## Physics 110A: Final Exam

INSTRUCTIONS: Do four problems. You must do problems 1 and 2. Then choose any two of problems 3, 4, and 5.

## [1] Central Forces

Two particles attract each other via a central force $U(r)=-C r^{-3 / 2}$, where $C$ is a constant.
(a) Write down and sketch the effective potential $U_{\text {eff }}(r)$.
(b) Find the radius $r_{\circ}$ of the circular orbit. Is this orbit stable? Why or why not?
(c) What is the period of the circular orbit?
(d) If the circular orbit is slightly perturbed, the relative coordinate can be written as $r(t)=$ $r_{\circ}+\eta(t)$. What is the period of the deviation $\eta(t) ?$
(e) Find the angular change $\Delta \phi_{\mathrm{p}}$ between successive instances of periapsis. Is periapsis receding (takes more than one complete revolution to achieve periapsis) or advancing (takes less than one complete revolution to achieve periapsis)?

## [2] Lagrangian Dynamics

The mechanical system depicted below rotates with angular frequency $\Omega$ about the central axis. The only degree of freedom is the angle $\theta$.
(a) Write down the kinetic energy $T$, the potential energy $U$, and the Lagrangian $L$.
(b) What is the equation of motion for $\theta$ ?
(c) Linearize about $\theta=0, \dot{\theta}=0$ and find the frequency of small oscillations. Show that this motion is stable (the oscillation frequency is real) provided $\Omega^{2} \leq \Omega_{\mathrm{c}}^{2}$. What is the critical frequency $\Omega_{\mathrm{c}}$ ?
(d) For $\Omega^{2}>\Omega_{\mathrm{c}}^{2}$, show that the system exhibits small oscillations when linearized about $\theta=\theta_{0}$, $\dot{\theta}=0$. Find $\theta_{0}$.
(e) What is the small oscillation frequency in the case $\Omega^{2}>\Omega_{\mathrm{c}}^{2}$ ? You may leave your answer in terms of $\theta_{0}$ and other quantities.

## [3] Driven Linear Systems

A driven system obeys the equation of motion

$$
\left(\frac{d}{d t}+\alpha\right)\left(\frac{d}{d t}+\beta\right)\left(\frac{d}{d t}+\gamma\right) x=f_{0} \cos \Omega t
$$

where $\alpha, \beta$, and $\gamma$ are all real and positive.
(a) What is the most general solution to the homogeneous equation, $x_{\mathrm{h}}(t)$ ? Hint: The equation is already factorized!
(b) Writing the general inhomogeneous solution as

$$
x=A(\Omega) f_{0} \cos \left((\Omega t-\delta(\Omega))+x_{\mathrm{h}}(t)\right.
$$

find expressions for the amplitude $A(\Omega)$ and the phase $\delta(\Omega)$.
(c) Assuming $\alpha \ll \beta \ll \gamma$, sketch $\delta(\Omega)$ and $A(\Omega)$.
(d) For the general inhomogeneous solution, write, but do not solve, three equations which will determine these constants of integration in terms of $x(0), \dot{x}(0)$, and $\ddot{x}(0)$.

## [4] Calculus of Variations

(a) Derive the equation for a geodesic on an ellipsoidal surface of revolution defined by

$$
\frac{x^{2}+y^{2}}{a^{2}}+\frac{z^{2}}{b^{2}}=1
$$

where $a$ and $b$ are constants. Work in cylindrical coordinates $(\rho, \phi, z)$ and derive a first order differential equation of the form $d \phi=F(\rho) d \rho$.
(b) Derive equations for the extremization of the functional

$$
S[x(t), y(t), z(t)]=\int_{t_{\mathrm{i}}}^{t_{\mathrm{f}}} d t\left[\frac{1}{2} \dot{x}^{2}+\frac{1}{2} \dot{y}^{2}+\frac{1}{2} \dot{z}^{2}+x \dot{y}+y \dot{z}+z \dot{x}-U(x, y, z)\right]
$$

subject to the constraints

$$
\begin{aligned}
x^{3} y z & =a^{5}-x y^{2} z^{2} \\
x+y+z & =b
\end{aligned}
$$

where $a$ and $b$ are constants. You don't have to solve any equations - just make sure you have as many equations as you have unknowns.

## [5] Phase Space Dynamics

In the dim and distant past, we explored the logistic equation, $\dot{N}=r N(1-N / K)$, for population dynamics. Consider now the following model for a harvested population:

$$
\frac{d N}{d t}=r N\left(1-\frac{N}{K}\right)-H
$$

where $H$ is the harvesting rate.
(a) Show that this equation may be adimensionalized to the form

$$
\frac{d \nu}{d \tau}=\nu(1-\nu)-h
$$

and determine $\nu, \tau$, and $h$. Hint: $\nu=N / K$.
(b) Locate all fixed points and identify their stability. Show that a bifurcation occurs at a certain value of $h$ - for $h>h_{\mathrm{c}}$ there are no longer any fixed points. Find $h_{\mathrm{c}}$, and plot the vector field $\dot{\nu}$ versus $\nu$ for the two cases $h<h_{\mathrm{c}}$ and $h>h_{\mathrm{c}}$.
(c) Discuss the long time behavior for the population for $h<h_{\mathrm{c}}$ and $h>h_{\mathrm{c}}$. Can you provide a biological interpretation for each case?
(d) This model has a very silly feature - the population can become negative. An improved model might start with the equation

$$
\frac{d N}{d t}=r N\left(1-\frac{N}{K}\right)-\frac{H N}{L+N}
$$

where $L$ is an additional parameter. The harvesting term now goes to zero in the limit $N \rightarrow 0$ and $N=0$ is thus a fixed point for all values of the parameters $r, K, H$, and $L$. Under what conditions will $N=0$ be an attractive fixed point, and under what conditions will it be repulsive? (The full analysis of this improved model is quite interesting.)

The following extra credit problem, basically worthless, is meant for listeners of 88.1 FM.
[*] Miles davis (trumpet) and John Coltrane (tenor saxophone) were two of the five members of one of the greatest quintets in the history of music. Name the other three members, along with their instruments. Incredibly, at the same time there was another great ("west coast") quintet, with Clifford Brown on trumpet and Harold Land/Sonny Rollins on tenor sax. Name the three other members. Hint: One of the other members had a more famous brother who specialized on the same instrument. Tragically, Brown and one of the other members died in a car crash on the Pennsylvania turnpike in the summer of 1956, four months before Brown's 26 th birthday.

