2} \text{ m} = 2 \text{ cm.} \end{aligned}$$

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$$B = \frac{\mu_0 I}{2\pi r}$$

$$r = \mu_0 I / 2\pi B$$

$$\begin{aligned} r &= (4\pi \times 10^{-7} \text{ T m / A})(5\text{A}) / (2 \pi 0.5 \times 10^{-4} \text{ T}) \\ &= (2 \times 10^{-7} \text{ T m / A})(5\text{A}) / 0.5 \times 10^{-4} \text{ T} \\ &= 2 \times 10^{-2} \text{ m} = 2 \text{ cm.} \end{aligned}$$

The E compass will spin freely ($F_{B_{\text{Earth}}} = F_{B_{\text{wire}}}$).

The W compass will really point north, as it feels $2 * F_{B_{\text{Earth}}}$

The N compass will point NE

The S compass will point NW

A power line 20m above the ground carries a current of 1000 A from E to W. Find the magnitude and direction of the B-field due to the wire at the ground below the line, and compare it to the Earth's B-field. Repeat for a wire 10m above ground.

At 20m:

$$B = \mu_0 I / 2\pi r$$

$$= (4\pi \times 10^{-7} \text{ T m / A} * 1000 \text{ A}) / (2 \pi 20\text{m})$$

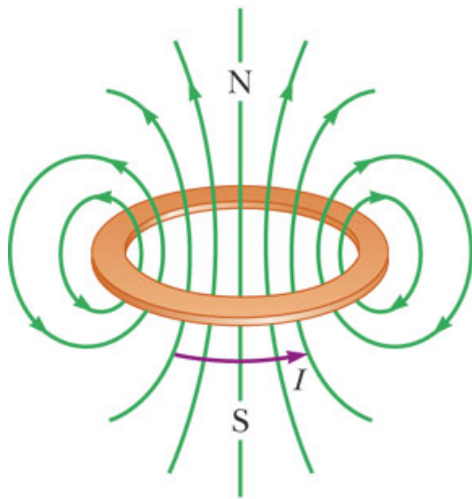
$= 1 \times 10^{-5} \text{ T}$ -- about a factor of 3-5 smaller than the Earth's B field (0.3-0.5 Gauss).

At 10m: $B(r=10) = 2 \times B(r=20) = 2 \times 10^{-5} \text{ T}$ -- still just smaller than the Earth's B-field

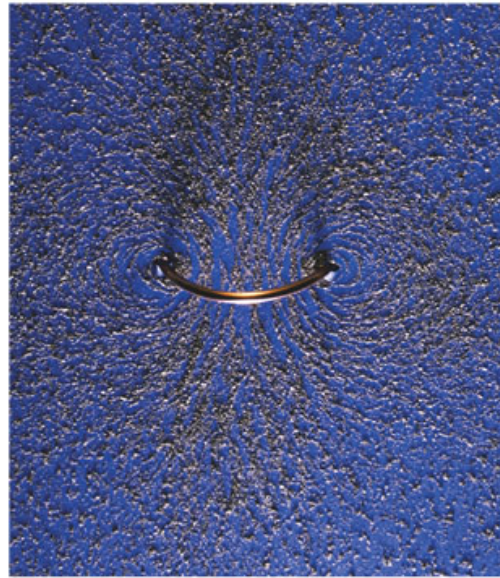
Direction of B-field when you're below the wire: south

B-field at the center of a current-loop:

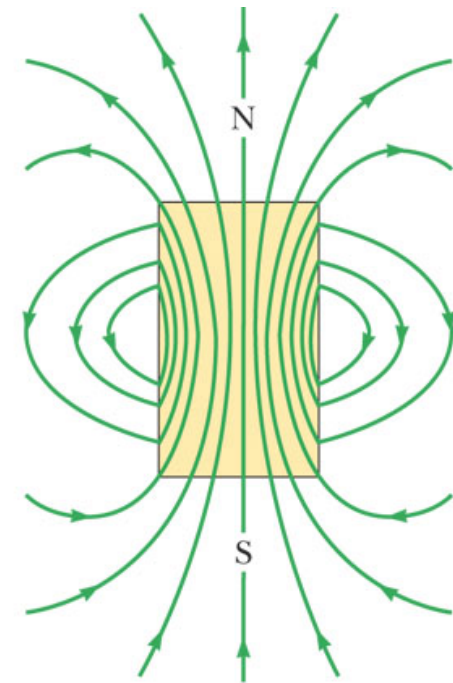
$$B_x = \frac{\mu_o I}{2R}$$



(a)



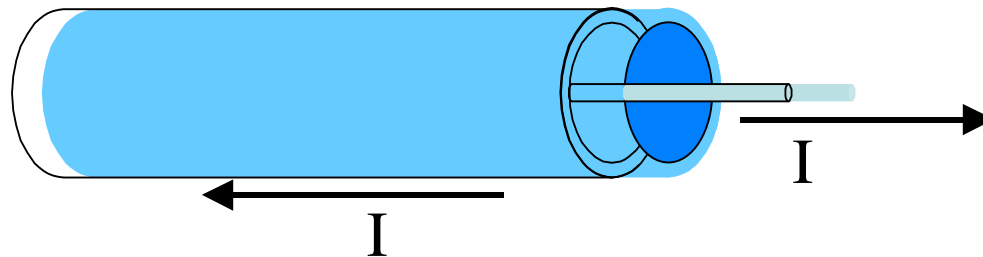
(b)



(c)

Example: A Co-axial cable

Inner conductor and outer conductor of radius R_{out} carrying currents in opposite directions.



What's B at $r > R_{\text{out}}$?

KEY: Remember superposition = vector addition: Total B -field from 2 sources = sum of B -fields from each source!

$+I + -I = \text{zero total current, so } B\text{-field} = 0.$

Example: $B(r)$, inside wire: Ex. 22.7, p. 749

Use Ampere's Law to derive that inside a wire with a uniform current distribution, $B(r)$ is proportional to r .

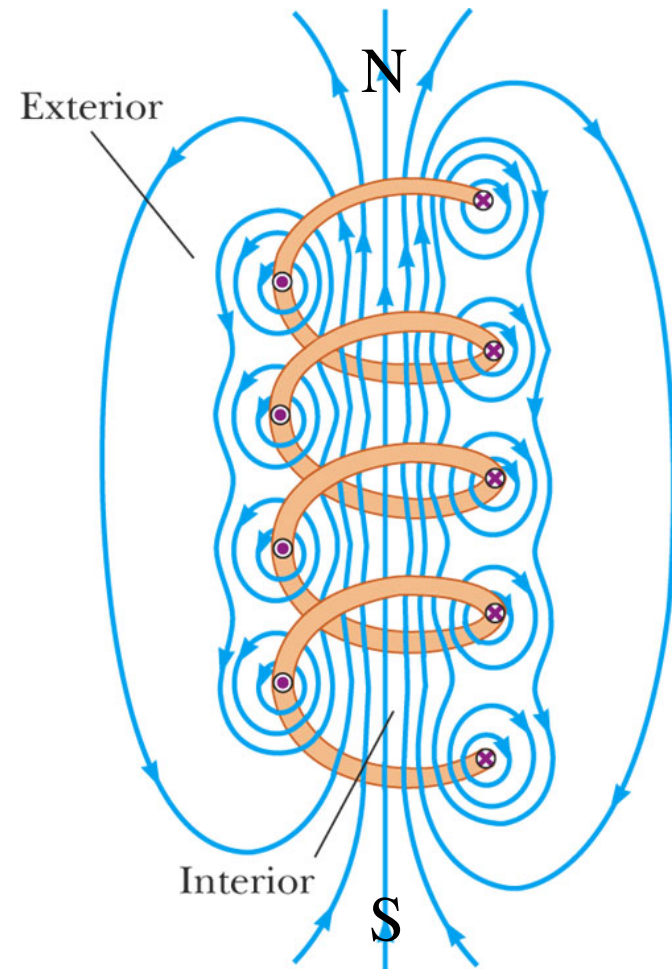
Recall the case of the electric field $E(r)$ inside a wire with a uniform charge distribution: $E(r)$ is also proportional to r .

Outside a long, straight wire, both E and B are proportional to $1/r$.

22.10: Stack of current loops = solenoid

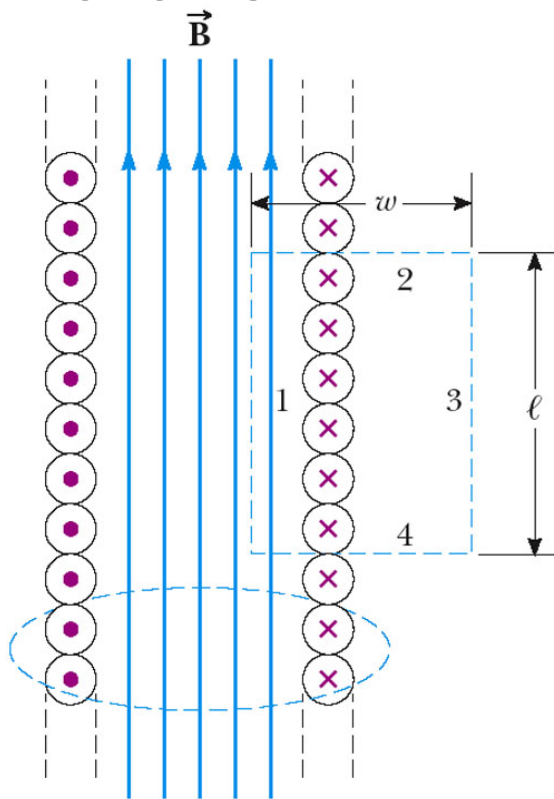
When the loops are spaced together tightly enough, the B-field inside is strong and rather uniform, and B-field outside is essentially negligible.

Commonly used in electromagnets, devices used to convert electrical current to magnetic field.



B-field in the center of a solenoid

Use Ampere's Law; choose a closed loop as follows:



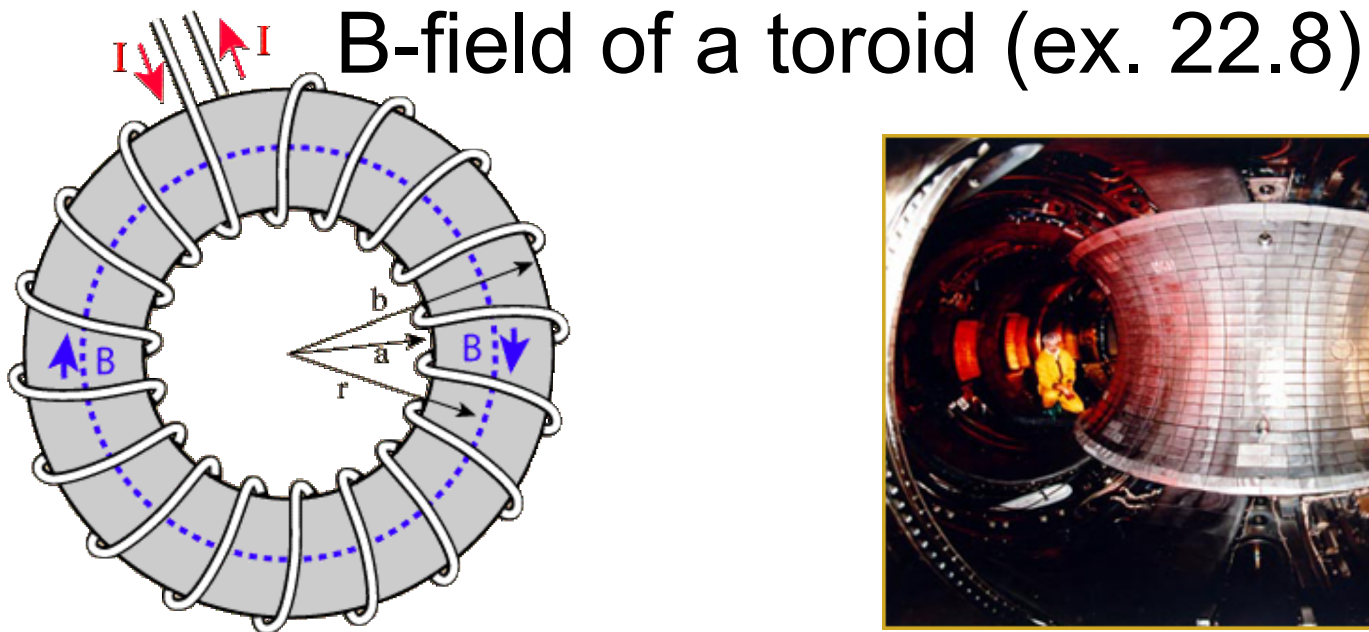
Only segment 1 contributes:
 $B_{\parallel} \Delta \ell = 0$ for other segments.

$$BL = \mu_0(NI)$$

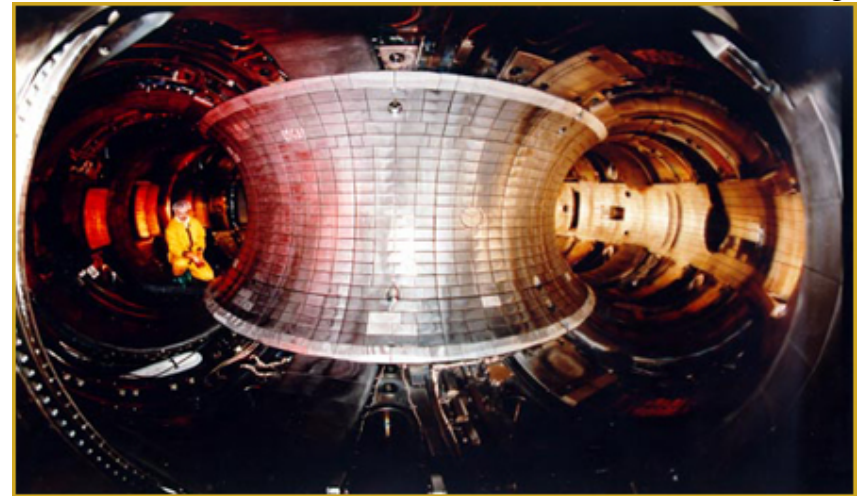
$$B = \mu_0 I (N/L) = \mu_0 I n \quad (n=N/L)$$

Example: An electromagnet consists of 100 turns of wire, and the length is 3.0 cm. The wire carries 20 Amps of current. What's the B-field at the center of the magnet?

$$B = \mu_0 I (N/L) = 4\pi \times 10^{-7} \text{ T m / A} * 20 \text{ A} \\ (100/0.03\text{m}) = 0.084 \text{ T}$$



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Tokamak: used for fusion energy research

$$\sum B_{\parallel} \Delta \ell = B 2\pi r$$

enclosed current on blue line = $\mu_0 N I$

$$\mathbf{B} = \mu_0 \mathbf{N I} / 2\pi r$$

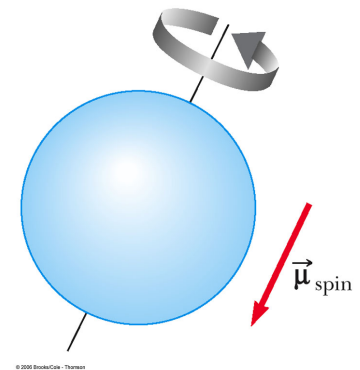
B-field higher towards inner radius (not perfectly uniform), but uniform along each radius

22.11: Magnetism in Matter / Magnetic Domains

Magnetic materials owe their properties to magnetic dipole moments of electrons in atoms

Classical model for electrons in atoms:

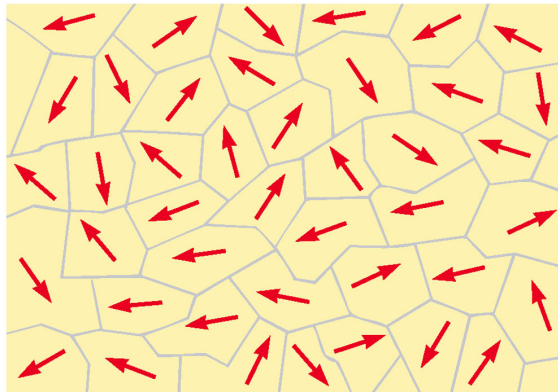
1. Orbital motion of electron: like a loop current (but B-field produced by 1 electron can be cancelled out by an oppositely revolving electron in the same atom)
2. “spin” of individual electrons produces much stronger B-field: each electron itself acts like a magnetic dipole



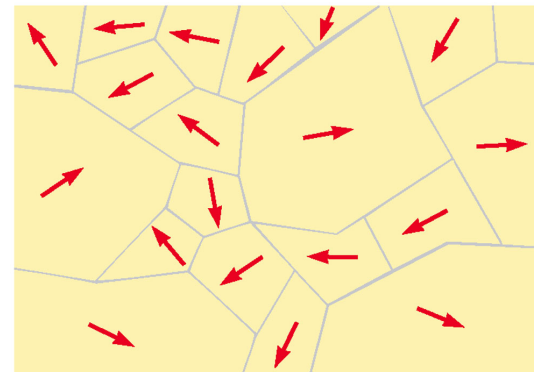
Magnetic Domains

Magnetic domains (10^{-4} - 10^{-1} cm): Each domain has a substantial fraction of atoms with magnetic moments coupled. They're separated by domain boundaries.

Ferromagnetic materials (Fe, Co, Ni): have these domains. Spins are randomly oriented, but when an external \vec{B} is applied, domains tend to align with magnetic field; domain boundaries adjust accordingly.



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Result: material produces its own **internal \vec{B}**

$$(\vec{B}_{\text{net}} = \vec{B}_{\text{external}} + \vec{B}_{\text{internal}})$$

Re-cap:

Soft magnetic materials (e.g. Fe): Easily magnetized in presence of external B, but doesn't retain magnetization for long. Used as cores for electromagnets.

When external B is turned off, thermal agitation returns dipoles to random orientations

Hard magnetic materials (e.g. metal alloys: Alnico (Aluminum, Nickel, Cobalt)): Harder to magnetize (requires higher $\vec{B}_{\text{external}}$) but retains the magnetization for a long time. Used as permanent magnets.